REFERENCE MANUAL

> DX8210

Omnidirectional Barcode Scanner

⊕DATALOGIC

⊕DATALOGIC

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DX8210 Omnidirectional Barcode Scanner Reference Manual

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CONTENTS

REFERENCES

REFERENCE DOCUMENTATION

The documentation related to the DX8210 management is listed below:

- CBX510 Connection Box Installation Manuals
- SC5000 Controller Manuals

SUPPORT THROUGH THE WEBSITE

Datalogic provides several services as well as technical support through its website. Log on to **www.datalogic.com** and click on **PRODUCTS** and **SUPPORT & SERVICES** links for further information:

- **PRODUCTS – FIXED INDUSTRIAL BARCODE READERS**

  Select your product from the links on the **Fixed Industrial Barcode Readers** page. The product page describes specific Info, Features, Applications, Models, Accessories, and Downloads including documentation, software drivers, and utility programs.

- **SUPPORT & SERVICES – INDUSTRIAL AUTOMATION**

  Several links from the **Industrial Automation** list take you to additional services such as: Service Program which contains Maintenance Agreements and Warranty Extensions; Repair Centers; On-Line RMA Return Material Authorizations; Technical Support through email or phone; Downloads for additional downloads.

PATENTS

See www.patents.datalogic.com for patent list.

This product is covered by one or more of the following patents:

Utility patents: EP0789315B1; EP0851376B1; EP0959426B9; EP1217571B1; EP1363228B1; JP4033958B2; JP4376353B2; US5979761; US5992740; US6347740; US6394352; US6443360; US6629639; US6742710; US9104928

CONVENTIONS

WARNINGS OR CAUTIONS: This symbol identifies a hazard or procedure that, if incorrectly performed, could cause personal injury or result in equipment damage. It is also used to bring the user's attention to details that are considered IMPORTANT.

HIGH VOLTAGE CAUTION: This symbol alerts the user they are about to perform an action involving, either a dangerous level of voltage, or to warn against an action that could result in damage to devices or electrical shock.

LASER CAUTION: This symbol alerts the user they are about to perform an action involving possible exposure to laser light radiation.

ESD CAUTION: This symbol identifies a procedure that requires you take measures to prevent Electrostatic Discharge (ESD) e.g., use an ESD wrist strap. Circuit boards are most at risk. Please follow ESD procedures.

NOTES: This symbol draws attention to details or procedures that may be useful in improving, maintaining, or enhancing the performance of the hardware or software being discussed.

COMPLIANCE

ELECTRICAL SAFETY

This product conforms to the applicable requirements contained in the European Standard for electrical safety EN 60950 at the date of manufacture.

LASER SAFETY

The following information is provided to comply with the rules imposed by international authorities and refers to the correct use of the DX8210 barcode scanners.

Standard Regulations

These barcode scanners use low-power laser diodes. Avoid staring at the beam as one would with any very strong light source, such as the sun.

Take care when installing the laser device to avoid inadvertent laser beam contact with the eye of an observer, including through reflective surfaces.

This product conforms to the applicable requirements of IEC 60825-1 and complies with 21 CFR 1040.10 except for deviations pursuant to Laser Notice N° 50, date June 24, 2007. The scanner is classified as a Class 2 laser product according to IEC 60825-1 regulations.

There is a safety device which allows the laser to be switched on only if the motor is rotating above the threshold for its correct scanning speed.

WARNING: Use of controls or adjustments or performance of procedures other than those specified herein may result in exposure to hazardous visible laser light.

BUREAU OF INDIAN STANDARD (BIS)

Self Declaration – Conforming to IS 13252 (Part 1):2010, R-41009288.

WARNING AND SERIAL LABELS

The Warning Label on the barcode scanner indicates exposure to laser light and the device classification.

Figure 1: Warranty, Device Class, and Warning Label Location

Produit(s) conforme selon 21CFR 1040.10 sauf des dérogations relatives à la Laser Notice N° 50, date Juin 24, 2007.

Dans le paquet il y a l'étiquette(s) pour les pays où le texte d'avertissement en français sont obligatoires. Le(s) mettre sur le produit à la place de la version anglaise.

Figure 2: Exemple d'étiquettes d'avertissement laser

WARNING: Disconnect the power supply when installing the device or during maintenance to avoid unintentional exposure to laser light.

WARNING: There are no user serviceable parts inside the barcode scanner. Service should only be performed by Datalogic trained and certified technicians.

Any violation of the optical parts in particular could result in exposure to Class 3B laser light.

POWER SUPPLY

This product is intended to be installed by Qualified Personnel only.

This product is intended to be supplied by a UL listed or CSA Certified Power unit with "Class 2" or LPS power source.

CSA CERTIFIED

CSA
C ® US
218441

CE COMPLIANCE

CE marking states the compliance of the product with essential requirements listed in the applicable European directive. Since the directives and applicable standards are subject to continuous updates, and since Datalogic promptly adopts these updates, therefore the EU declaration of conformity is a living document. The EU declaration of conformity is available for competent authorities and customers through Datalogic commercial reference contacts. Since April 20th, 2016 the main European directives applicable to Datalogic products require inclusion of an adequate analysis and assessment of the risk(s). This evaluation was carried out in relation to the applicable points of the standards listed in the Declaration of Conformity. Datalogic Automation products are mainly designed for integration purposes into more complex systems. For this reason it is under the responsibility of the system integrator to do a new risk assessment regarding the final installation.

WARNING: This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

FCC COMPLIANCE

Modifications or changes to this equipment without the expressed written approval of Datalogic could void the authority to use the equipment.

This device complies with PART 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference which may cause undesired operation.

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his/her own expense.

GENERAL VIEW

Figure 3: DX8210 Barcode Scanner Front and Left Side Views

1 INTRODUCTION

1.1 PRODUCT DESCRIPTION

The DX8210 omnidirectional barcode scanner is designed to provide an innovative and high performance solution in omnidirectional reading applications by combining the following advanced technologies with Datalogic solid experience in the material handling sector.

Some of the main features of the DX8210 are listed below:

- Scanning speed 1000 scans/sec

- Reads all popular codes

- Supply voltage from 20 to 30 vdc

- Test mode to verify the reading features and exact positioning of the scanner without the need for external tools

- Programmable in several different operating modes to suit the most various barcode reading system requirements

- Light source: solid state laser diodes; the light emitted has a wave length between 630~680 nm. For laser safety precautions refer to the "compliance" section at the beginning of this manual

1.2 APPLICATIONS

The DX8210 omnidirectional barcode scanners are specifically designed for industrial applications and for all cases requiring high reading performance such as:

- Code reconstruction (ACR™)

- Reading of codes covered by plastic film

- Reading of codes with a wide depth of field

- Reading codes within a wide field of view

- Reading of high resolution codes positioned at long distances from the reader

- Code reading on fast moving objects

These barcode scanners are designed for both single-reader layouts and multi-reader layouts. For typical layouts, *see section 5.9.*

Feature	Benefit
DST	Digital Signal Technology converts analog signals to digital before processing for much improved decoding capability especially on poorly printed or damaged codes.
ACR™	Fifth generation Advanced Code Reconstruction technology allows the reading of low aspect ratio labels placed anywhere on a parcel and enhances the readability of poorly printed or damaged codes.
PACKTRACK™	Second generation Datalogic patented parcel tracking system which improves the reading features in omnidirectional stations. In particular, PackTrack manages 6-sided reading systems when it is impossible to detect the real position of the code on the parcel, thus overcoming the need for external accessories essential in traditional tracking systems.
ASTRA™	Third generation Automatically SwiTched Reading Area is the Datalogic technology based on a multi-laser architecture and a fixed mounted optic system which concentrates the multiple laser emissions in a single laser beam. As each laser emitter is focused on a specific range of the reading area, a sophisticated electronic controller selects the best focused laser emitter with respect to the code to read. This allows the reading of medium-high density codes in a large reading area on very fast conveyors.
Flexibility	The high frequency laser diode modulation system guarantees complete immunity to ambient light and allows installation of the DS8110 in any working area.
Reading parcels on conveyors	As a result of the ASTRA multiple laser technology, DX8210 and DS8110 give a great real time DOF even on high speed conveyors. Furthermore, DX8210 and DS8110 implement the PackTrack functionality which leads to an increase of the plant production as a result of the augmented system throughput.
EBC	Ethernet Based Connectivity is a reliable real-time network communication between scanners in a reading station tunnel or array.
e-Genius	e-Genius is a browser-based User Interface with the following characteristics: No software to install; Multilanguage platform; All the configuration parameters stored in the scanner; Not dependent on the Physical interface; Remote access through local network.
Energy Saving	A software parameter group which allows management of the energy saving feature. In particular, it allows turning on/off the motor and laser of all network scanners according to the selected digital input, encoder, or communication channel. The time required to restart the system is less than 1 minute independently from the number of scanners connected. It is suggested to use this parameter for example when the conveyor is stopped for a lengthy period.

1.3 MODEL DESCRIPTION

The DX8210 barcode scanner is available in versions that differ depending on the interface connection, the optical resolution and on the optic version:

$$DX8210 - X\ X\ X\ X$$

Laser Number:

2 = Double lasers
4 = Four lasers

Optical Resolution:
1 = Standard resolution
2 = High resolution

Optic Version:
0 = Linear

Communication Type:
0 = Standard version
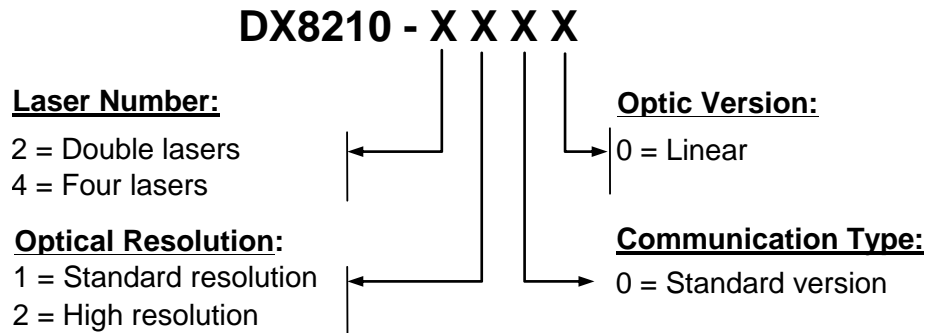
Figure 4: Model Description Key

1.4 DX8210 VERSIONS

Model	Description	Part Number
DX8210-2100	2 Laser, Standard Resolution	936300001
DX8210-4100 (focus 1)	4 Laser, Standard Resolution	936300003
DX8210-4200 (focus 2)	4 Laser, High Resolution	936300004

1.5 X-PRESS (HUMAN MACHINE INTERFACE)

The DX8210 barcode scanner includes two external buttons that make up the X-PRESS HMI interface and perform specific tasks without the need of connecting to **e-Genius**. *See section 5.5* for functional description.

Figure 5: DX8210 X-PRESS Interface Buttons

NOTE: Some of these functions may be performed using **e-Genius**. *See Chapter 4.*

1.6 ACCESSORIES

The following accessories are available on request for the DX8210 barcode scanner.

Category	Description	Part Number
Cables and Terminators		
Ethernet Cables	ETH CABLE M12-M12 1M (straight-straight) Scanner to Scanner EBC (ETH1 or ETH2)	93A050065
	ETH CABLE M12-M12 3M (straight-straight) Scanner to Scanner EBC (ETH1 or ETH2)	93A050066
	ETH CABLE M12-M12 5M (straight-straight) Scanner to Scanner EBC (ETH1 or ETH2)	93A050067
	ETH CABLE M12-M12 1M (straight- 90°) SC5000 to Scanner EBC (ETH1 or ETH2)	93A050068
	ETH CABLE M12-M12 3M (straight- 90°) SC5000 to Scanner EBC (ETH1 or ETH2)	93A050069
	ETH CABLE M12-M12 5M (straight- 90°) SC5000 to Scanner EBC (ETH1 or ETH2)	93A050070
	ETH CABLE M12-RJ45 5M (90°-RJ45) SC5000 to the Host or Configuration PC (HOST or CFG)	93A050088
	CAB-ETH-M01 M12-IP67 1M (straight- RJ45) Scanner to the Host or Configuration PC	93A051346
	CAB-ETH-M03 M12-IP67 3M (straight- RJ45) Scanner to the Host or Configuration PC	93A051347
	CAB-ETH-M05 M12-IP67 5M (straight- RJ45) Scanner to the Host or Configuration PC	93A051348
REDs Cables	ETH CABLE M12-M12 1M (90°- 90°) SC5000 to SC5000 EBC (ETH1 or ETH2)	93A050087
	REDS POWER ALARM CABLE 5M PWR-480B to CBX510 power alarm connections	93A050086
EBC Patch Cable	ETH CABLE M12-M12 0.5M (straight-straight) Female to Female EBC patch cable; close the EBC when a scanner is sent to repair, only for Master/Slave	93A050085
Interface Cable	SC5000 to CBX510 for Serial or I/O connections	93A050071
CBX Cables	CAB-DS01-S M12-IP67 1M Scanner to CBX for Serial or I/O connections	93A050058
	CAB-DS03-S M12-IP67 3M Scanner to CBX for Serial or I/O connections	93A050059
	CAB-DS05-S M12-IP67 5M Scanner to CBX for Serial or I/O connections	93A050060
AS-I Terminal	AS-I CABLE TERMINAL for AS-I branch topology wiring	93ACC0083
Power Cables	PWR CABLE, AS-I, 2 Wires, 10M (Backbone with caps)	93ACC0081
	PWR CABLE, AS-I, 2 Wires, 25M (Backbone with caps)	93ACC0082
	PWR CABLE M12- ASI standard 1M (Node)	93ACC0067
	PWR CABLE M12- ASI standard 2M (Node)	93ACC0068
	PWR CABLE ext. M12 Male-M12 Fem 3M for PG-240	93ACC0149
	PWR CABLE ext. M12 Male-M12 Fem 5M for PG-240	93ACC0150
	PWR CABLE, CAB-LP-05 M12 Female-Free Wires 5M for alternative power connections	93A050037
Connection Boxes		
	CBX100 Compact	93A301067
	CBX100 Compact All in One (includes BM100)	93A301076
	CBX510 Modular	93A301087
	CBX510 Modular All in One (includes BM100) + BA200	93A301091
Backup Module	BM100 Backup Module	93ACC1808
Mounting Hardware	BA200 Mounting Adapters (to Bosch or 80/20 Frames)	93ACC1822
Fieldbus Modules	BM300/310 Profibus Module STD/IP65	93ACC1810, 93ACC1811

Category	Description	Part Number
Fieldbus Modules	BM700/710 Profinet Module STD/IP65	93ACC1816, 93ACC1886
Controllers		
	SC5000-1000 Standard System Controller	935750001
	SC5000-1100 Profibus System Controller	935750002
	SC5000-1200 Profinet System Controller	935750003
Mounting Hardware	BA200 Mounting Adapters (to Bosch or 80/20 Frames)	93ACC1822
Power Supplies		
	PG-100-K03 POWER SUPPLY 60W KIT (US) w/ M12 cable	93ACC0058
	PG-100-K01 POWER SUPPLY 60W KIT (EU) w/ M12 cable	93ACC0059
	PG-100-K02 POWER SUPPLY 60W KIT (UK) w/ M12 cable	93ACC0060
	PG-240-K03 POWER SUPPLY 240W 8 Port M12 (US) w/o M12 Cable	93ACC0144
	PG-240-K01 POWER SUPPLY 240W 8 Port M12 (EU) w/o M12 Cable	93ACC0145
	PWR-480B POWER UNIT 110/230VAC 24V	93ACC0076
Sensors		
	MEP-593 PHOTOCELL KIT PNP (PH-1) with Free Wires	93ACC1791
	MEP-604 PHOTOCELL KIT PNP M12-M12 Photocell with M12 connector for SC5000	93ACC0140
Encoders		
	OEK-2 OPTICAL ENCODER KIT (CAB 10M +SPRING)	93ACC1770
	OEK-4 ENC KIT PNP 250PPR + M12-M12 CABLE	95B082040
	OEK-4 ENC KIT PNP 250PPR + M12-FREE CABLE	95B082050
Field Mount Connectors	FMC-5000 2xM12 TRIG+ENC INPUT KIT Connectors for PLC signal to SC5000 (Tilt-Tray or Cross-Belt applications)	93ACC0181
Mounting Brackets		
L-Bracket	L-Bracket	L-Bracket
L-Bracket	L-Bracket	L-Bracket

1.7 PHOTOELECTRIC SENSOR

The optional Datalogic Photoelectric Sensor is used in DX8210 barcode scanner systems to detect the presence of an item in the scanning area.

The photoelectric sensor is used in singulated systems where the packages are separated by an open space between the trailing edge of one package and the leading edge of the next. The photoelectric sensor, along with the encoder, enables a programmable transmit point at a defined distance from the sensor. Without the photoelectric sensor, the barcode scanner can be run in continuous mode. *See **4.5.1 Modify Settings | Global Settings | Operating Mode**.*

Depending on the application, these devices may need to be configured differently. While the photoelectric sensor and tachometer work well with belt conveyors, a special configuration is needed for tilt-tray and cross-belt sorter applications. *See section 3.11 for wiring options.*

Figure 6: Photoelectric Sensors

Photoelectric Sensor and Cable (recommended)

MEP-593 PHOTOCELL KIT	PNP (PH-1) with Stripped Wires	93ACC1791
MEP-604 PHOTOCELL KIT	PNP M12-M12 Photocell with M12 connector for SC5000	93ACC0140

1.8 ENCODER (TACHOMETER)

The tachometer provides a continuous pulse to the system, which provides feedback on conveyor speed and transmit point, and can be used to help track the package position along the length of the conveyor. *See section 3.12 for wiring options.*
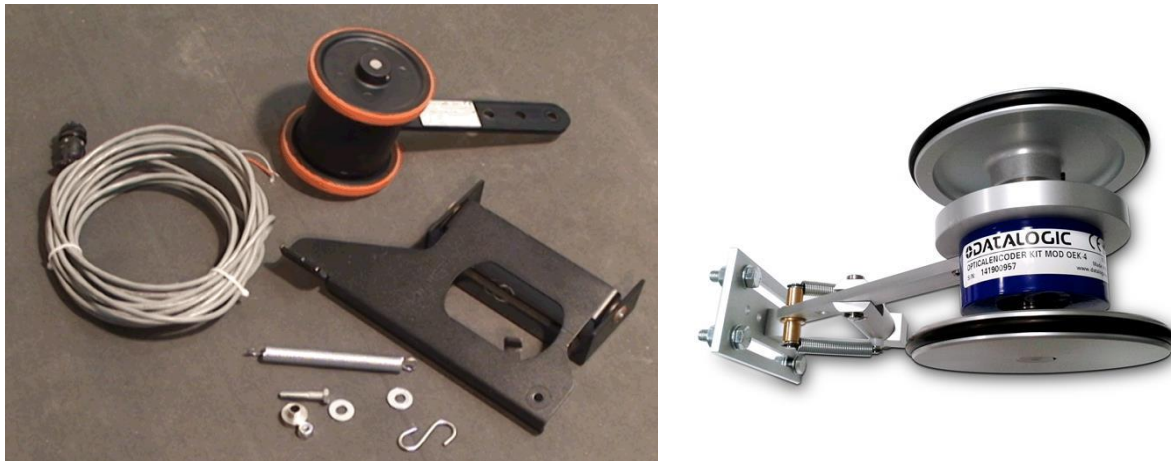
Figure 7: Encoder/Tachometer, Mounting Bracket, and Cable

Encoder (Tachometer)

OEK-2 ENCOD KIT	OEK-2 ENC KIT (CAB 10m +SPRING)	93ACC1770
OEK-4 ENCOD KIT	OEK-4 ENC KIT PNP 250PPR + M12-M12 CABLE	95B082040
OEK-4 ENCOD KIT	OEK-4 ENC KIT PNP 250PPR + M12-FREE CABLE	95B082050

1.8.1 Encoder/Tachometer Step Settings

The following table shows the **Encoder Step** setting used based on pulses per revolution. The Encoder Step setting is entered in **e-Genius** *(see section 4.5.1 Modify Settings | Global Settings | Operating Mode – Encoder Step (hundredths of millimeter))*

Encoder Model	PPR (Pulses Per Revolution)	PPI (Pulses Per Inch)	Encoder Step Setting
OEK-4 (Datalogic)	250	20	63
OEK-2 (Photocraft)	24	2	635
OEK-2	48	4	317
OEK-2	192	16	79
OEK-2	240	20	63

NOTE: The maximum allowed encoder frequency is 5 kHz (equivalent to an encoder set to 20 PPI with a conveyor speed of 381 m [1250 ft.] /minute.

1.8.2   Photocraft Encoder/Tachometer Switch Setting
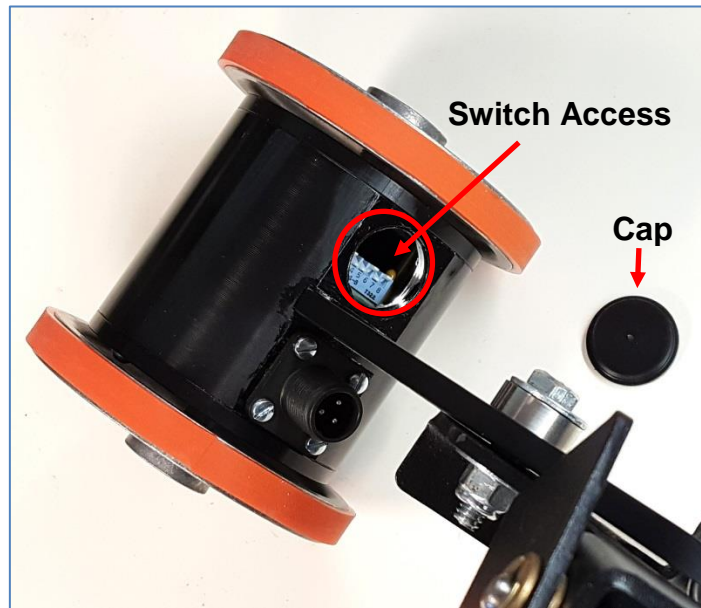
Figure 8: Photocraft (OEK-2) Encoder/Tachometer Switch Location
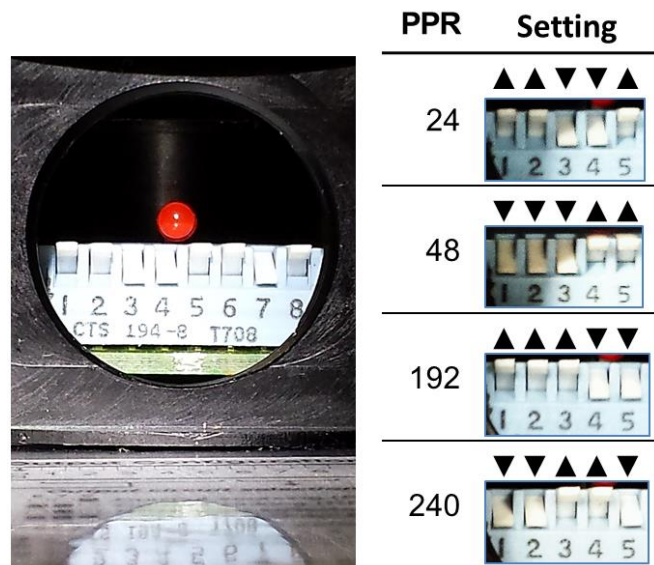
NOTE: Only switches 1-5 are used to set the PPR (Pulses Per Revolution). Switches 6-8 are used for PNP/NPN settings as shown in the label on the arm of the encoder.

Figure 9: Photocraft (OEK-2) Encoder/Tachometer Switch Settings

1

1.9 CBX INDUSTRIAL CONNECTION BOX

CBX Series are industrial connection boxes that can be used to connect the barcode scanners to an encoder/tachometer, photoelectric sensor, serial devices, relays, or other peripherals. The CBX510 includes a BM100 backup module, which allows easy parameter restore and backup operations. The backup module also provides an easy way to upload existing parameters to a replacement barcode scanner when necessary. *See section 3.9 for wiring options.*

Figure 10: CBX510 Connection Box

NOTE: Scanner operation requires a CBX510 connection box or SC5000 controller.

Industrial Connection Box

CBX510 Connection Box	CBX510 for DS8110 and DX8210	93A301087
CBX510 Connection Box	CBX510 ALL IN ONE + BA200	93A301091

1.10 SC5000 SYSTEM CONTROLLER

The SC5000 Controller offers all the necessary functions to make the phases of installation, setup, testing, and maintenance of the omni-directional reading array or tunnel easy and quick.

The SC5000 Controller is fully compatible with DS8110 and DX8210 scanners and its sturdy mechanical structure makes the SC5000 Controller the ideal solution for industrial environments. The Controller allows connection to the Trigger and Encoder/Tachometer. PNP inputs are available via M12 circular connectors, placed on the lower front panel *(see section 3.15).* NPN can be wired directly to the internal terminal block *(see section 3.9).*
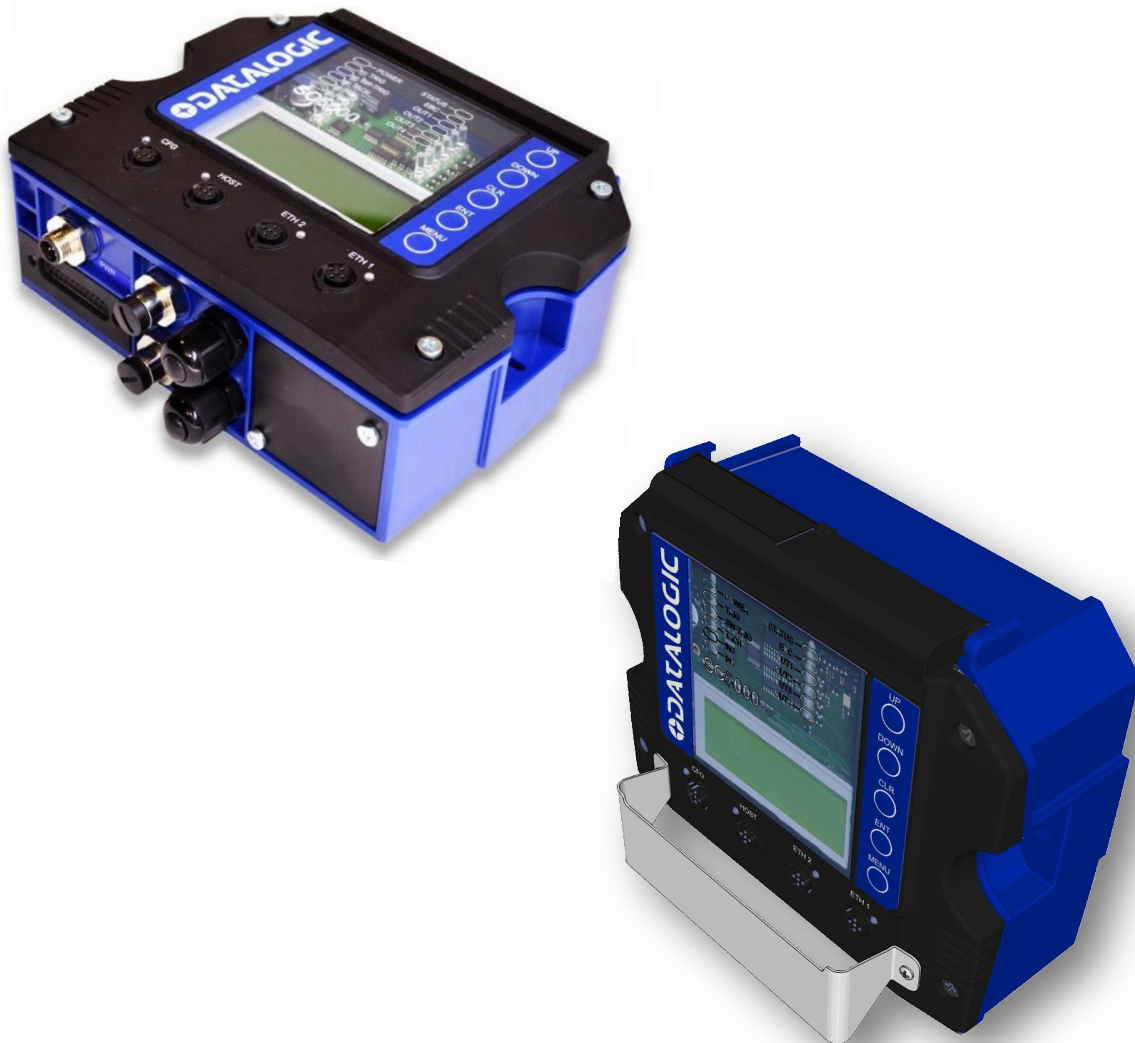
Figure 11: SC5000 System Controller

System Controller

SC5000-1000 System Controller	Standard	935750001
SC5000-1100 System Controller	Profibus	935750002
SC5000-1200 System Controller	Profinet	935750003

2   MECHANICAL INSTALLATION

WARNING: Electrical Installation by Qualified Service Technicians Only! Procedures may involve exposure to high-voltage. A trained and authorized technician must perform these procedures. Do not attempt to perform any electrical installation procedures unless you are a trained technician.

IMPORTANT: DX8210 barcode scanners contain electronics that may be affected by electrostatic discharge (ESD). To prevent personal injury or damage to the unit, please follow the safety precautions and warnings found in the References section at the beginning of this manual. Failure to follow these precautions may void your warranty.

2.1   PREPARING FOR MECHANICAL INSTALL

IMPORTANT: Application-specific drawings and documents provided by Datalogic supersede any contradictory content in this manual.

Before mounting any components, please do the following:

- Read all instructions before beginning your installation.

- Define and confirm the accuracy of your application's requirements and structure position, especially the height of the conveyor from the floor.

- Review all installation-specific drawings provided with your equipment.

- Review and plan the mechanical installation of all devices used in your application. Be sure to allow adequate clearance for maintenance.

- Review and plan the power requirements for your application.

- Check the contents of the shipping cartons against the packing list.

- Record all product serial numbers.

NOTE: Refer to the *Chapter 3 Electrical Installation* and Reference Documentation for details on connecting your barcode scanners to other devices in the system.

WARNING: When installing several scanners, take care to position them so that no laser beam enters the reading window of other scanners. This condition could occur more frequently for side mounted applications. If these precautions are not followed, read rate could be negatively affected. To resolve this problem, it is sufficient to slightly change the inclination and position of one of the two scanners involved.

2.2 UNPACKING INSTRUCTIONS

Verify that the DX8210 barcode scanners and all the parts supplied with the equipment are present and intact when opening the packaging; the list of parts includes:

- DX8210 barcode scanner

- L-Bracket

- Mounting screws and washers

- Shoulder screw *(see Figure 15: Keyhole mounting with large L-Bracket)*

- Barcode Test Chart

Figure 12: Package contents

2.3 INSTALLATION SEQUENCE

NOTE: Everything should be MECHANICALLY INSTALLED before performing any ELECTRICAL INSTALLATION.

See Chapter 3 Electrical Installation for electrical installation details.

To complete mechanical installation and setup, you must:

- Review the details of your application's requirements

- Erect mounting structure or other supporting structures

- Determine and mark the Mounting Bracket location(s)

- Mount the bracket to the mounting structure

- Mount the DX8210 to its mounting bracket

- Mount the photoelectric sensor to the mounting structure (optional)

- Mount the tachometer to the mounting structure (optional)

- Mount the CBX connection box to the mounting structure

- Mount the SC5000 to the mounting structure

- Complete electrical installation *(See Chapter 3)*

- Align the DX8210 for proper operation

- Configure the DX8210 *(See Chapter 4)*

- Check DX8210 operations *(See Chapter 5)*

2.4 WHAT YOU NEED TO KNOW ABOUT YOUR APPLICATION

To assure you get optimal performance out of your DX8210, it must be installed to meet the complete needs of your application. Therefore, take the time to learn the details of your application. The better you know your application, the easier it is to apply the DX8210's capabilities to meet your application's requirements.

Below is what you will need to know before you can begin installation:

- Conveyor Specifications

    - Conveyor type: Belt, tilt-tray, cross belt, other?
    - What is the conveyor width?
    - What is the conveyor speed?
    - Does conveyor speed vary or is it constant?

- Product Specifications

    - Are the packages being transported always singulated (not touching) or non-singulated (possibly touching)?
    - How many different product sizes may be involved?
    - Are products justified: toward/away from reader, centered, or variable?

- Application Specifications

    - How will the barcode information be used in your application?
    - What are your communication requirements?

While it is nearly impossible to cover all application configurations, the next several pages provide the basics on determining how to mechanically install your DX8210. If you need additional assistance, contact your sales representative or customer service (www.datalogic.com).

2

2.5 MECHANICAL INSTALLATION

2.5.1 Dimensions and Clearances

The overall dimensions of the DX8210 are 384 x 128 x 328 mm [15.1 x 5 x 12.9 in].
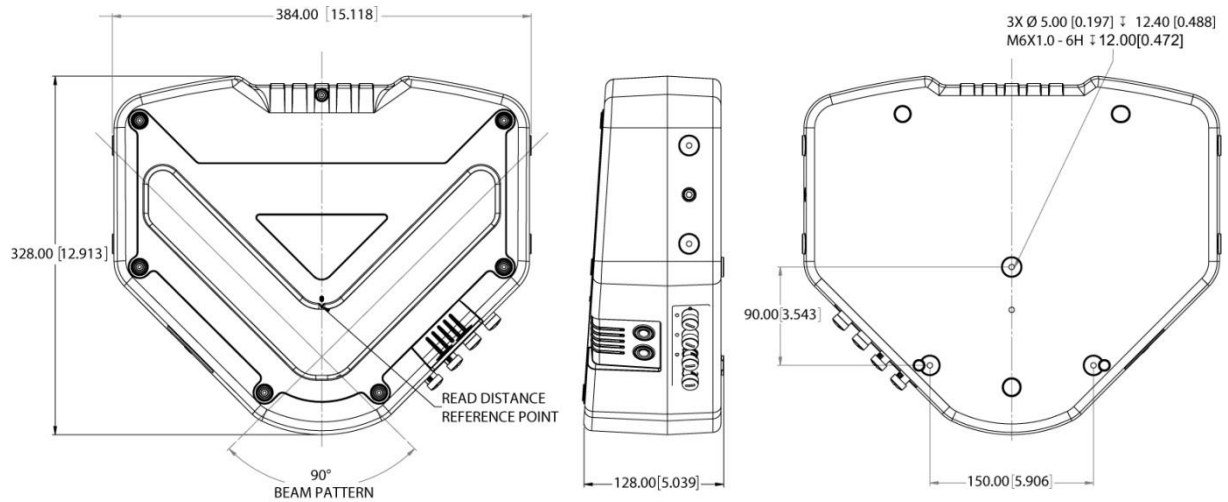
Figure 13: DX8210 Overall Dimensions

IMPORTANT: The DX8210 is a sealed, unventilated unit. Mounting the unit with 300mm [12 inches] of clearance (front, top, and sides) is recommended for cooling and ease of maintenance.

2.5.2 Physical Support Requirements

For details on the weight of the barcode scanners, *see Chapter 8, Technical Features.* Multiple-head systems may include further details on the physical support requirements with any application-specific documentation provided.

2.5.3 Vibration Limitations

See Chapter 8, Technical Features.

2.5.4   General Mounting Guidelines

It is important that you follow these general precautions when installing, setting up, operating, maintaining, troubleshooting, or replacing any Datalogic products, parts or related equipment.

As you plan and install your DX8210 barcode scanning system application, be sure to keep the following guidelines in mind:

- All mounting structure assembly and equipment installation can be performed by one installer.

- Determine the proper orientation and position of the barcode scanner.

- Leave adequate clearances (approximately 300 mm [12 inches]) for wiring.

- Route wires carefully to reduce or minimize electrical noise. When power and communication wiring must cross, make their intersection perpendicular.

- Proper grounding limits the effects of noise due to Electromagnetic Interference (EMI).

2.5.5   Mounting Structure Considerations

Your first task is to mount your DX8210 barcode scanner. You can provide your own mounting structure or Datalogic can design one for you. We recommend using a Datalogic mounting structure for standard applications.

Your mounting structure must provide the following capabilities:

- It is adjustable enough for you to move your unit to the optimum position for proper scanning.

- It allows a technician access to the barcode scanner while it is mounted.

- It must be as vibration free as possible so as not to affect the scanning accuracy.

- It is constructed of steel or aluminum.

- It provides approximately 300 mm [12 inches] minimum clearance on all sides. This clearance is necessary to provide proper ventilation, allow access to all panels of the barcode scanner, and allow room for proper servicing.

2.5.6 Mounting the Scanner

The DX8210 can be installed to operate in any position. There are screw holes (M6 X 8) on the sides and back of the scanner for mounting. The diagram below can be used for installation; refer to your application drawing for correct positioning of the scanner with respect to the reading zone and scanner orientation.

There are two bracket options for mounting the DX8210, the large rear-mounted L-Bracket (93ACC0151, included in the box with the reader), and two smaller side-mounted L-Brackets (93ACC0079, optional accessories).

Large Rear-Mounted L-Bracket
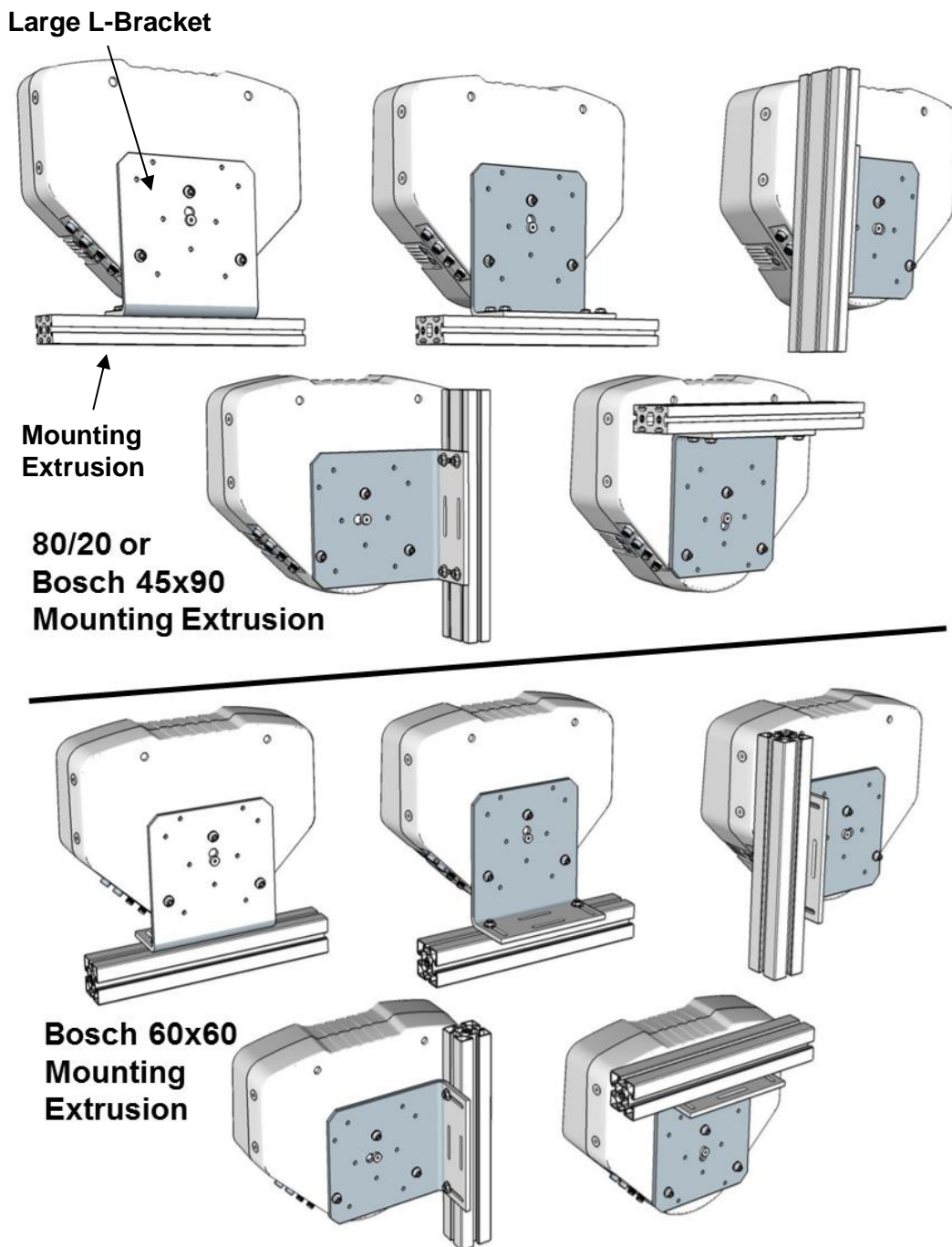
Figure 14: DX8210 Large L-Bracket Mounting Options (93ACC0151, Included with Reader)

To aid in mounting the DX8210 with the large L-Bracket, mount the bracket to the mounting structure as shown. Next, insert the shoulder screw (provided) into the central mounting hole in the back of the unit, and then hang the scanner using the brackets keyhole, as shown in figure 14 below. Finally, secure the scanner to the bracket with mounting screws.

Mounting Screws

Bosch 60x60 Mounting Extrusion

Large L-Bracket

Shoulder Screw

DX8210

1. Slip the shoulder screw up through the large end of the keyhole.

2. Slide the scanner to the small end of the keyhole.
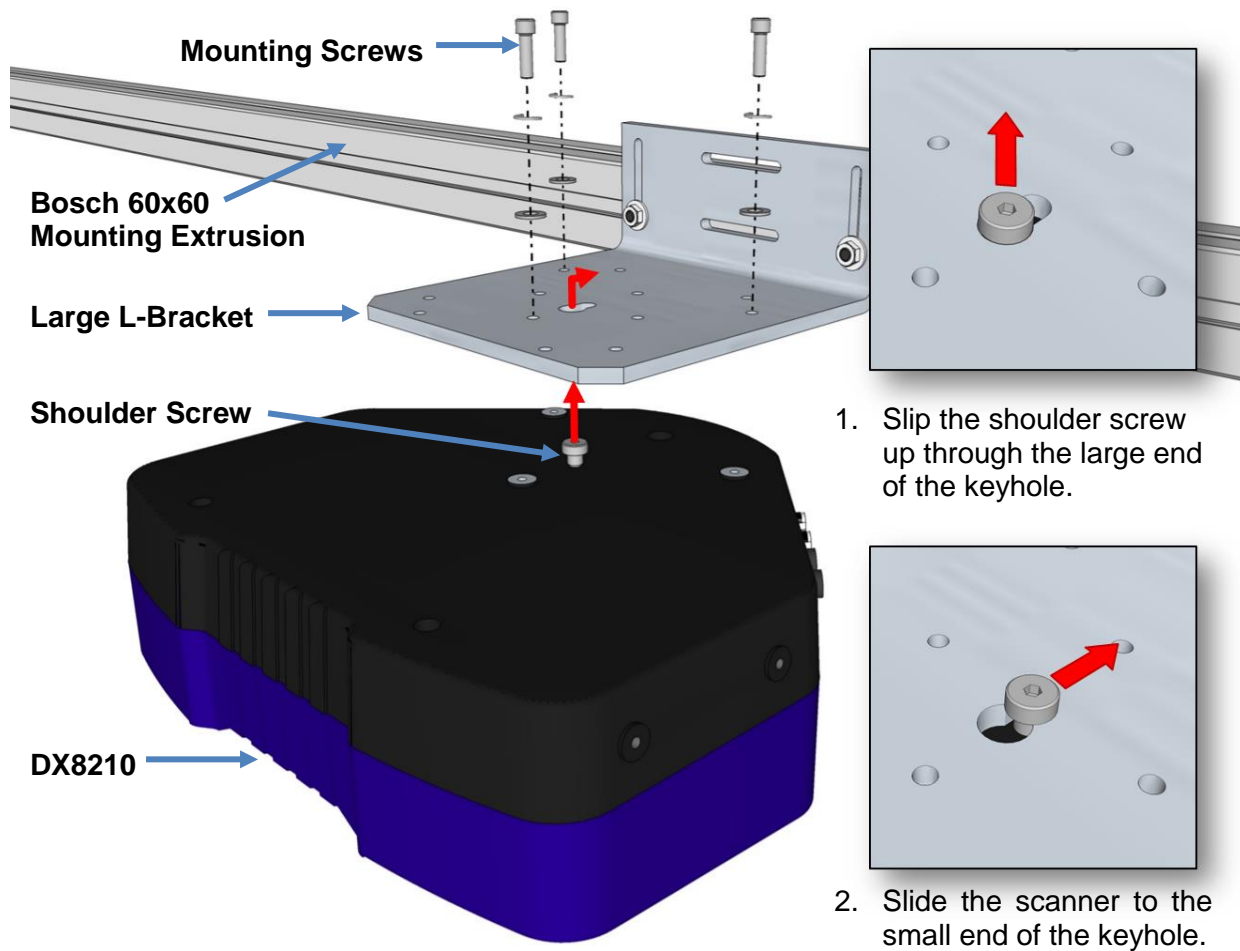
Figure 15: Keyhole mounting with large L-Bracket (Bosch 60x60 Extrusion)

Mounting Screws

80/20 or Bosch 45x90 Mounting Extrusion

Large L-Bracket

Shoulder Screw

DX8210

3. Slip the shoulder screw up through the large end of the keyhole.

4. Slide the scanner to the small end of the keyhole.
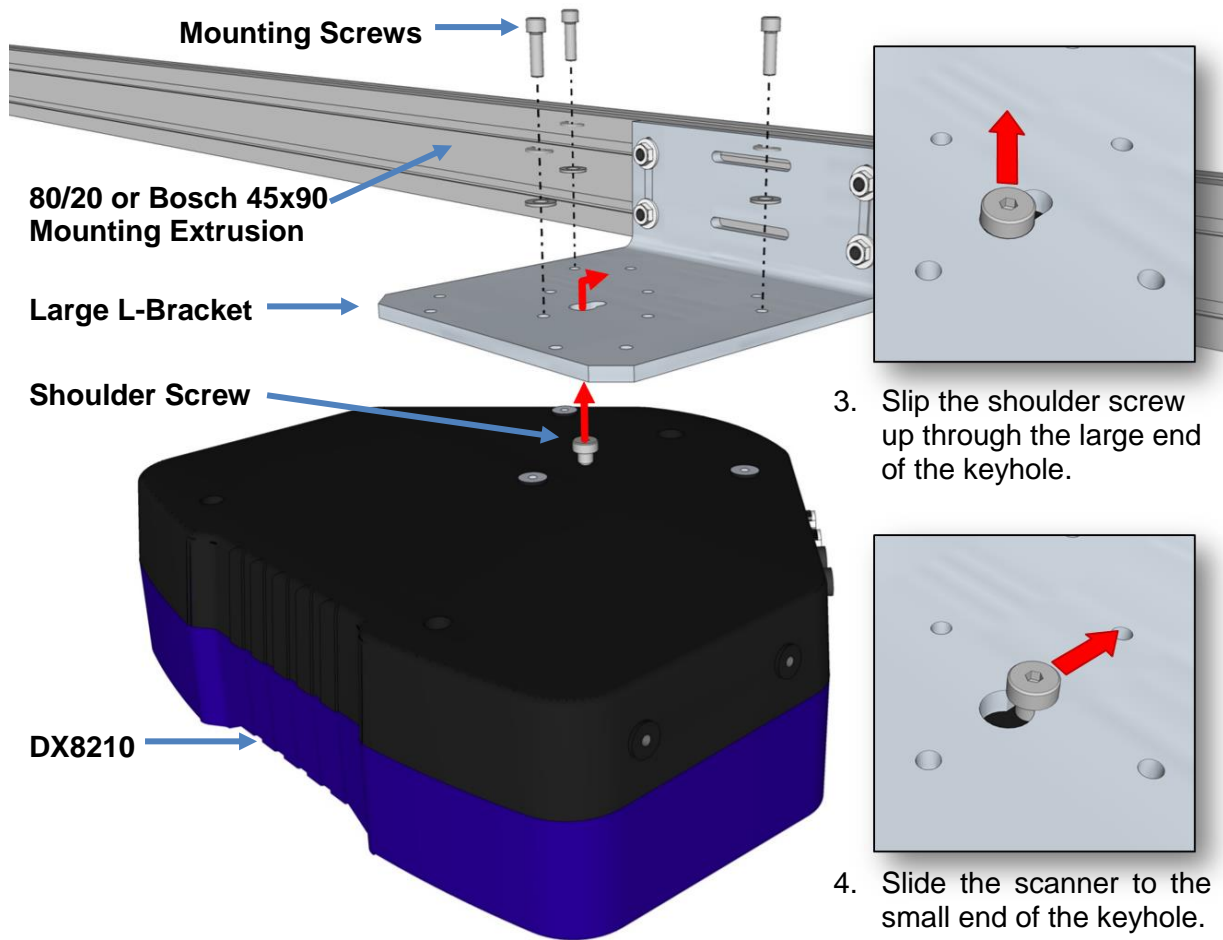
Figure 16: Keyhole mounting with large L-Bracket (80/20 or Bosch 45x90 Mounting Extrusion)

Small Side-Mounted L-Brackets

Small L-Brackets

80/20 or Bosch 45x90 Extrusion

Mounting Structure

Bosch 60x60 Extrusion
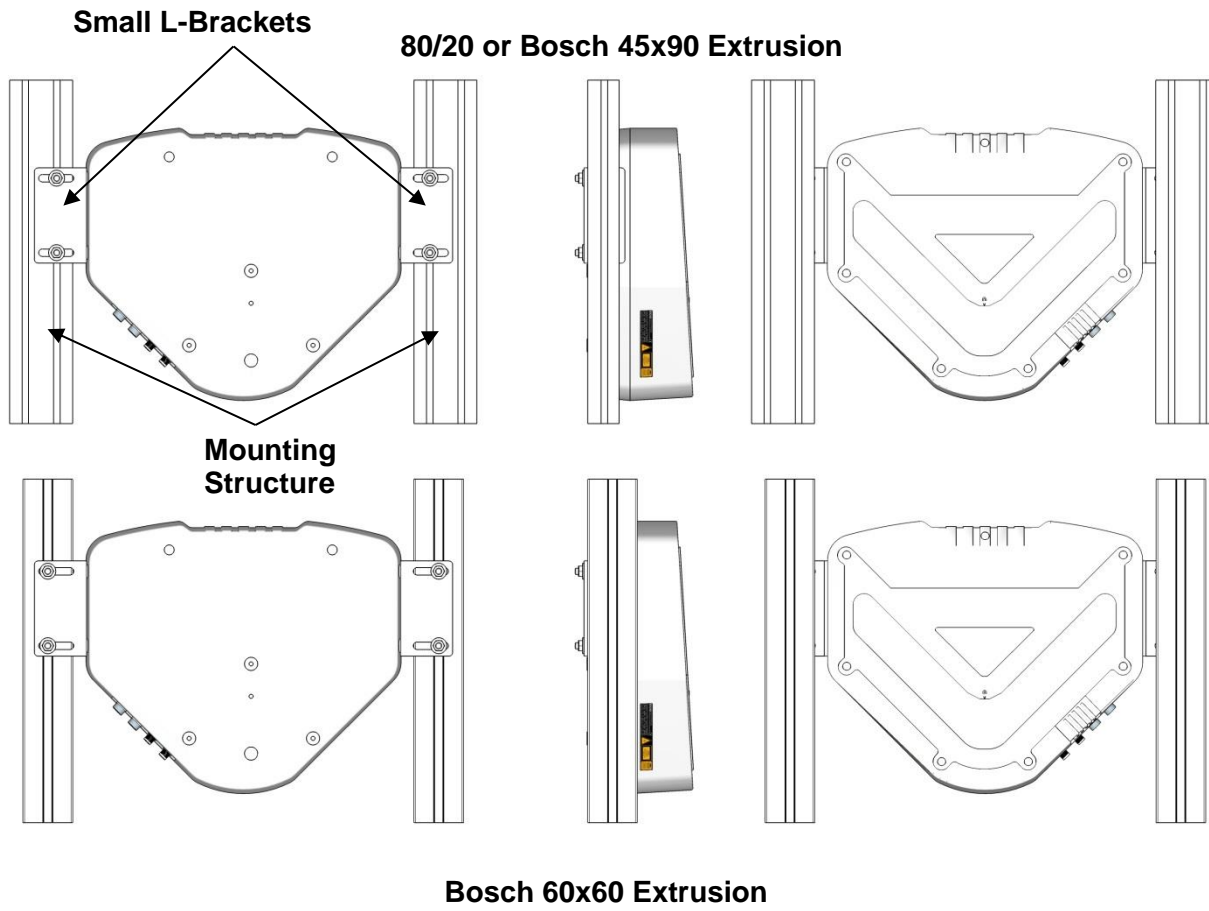
Figure 17: DX8210 Small L-Brackets Mounting Options (93ACC0079)

3 ELECTRICAL INSTALLATION

WARNING: Electrical Installation by Qualified Service Technicians Only! Procedures may involve exposure to high-voltage. A trained and authorized technician must perform these procedures. Do not attempt to perform any electrical installation procedures unless you are a trained technician.

IMPORTANT: ThE DX8210 barcode scanners contain electronics that may be affected by electrostatic discharge (ESD). To prevent personal injury or damage to the unit, please follow the safety precautions and warnings found in the References section at the beginning of this manual. Failure to follow these precautions may void your warranty.

3.1 PREPARING FOR ELECTRICAL INSTALLATION

Before mounting any components, please do the following:

- Read all instructions before beginning your installation.

- Observe all electrical safety requirements discussed in the Introduction to this manual.

- Define and confirm the accuracy of your application's requirements.

- Review all installation-specific drawings.

- Review and plan the power requirements for your application.

- Review and plan the communications requirements for your application.

IMPORTANT: The content of this manual may be superseded by any customer-specific documentation provided by Datalogic. Before proceeding with any installation procedures, be sure to review ALL documentation, especially content that contains details specific to your installation.

NOTE: Everything should be MECHANICALLY INSTALLED before performing any ELECTRICAL INSTALLATION. See Chapter 2 for mechanical installation details.

Most DX8210 applications are shipped with the CBX connection box and all the necessary cabling required to electrically install the system. If your system requires custom-length cables or other special wiring, documentation specific to these requirements has been provided in your shipment. This special documentation supersedes any contradictory content in this manual.

NOTE: To reduce the possibility of damage to the unit, check all cabling between the scanner and other devices for accuracy.

3.2 CONNECTING A DX8210 SCANNER

To install a DX8210 barcode scanner, follow this sequence:

- Complete mechanical installation *(See Chapter 2.)*

- Complete electrical installation *(See wiring illustrations provided in this chapter.)*

- Observe all electrical safety requirements outlined in this chapter.

- Ground the mounting structure to protective earth (PE) ground.

- If used, wire the photoelectric sensor (or other trigger) to the CBX connection box/SC5000.

- Wire the tachometer to the CBX connection box/SC5000 (if used).

- Wire serial ports to the CBX connection box/SC5000 if needed.

- Connect the M12 end of the Ethernet cable to the scanner's HOST port and network switch as required by your application.

- Connect the scanner to its power supply.

- Connect the power supply to the power source.

- Setup / check scanner operations *(See Chapter 5.)*

3.3 TYPICAL CONNECTION BLOCK DIAGRAMS

3.3.1 Single DX8210 Barcode Scanner to CBX
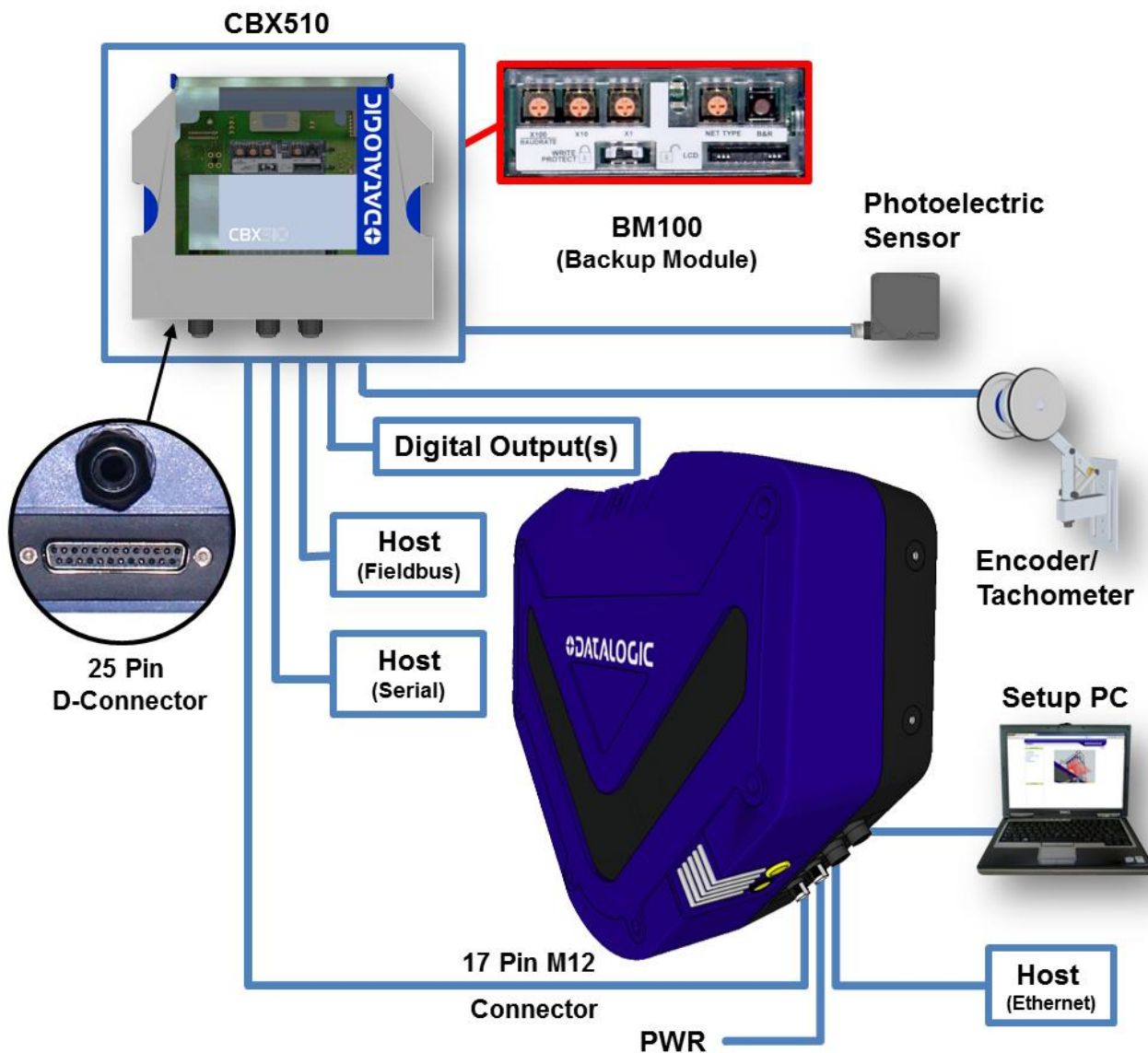
Figure 18: Single DX8210 to CBX510

NOTE: The BM100 switches indicated below must be set to 0 (zero), and the connector indicated is not supported.
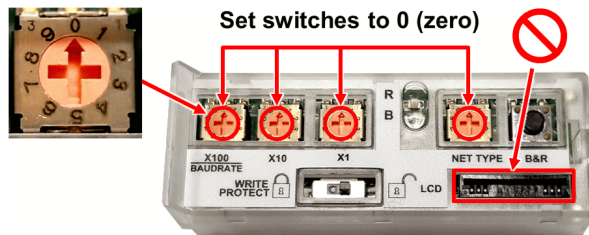
Figure 19: BM100 Backup Module in CBX510

3.3.2   Master/Slave Array with CBX510
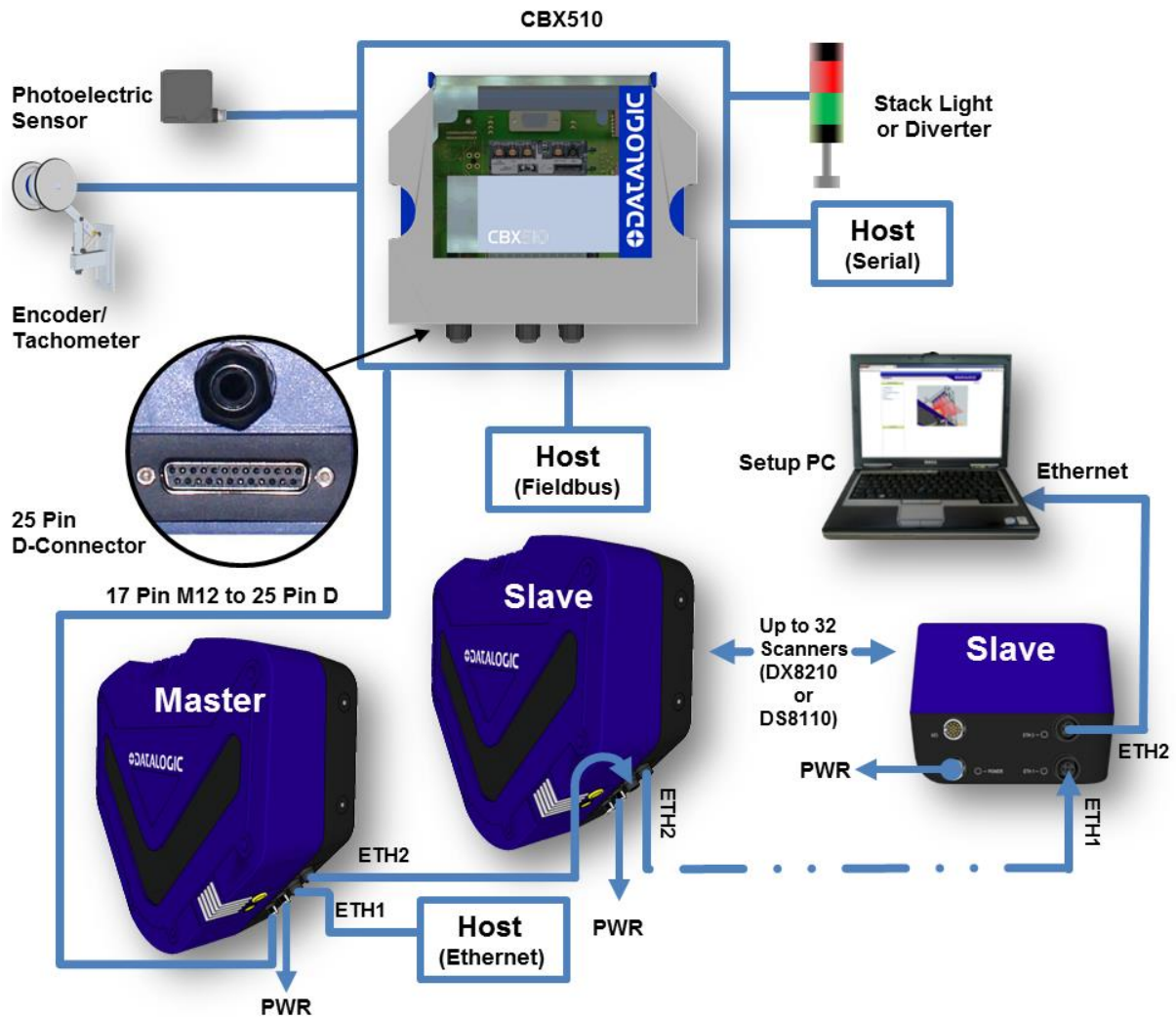
Figure 20: DX8210 Array (Tunnel) to CBX510

NOTE: The BM100 switches indicated below must be set to 0 (zero), and the connector indicated is not supported.
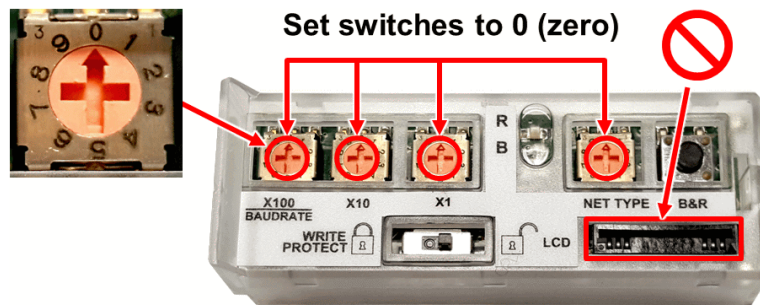
Figure 21: BM100 Backup Module in CBX510

3.3.3 DX8210 Barcode Scanners in an Array with SC5000 Master

In an array (tunnel) using the SC5000 Controller, the chain of scanners completes a circle from and to the SC5000 Controller via ETH1 and ETH2. In this scenario, if one scanner fails, communication from the other scanners to the SC5000 Controller is not interrupted.
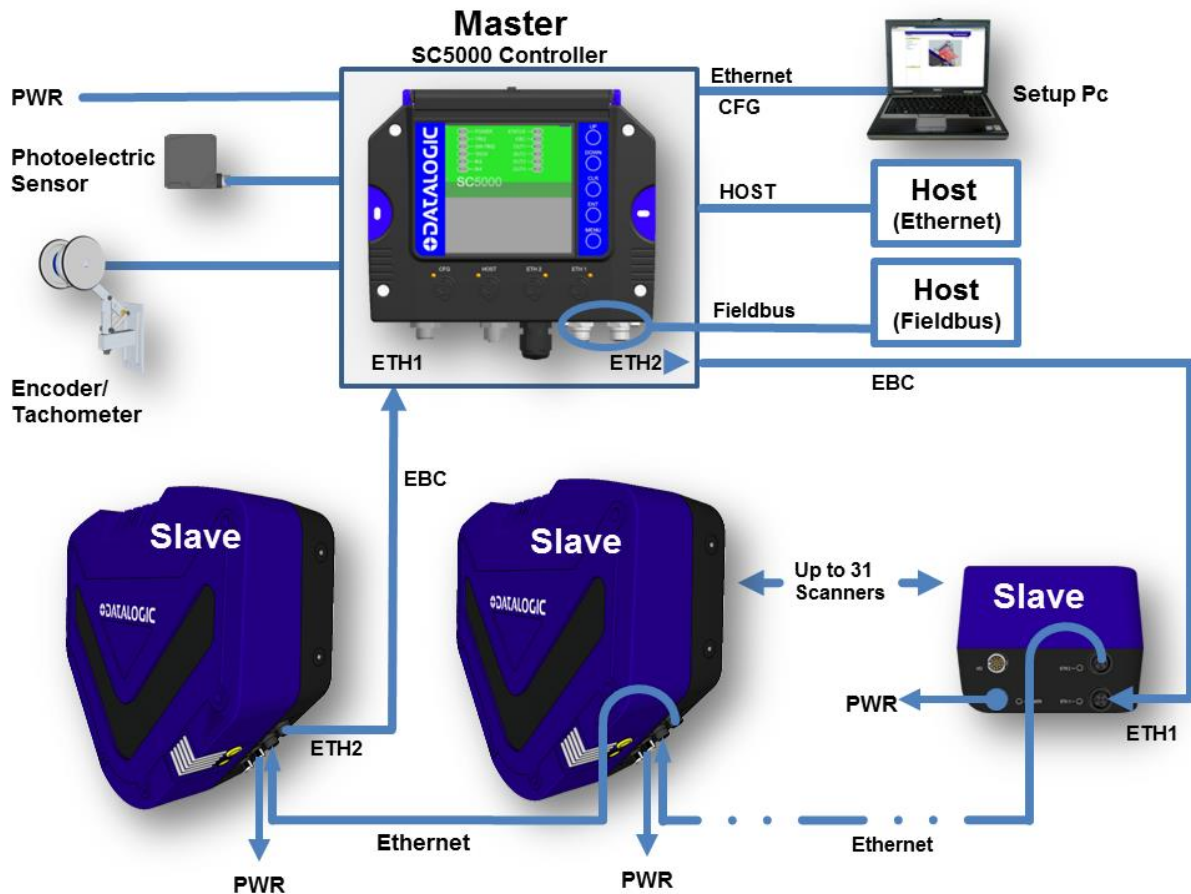
Figure 22: DX8210 Array (Tunnel) with SC5000

NOTE: When using the SC5000, a **Fieldbus Host** only connects to the SC5000 Fieldbus model (Profinet or Profibus) at the connectors shown. It cannot connect to the CBX.

An **Ethernet Host** connects to the **HOST** connector on the SC5000 top cover. A **Serial Host** must connect through the CBX *(see Figure 23).*
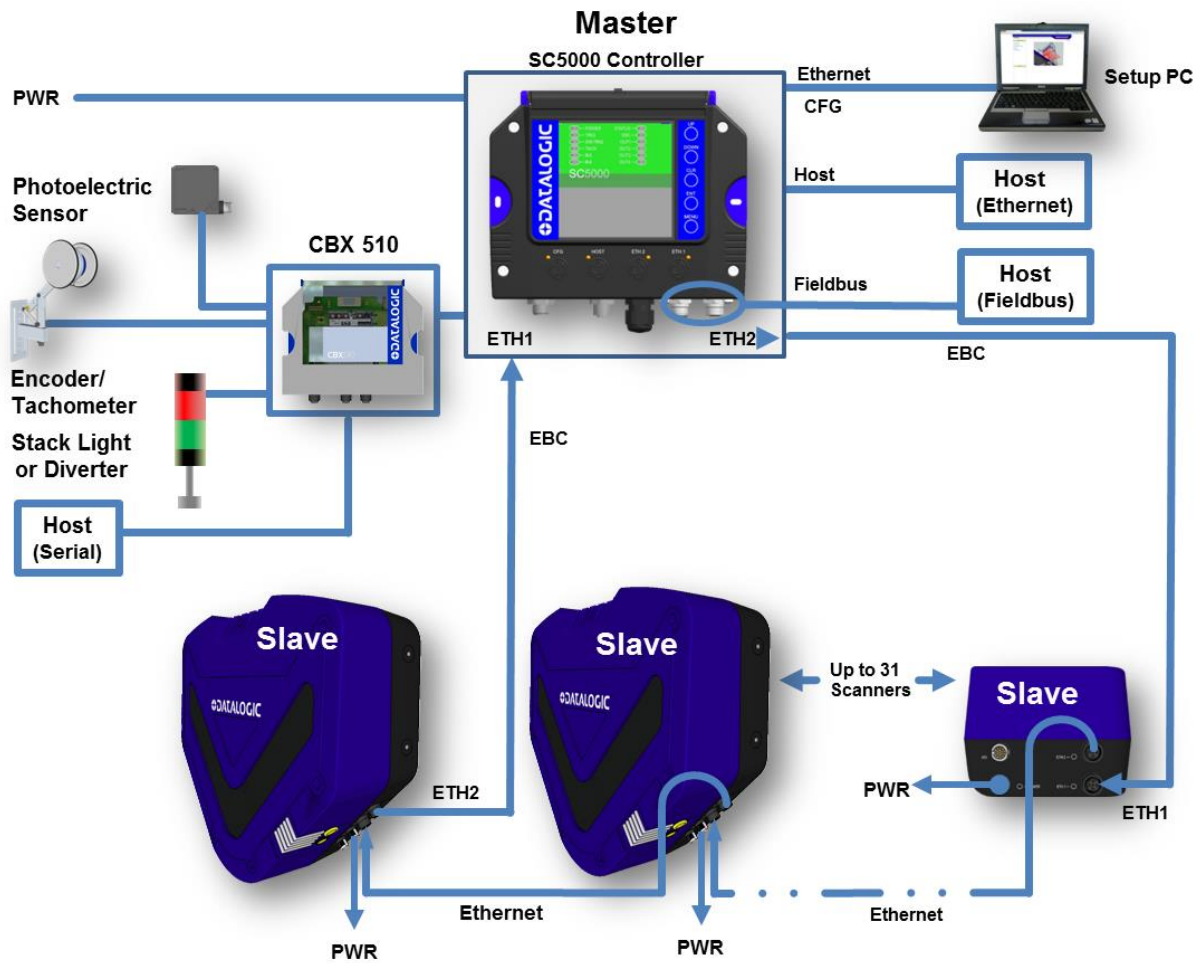
Figure 23: DX8210 Array (Tunnel) to SC5000 (alternate with CBX)

3.4 GENERAL ELECTRICAL INSTALLATION GUIDELINES AND PRECAUTIONS

It is important that you follow these general precautions when installing, setting up, operating, maintaining, troubleshooting or replacing any Datalogic products, parts or related equipment. As you plan and install your scanner(s), be sure to keep the following guidelines in mind:

• Determine the scanner is in the proper location as outlined in Chapter 2.

• Leave adequate clearances (approximately 300mm [12 inches]) for wiring.

• Route wires carefully to reduce or minimize electrical noise.

• When extraneous power and communication wiring must cross, make their intersection perpendicular. Avoid running power and data wiring parallel to each other. If possible, maintain one of the following separations between the power and data wiring:

  • 300 mm [12 inch] gap
  • use steel conduit and 25 mm [1 inch] gap
  • 6.5 mm [0.25 inch] of aluminum.

IMPORTANT: When planning your installation wiring, remember all power connections must be quick-disconnect. For PERMANENTLY CONNECTED EQUIPMENT a readily accessible disconnect device must be incorporated in the building installation wiring. For PLUGGABLE EQUIPMENT the socket-outlet must be installed near the equipment and must be easily accessible

WARNING: To assure no ESD damage will occur, be sure to observe the precautions outlined in the Introduction to this manual.

IMPORTANT: Ground the mounting structure to safety ground (protective earth ground (PE)). See wiring recommendations for safety ground.

3.5 DX8210 CONNECTOR PANEL

After completing mechanical installation, use this section to properly wire your scanners for optimal performance in your application. DX8210 wiring connections are made to the connector panel and through the CBX connection box (connected to the I/O port of the scanner). In most applications, the cable connections to the scanner will include:

1. ETH 2 (Setup or EBC scanner network, default IP Address: 192.168.3.100)
2. ETH 1 (Host or EBC scanner network, default IP Address: 172.27.101.220)
3. POWER
4. I/O (Connects directly to the 25-pin D type connector on the CBX connection box)

NOTE: The M12 I/O connector Vcc pin is allowed a max sink current of 0.6A.
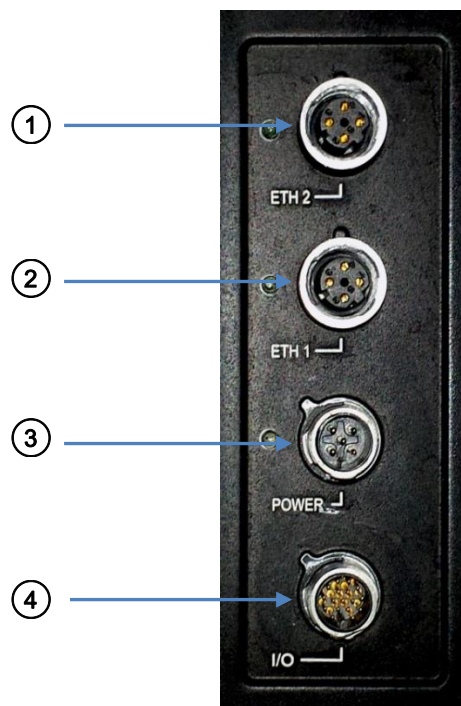
Figure 24: DX8210 Connector Panel

Route wiring to the scanner's connector panel through the wiring channels (if available) on the Datalogic mounting structure when running interconnecting cables between other devices and the scanner.

Figure 25: Wiring Channels

3.6 CONNECTING A PC TO THE DX8210

During initial setup, a PC (laptop) may be connected to the DX8210 with a M12 to RJ45 cable. Screw the M12 connector to the ETH 2 port of the scanner and plug the RJ45 into the Ethernet port of your PC. If the ETH 2 port is in use, ETH 1 port can be used. For information on connect to **e-Genius**, *see Chapter 4.*

NOTE: ETH2 is typically the **Setup** port, **ETH1** is the **HOST** port.
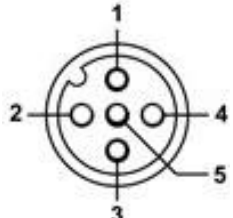
NOTE: A laptop can only communicate to a scanner that is connected to a CBX Connection Box or SC5000 Controller.

NOTE: Parameters for tunnel are set up in MASTER scanner (or SC5000 Controller only.)

3.7 POWER CONNECTOR PIN-OUT TABLE

A recommended power supply and cabling is available with the DS8110 and DX8210 (and SC5000 Controller). However, if your installation requires custom power supply wiring, the pin-outs of the unit power connector are provided below for your convenience.

24V - - - 4A MAX		POWER Input	
		Unit Connector (shown)	Mating cable connector
		5-PIN M12-TYPE MALE	5-PIN M12-TYPE FEMALE
MALE 5-PIN M12-TYPE	Pin	Function	
	1	+24 VDC	
	2	n/c	
	3	dc return	
	4	n/c	
	5	protective earth (chassis)	

NOTE: When using a DX8210 barcode scanner, no power supply is required for the CBX510 connection box. All power and some communication options are fed to the CBX510 through the scanner's 17-pin I/O connector to the CBX510 25-pin connector using the cable provided.

NOTE: In cases where the AS-I cabling is not used, the alternative CAB-LP-05 cable can be used to connect the power supply to the scanner. Connect the Brown/White pair to +24 Vdc and the Blue/Black pair to 0 V- (GND).

3.8 POWER CONNECTIONS

IMPORTANT: When planning your installation wiring, remember all power connections must be quick-disconnect.

CAUTION: While performing the following wiring connection procedures, be sure to follow all safety procedures regarding high-voltage as outlined in the Introduction to this manual. No power should be applied to any device until all wiring is completed and checked for accuracy.

IMPORTANT: The socket-outlet must be installed near the scanner. The outlet must be a readily accessible disconnect device.

GROUND: Ground the scanner to safety ground (protective earth ground (PE)). See wiring recommendations for safety ground.

The CBX connection boxes provide flexible connectivity to a range of I/O devices as well as serial hosting. The DX8210 connects to the CBX via its I/O port using a single 17-pin M12 to 25-pin D cable. The CBX connection box also provides space for an optional BM100 backup module (recommended) for parameter storage, allowing quick replacement and configuration of the scanners.

In a system with multiple scanners and other devices required in a scanning array (tunnel), an SC5000 Controller serves as the system Master and provides communications between devices and to the Host. Complete installation information for the SC5000 Controller is available in the *SC5000 System Controller Reference Manual* available at www.datalogic.com.

3.9 CBX510 CONNECTION BOX

Complete installation information for the connection box is available in the **CBX510 Installation Manual** available at www.datalogic.com. A simple drawing of the interior of the box is shown below.
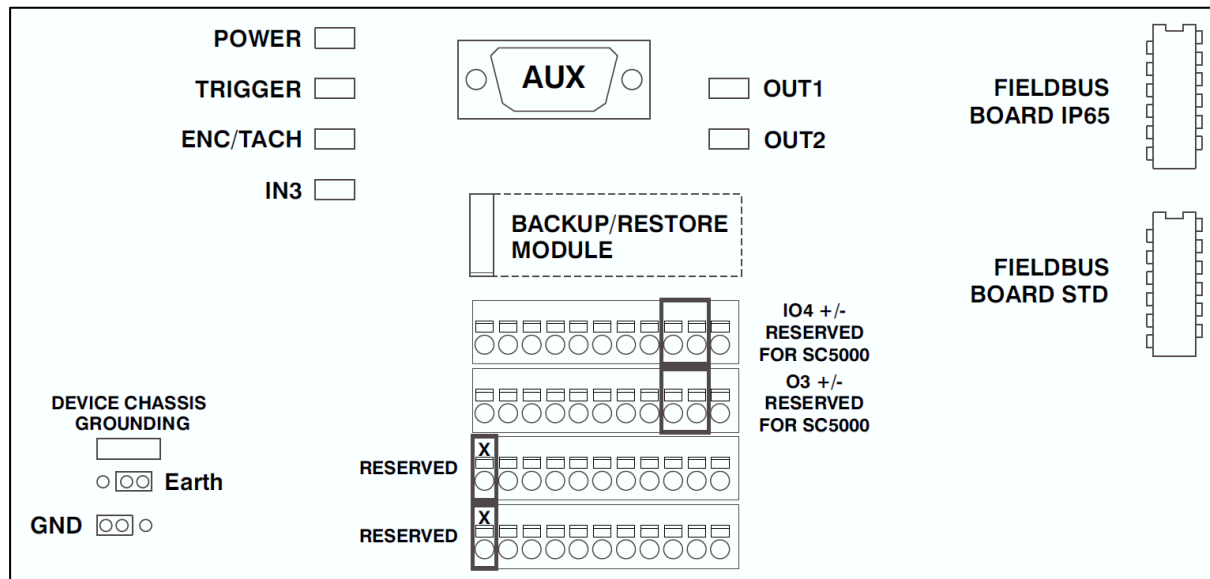
Figure 26: CBX510 Interior

3.9.1 Wiring Into the CBX510 Connection Box

> **WARNING: DO NOT** connect a separate power source to the CBX510 connection box. The CBX510 receives its power through its connection to the DS8110/DX8210 Barcode Scanner. Connecting a separate power source will be detrimental to the system operation.

> **IMPORTANT: DISCONNECT POWER** from the scanning system and CBX510 before wiring any components.

Loose-lead cables must pass through the water-tight seals in the base of the CBX510 connection box. Insert the cables allowing enough slack for the individual wires to reach the appropriate pin block connectors. Securely tighten the water-tight seals after the cables have been inserted.

Insulation on individual wires should be removed to expose 13 mm [0.5 inch] of bare metal before inserting into the pin block.

3.10 MAIN SERIAL INTERFACE

The optocoupled main serial interface is compatible with the following electrical standards:

- RS232
- RS422 full-duplex

3.10.1 RS232 Interface

The main serial interface is used for communication with the Host computer and allows transmission of code data.

It is always advisable to use shielded cables. The overall maximum cable length must be less than 15 m (49.2 ft.).

The following positions of the CBX510 spring clamp connector (row 4) are used for RS232 interface connection:
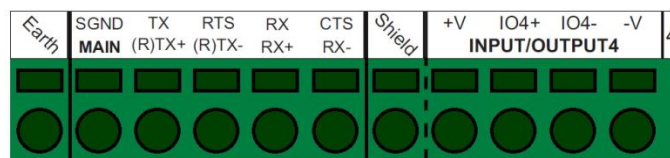
Name	Function
SGND	Signal ground (isolated)
TX	Transmit
RTS	Request to send
RX	Receive
CTS	Clear to send

As suggested above, the cable shield should be connected in the 'Shield' position.

The RTS and CTS signals control data transmission and synchronize the connected devices. If the RTS/CTS hardware protocol is enabled, the scanner activates the RTS output to indicate a message can be transmitted. The Host must activate the CTS input to enable the transmission.

IMPORTANT: RTS/CTS lines should only be connected if the Main serial port handshaking is configure for **Hardware (RTS/CTS)** *(see section 4.5.4).*
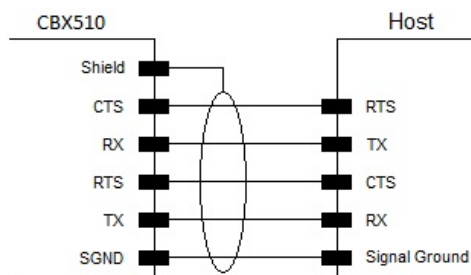
Figure 27 - RS232 Connections: Host – CBX510

3.10.2 RS422 Full-Duplex Interface

The RS422 full-duplex interface is used for non-polled communication protocols in point-to-point connections over longer distances (max 1200 m / 3940 ft.) than those acceptable for RS232 communications or in electrically noisy environments.

The following positions of the CBX510 spring clamp connector (row 4) are used for RS422 full-duplex interface connection:
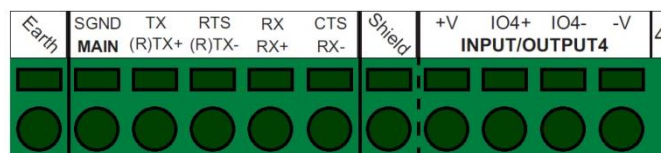
Name	Function
SGND	Signal ground (isolated)
TX+	RS422 output (+)
TX-	RS422 output (-)
RX+	RS422 input (+)
RX-	RS422 input (-)
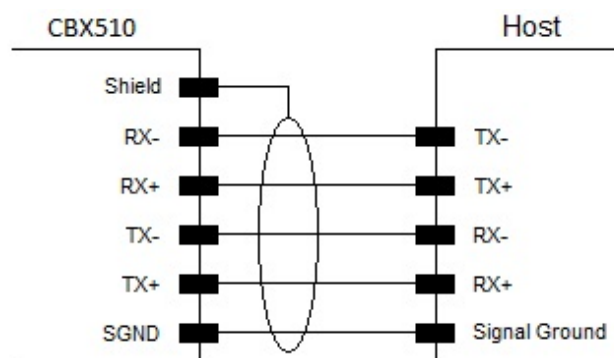
Figure 28 - RS422 Full-Duplex Interface Connections: Host – CBX510

⚠ **IMPORTANT:** For applications that do not use RS422 RX signals, do not leave these lines floating but connect them to SGND as shown below.
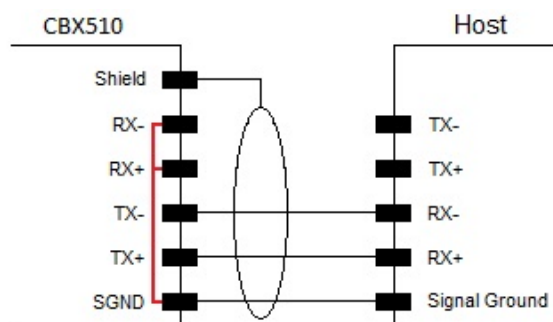
Figure 29 - RS422 Full-Duplex Interface Connections Using Only TX Signals: Host - CBX510

3.11 PHOTOELECTRIC SENSOR CONNECTIONS TO CBX510

Barcode scanning applications may use a Datalogic photoelectric sensor as a trigger device. The photoelectric sensor is wired directly into the CBX510 terminal block.

If your application uses a trigger other than the one specified by Datalogic, follow the appropriate wiring diagram to assure proper wiring.

NOTE: To confirm the photoelectric sensor is functioning properly, watch the TRIG LED while the photoelectric sensor's beam is blocked. The Datalogic photoelectric sensor also includes a status LED.

The following diagrams illustrate standard recommended wiring of the Photoelectric Sensor to the CBX510 terminal block.

3.11.1 Photoelectric Sensor (NPN)
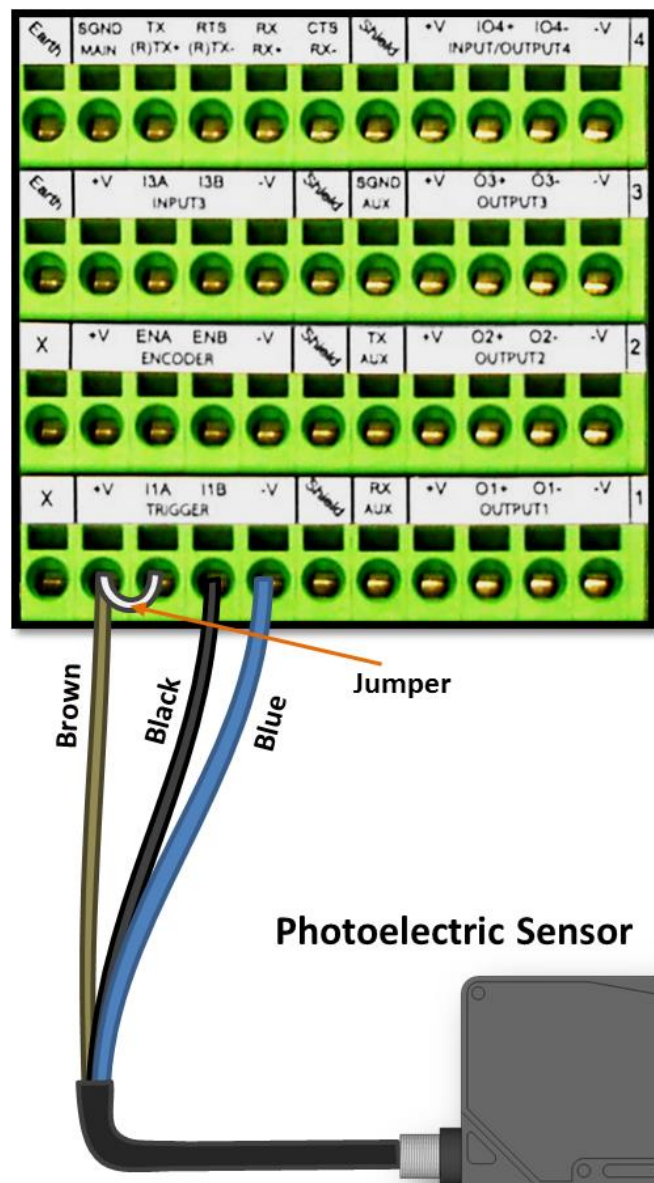
Figure 30: Photoelectric Sensor Wiring (NPN Output)

3.11.2 Photoelectric Sensor (PNP)
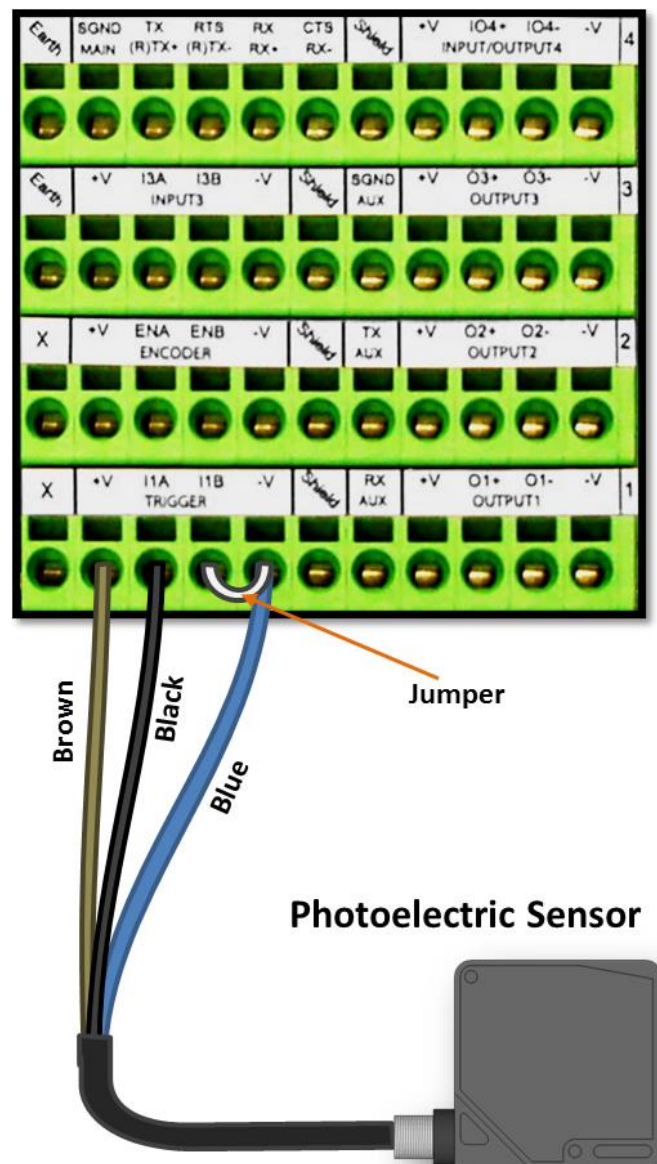
Figure 31: Photoelectric Sensor Wiring (PNP Output)

3

3.12 TACHOMETER WIRING TO CBX510 OR SC5000 CONTROLLER

DX8210 applications over a conveyor belt use an encoder (tachometer) and mounting kit. The following diagrams illustrate standard recommended wiring of an encoder to the CBX510 terminal block.

3.12.1 Encoder/Tachometer Wiring for NPN Output (two models)

NOTE: Some tachometers may have a different color coding:

(+V) Red or **White/Orange**

(Signal) White or **White/Blue**

(Ground) Black or **Orange/White**
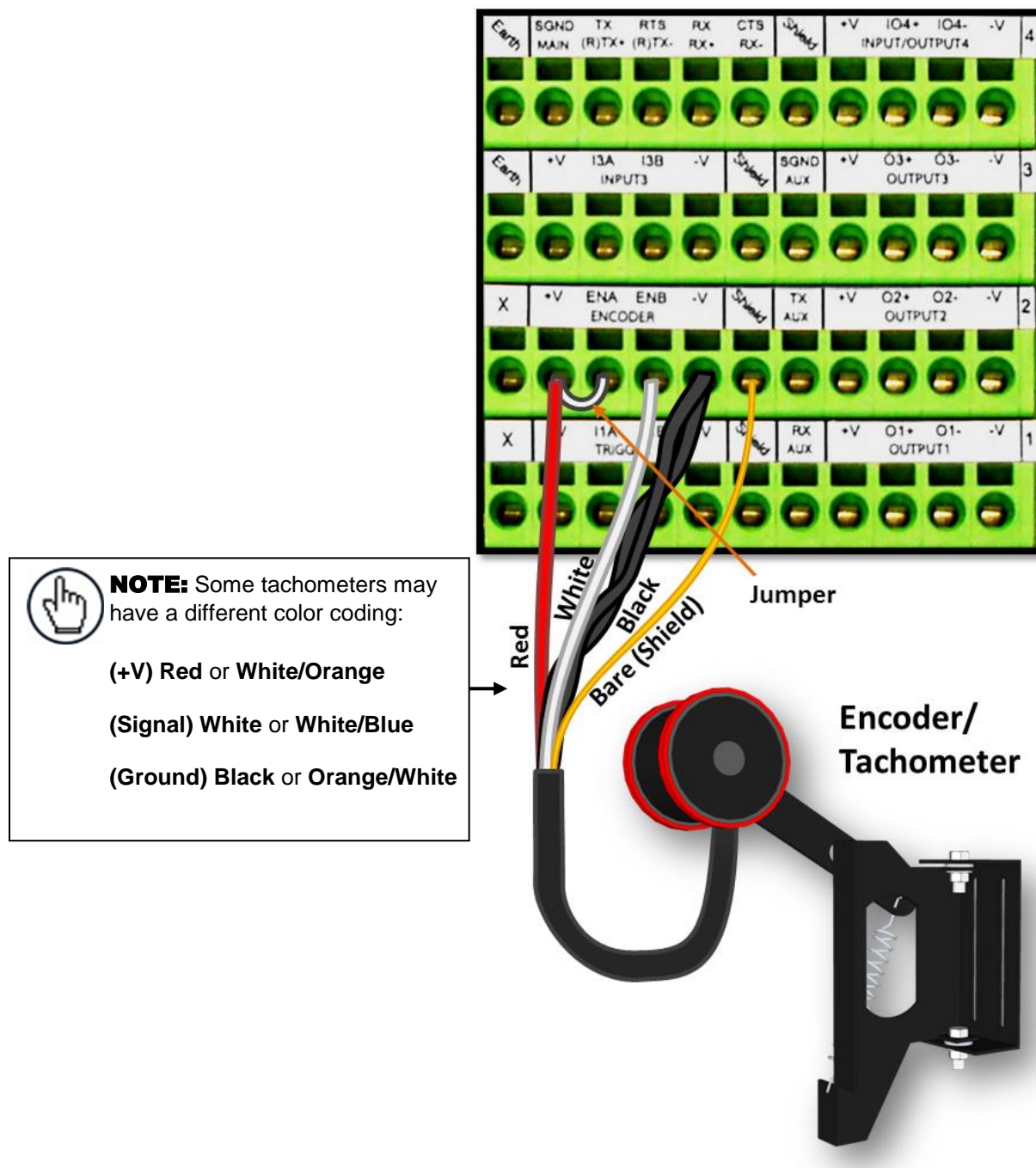
Figure 32: OEK-2 Encoder/Tachometer Wiring (NPN Output)
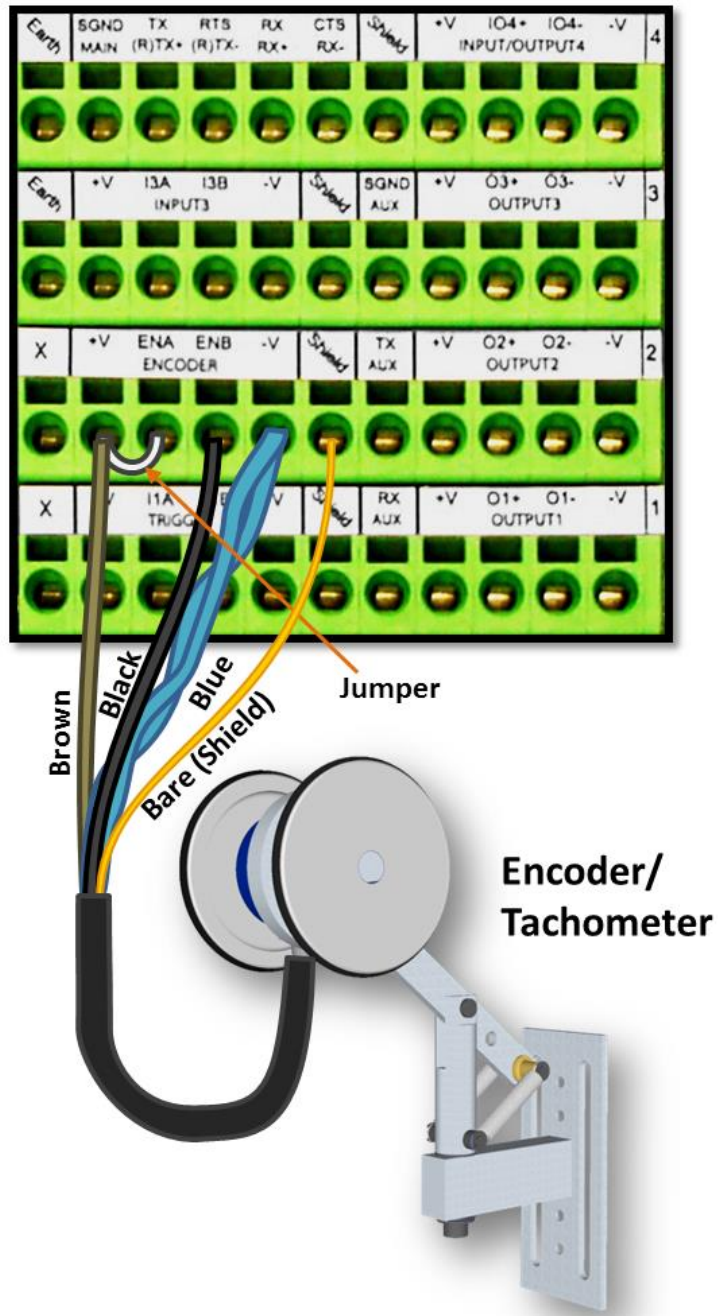
Figure 33: OEK-4 (95B082050) Encoder/Tachometer Wiring (NPN Output)

3.12.2 Encoder/Tachometer Wiring for PNP Output (two models)

NOTE: Some tachometers may have a different color coding:

Red (+V) or **White/Orange**

White (signal) or **White/Blue**

Black (ground) or **Orange/White**
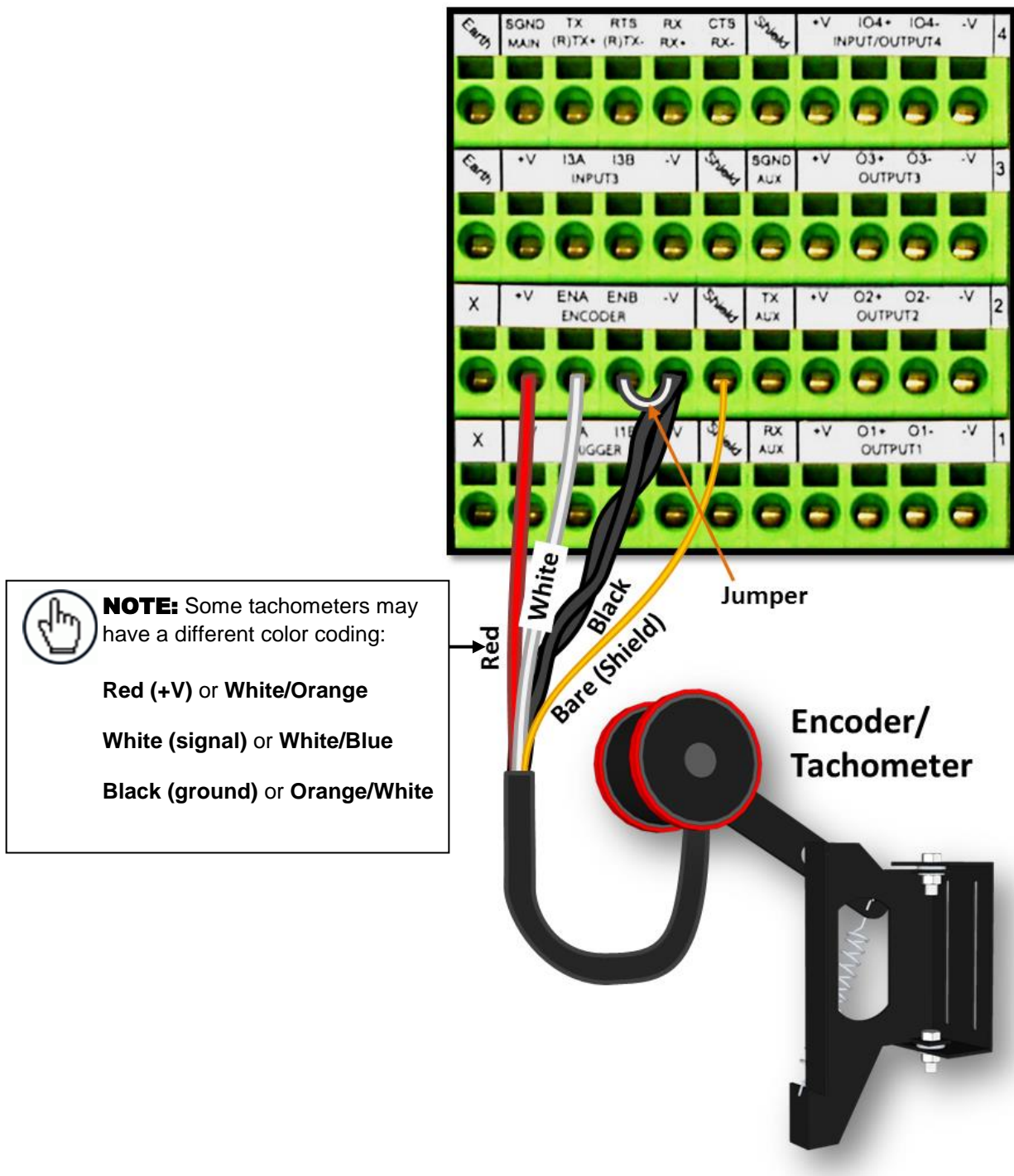
Figure 34: OEK-2 (93ACC1770) Encoder/Tachometer Wiring (PNP Output)
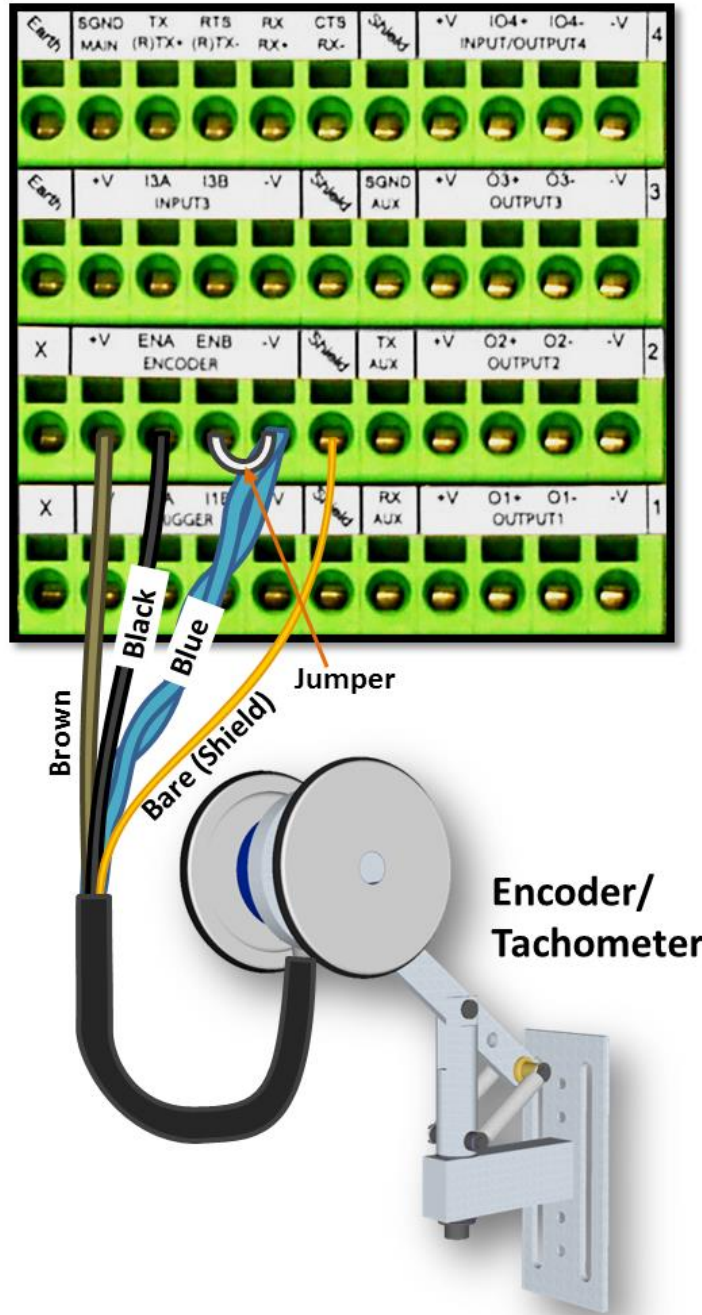
Figure 35: OEK-4 (95B082050) Encoder/Tachometer Wiring (PNP Output)

3

3.14 DIGITAL OUTPUT CONFIGURATION TO CBX510

The CBX510 includes an OUTPUTS block for wiring relays as needed for external accessories. The **e-Genius Modify Settings | Digital I/O** window includes options for outputs 1 and 2 with **Primary** and **Secondary Activation Event** options including **Complete Read, Partial Read, No Read, Trigger On, Trigger Off, Multiple Read, Right/Match,** and **Wrong/No Match**.

Schematics for Isolated and Non-Isolated digital outputs are provided below.
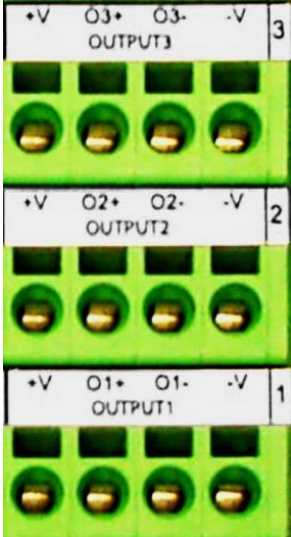
Outputs 1 - 3
Maximum Voltage 30 V
Collector Current (pulse) 130 mA Max.
Collector Current (continuous) 40 mA Max.
Saturation Voltage (VCE) 1 V at 10 mA Max.
Maximum Power Dissipation 90 mW at 50°C (Ambient temperature)

Figure 36: OUTPUTS Block

3.14.1 Unpowered Outputs
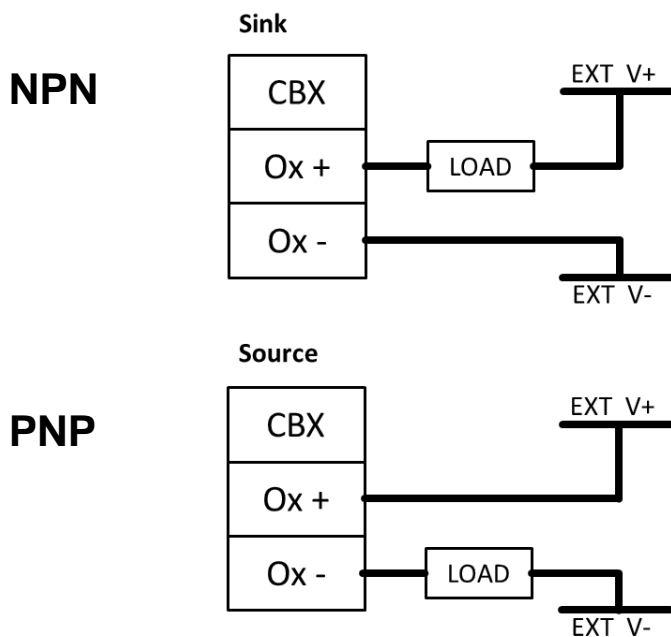
Figure 37: Unpowered Outputs

3.14.2 Powered Outputs
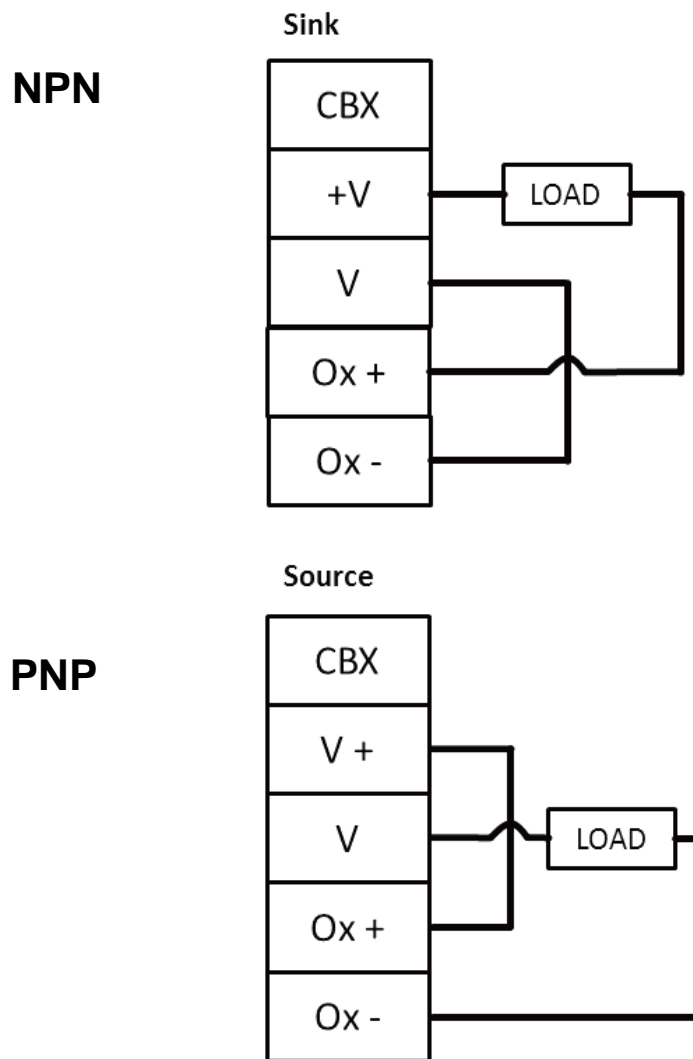
Figure 38: Powered Outputs

3.15 CONNECTING TO THE SC5000 SYSTEM CONTROLLER (OPTIONAL)

In larger scanning arrays (scanning tunnels), an SC5000 controller can act as the system master and support up to 31 slave DS8110/DX82110 barcode scanners in an Ethernet-based connection loop (EBC). SC5000 wiring connections are made to the front and bottom connector panels. In most applications, the cable connections to the scanner will include:

1. CFG (Configuration via laptop Ethernet cable)
2. HOST
3. ETH 1 (EBC scanner network)
4. ETH 2 (EBC scanner network)
5. POWER
6. I/O (Connects directly to the 25-pin D type connector on the CBX connection box)
7. ENC (PNP Encoder/Tachometer)
8. TRG (PNP Trigger/Photoelectric Sensor)
9. Water-tight connectors

Figure 39: SC5000 Bottom Panel Connectors

Complete installation information for the SC5000 Controller is available in the *SC5000 System Controller Reference Manual* available at www.datalogic.com.

3.16 GROUNDING

In order to avoid any problems with electrical noise that could negatively affect system function, make sure that:

1. The AC power cable coming into the PWR box is always provided with a Ground and connected to the proper connector (Protective Earth - PE).

2. The structure where the readers, controllers, encoders/tachometers, and photoelectric sensors are mounted is grounded to the conveyor or to the PE terminal inside the PWR.

3. The Shield wires from the Encoder/Tachometer and photoelectric sensor cables are connected to the proper *Shield* terminal in the CBX box.

4. Normally, steps 1 through 3 will guarantee proper function. In case of problems such as transmission of strange or wrong characters, devices stop working without any reason, or other unexpected behavior, try connecting the CBX or Controller Earth terminal to the PE terminal inside the PWR box.
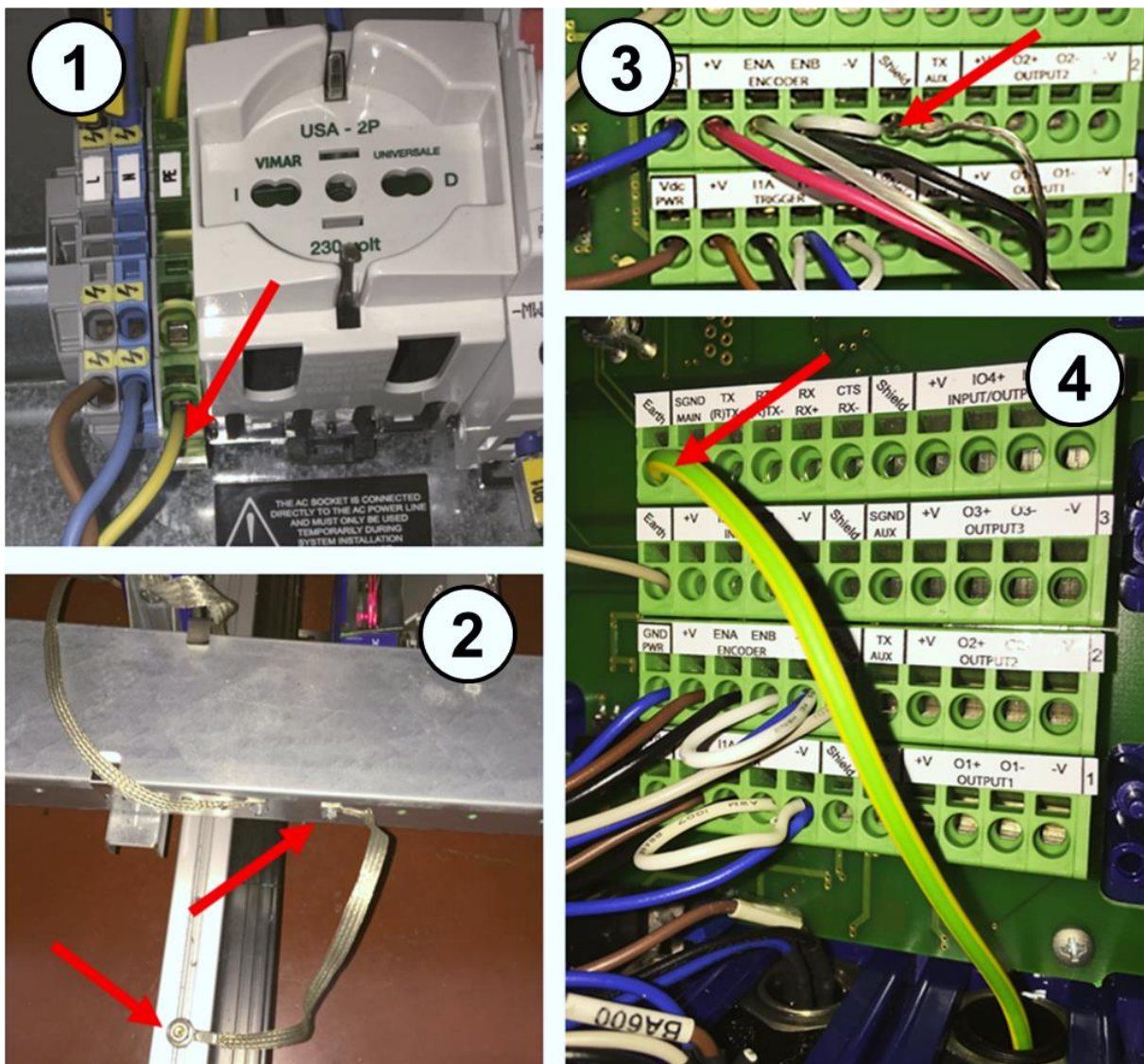
Figure 40: Grounding Examples

3

3.17 CHECK SCANNER INSTALLATION

After completing the installation of your barcode scanner, confirm that the barcode scanners, CBX connection box and/or SC5000 Controller have been properly installed mechanically and electrically. Use the Installation Sequence at the beginning of this chapter and your application specifications to check your installation.

4 E-GENIUS

4.1 GETTING STARTED

The **DS8110/DX8210** barcode scanners are designed for ease-of-setup. **e-Genius** is a browser-based application you will use to define operating parameters, monitor read quality, construct output messages, and view diagnostics. **e-Genius** enables you to easily configure, fine-tune, and monitor your scanner's operation.

e-Genius provides ease-of-use for any operator level.

4.1.1 Prerequisites

Before setting up your barcode scanner you will need the following:

Computer	Laptop
Browser	Internet Explorer 11 (or later)
	Firefox 30 (or later)
	Chrome 36 (or later)

4

4.1.2   Starting e-Genius

To access e-Genius:

NOTE: Before starting up or testing the scanner, it must be connected to a **CBX510 Connection Box** *(see section 3.9)* or an **SC5000 Controller** *(see section 3.15)* depending on the system configuration.

1. Connect your computer to the scanner's ETH 2 (setup) port using either the CAB-ETH-M0x M12-IP67 ETHERNET CABLE or CBL-1534-0.2 ADAPT.CABLE ETH M12-TO-RJ45F. If the ETH 2 (setup) port is taken, ETH 1 (host) can be used.

2. Turn on your computer.

3. If you are connecting to a stand-alone unit (not connected to an in-house network), you must configure your PC's IP Address to be in the same network as the scanner's (or if used, controller's) IP Address.

    To change your PC's IP Address:

    a. From the desktop, click the **Start** button, and then select **Control Panel**.

    b. Type **adapter** in the search box, and then from the results, under **Network and Sharing Center**, click **View network connections**.

    c. Right-click **Local Area Connection** and then select **Properties**.

    d. Select the **Networking** tab. Under **This connection uses the following items**, click **Internet Protocol Version 4 (TCP/IPv4)**, and then click **Properties**.

    e. Select **Use the following IP address**.

    f. In the **IP address** field, type the first 3 octets of the IP address of the reader/controller unit.

    g. For the last octet, type a number that differs from the last octet in the reader/controller's IP address. The actual number used is not important as long as it does not match that of the reader/controller.

        Example: If the barcode scanner's IP Address is 192.168.3.100, set your PC's IP Address to 192.168.3.101.

    h. In the Subnet mask field, type 255.255.255.0

    i. Click **Okay**.

4. Open a web browser and enter the IP address for the DS8110/DX8210. If the correct IP address is entered, the DS8110/DX8210 **Log On** window will appear.

    The default setup IP address for all **DS8110/DX8210** units is: 192.168.3.100 (setup/ETH2) and 172.27.101.220 (Host/ETH1).
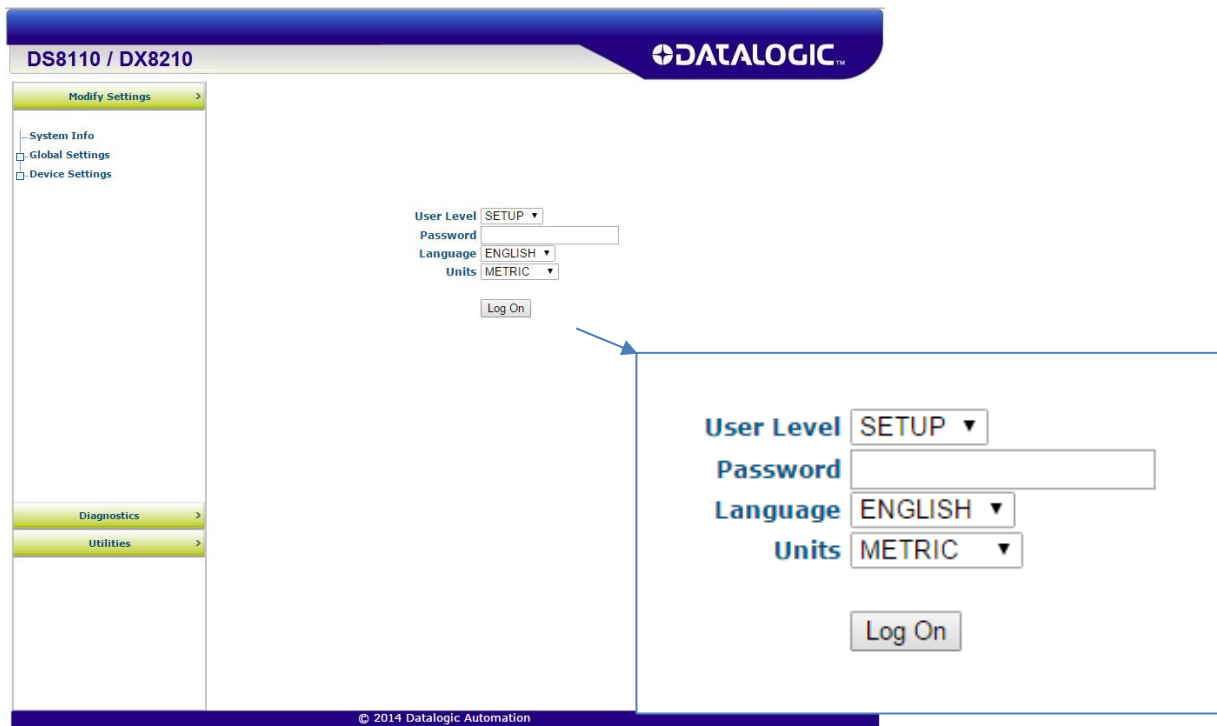
5. Enter the **Password** (default is DLA) for your system in the fields provided.

6. Select a language from those available in the **Language** drop-down list.

7. Select **METRIC** or **IMPERIAL** from the **Units** drop-down list.

8. Click **Log On**.

   If the password is valid, the application enables all functions available to the user and displays the **System Info** window.

   If the password is not valid, the application displays a results box with the message, **"Incorrect Password."** Click **OK** to return to the **Log On** window and enter the correct user name and password. I you don't know the password, contact your system manager.
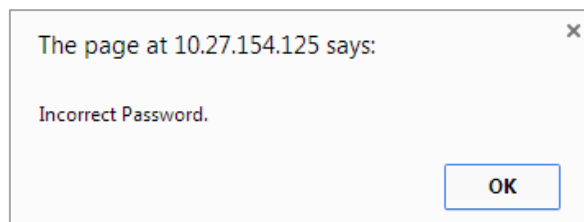
To log out of the e-Genius:

Click at the upper right corner of the **e-Genius** window to Log Out. When logged out, the Log On window will appear.

4.2 E-GENIUS BASICS

4.2.1 e-Genius Menu Tree

The functions that you can select are displayed in a menu tree on the left–hand side of **e-Genius**. The function list is organized much like the hierarchy of a file system, where you can expand items that are preceded by a box (🔲) to further sub–levels until you find a function of interest.

Sub–levels appear indented below the items from which they are expanded. Clicking the box again will collapse that branch of the menu. You can expand no further when an item is not preceded by a box.

The reader/controller **e-Genius** menu tree appears with no items expanded. Click the folders to display the active window for the setup function and/or expand the folders to view any additional setup features.

4.2.2 Entering Text Using the Text Entry Tool

In cases where text needs to be entered to create message headers, trailer, custom messages, or for other reasons, the **Text Entry Tool** pencil icon " ✏ " will be displayed.

Click ✏ to open the **Text Entry Tool.**
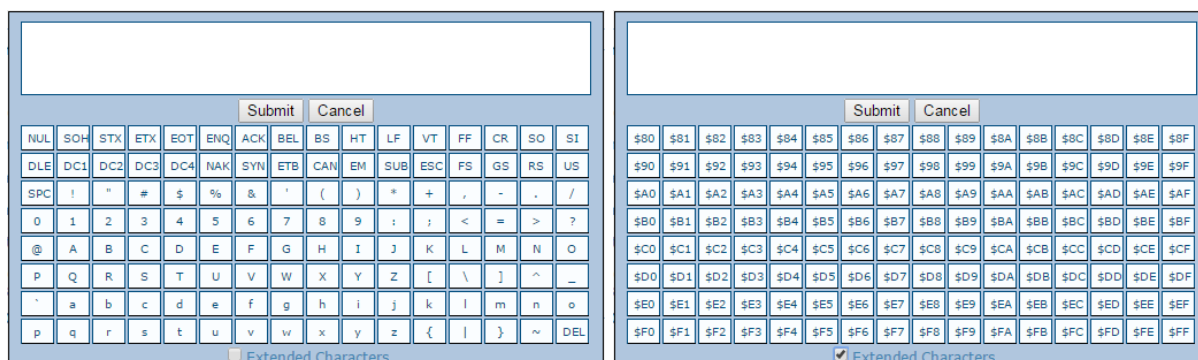
NOTE: The **Text Entry Tool** is needed to enter unprintable/untypable characters. For example, <CR> is a single character presented as a string for more easily reading.

The character must be entered with the tool, if typed normally it will be recognized as a string and not as a single character.

You can enter text in the text field by typing, or click on the character buttons to create your message. Select the **Extended Characters** check box to reveal a new set of control characters.

Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

4.2.3 Update and Reset Buttons

The **Update All**, **Reset All**, and **Reset Page** buttons provide the following functions:

- **Update All:** Click to save all pending parameter changes (across active windows)

- **Reset All:** Click to revert all pending parameter changes (across active windows) to their last saved values

- **Reset Page:** Click to revert pending parameter changes on the current page to their last saved values

4.2.4 Getting Help

e-Genius provides complete online help.

To access the complete help system:

Select **Utilities | Help** in the **e-Genius** menu tree. The help **Welcome** window appears. The **Welcome** page provides important product information as well as three ways to find specific help information: **Contents, Index,** and **Search.**
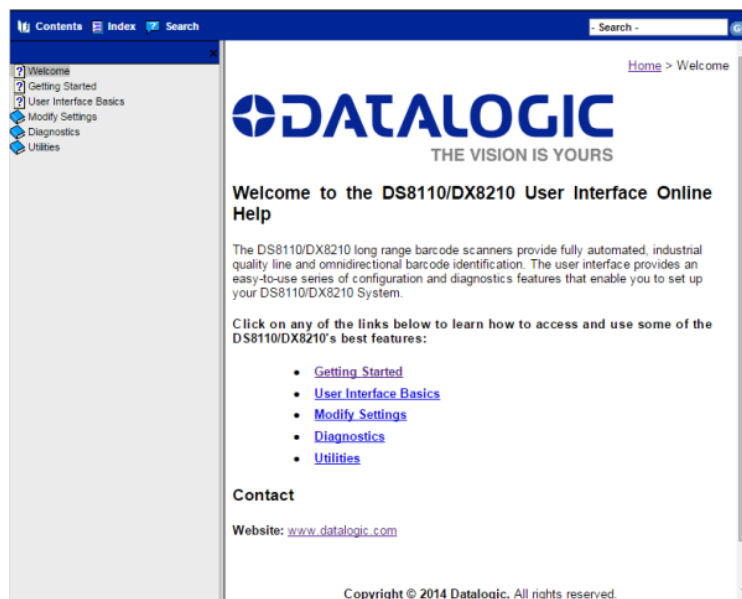
To display contextual help for a current window:

1. Click the **Help Icon** displayed at the top right of the screen. A help window appears, providing you with information for that specific page.
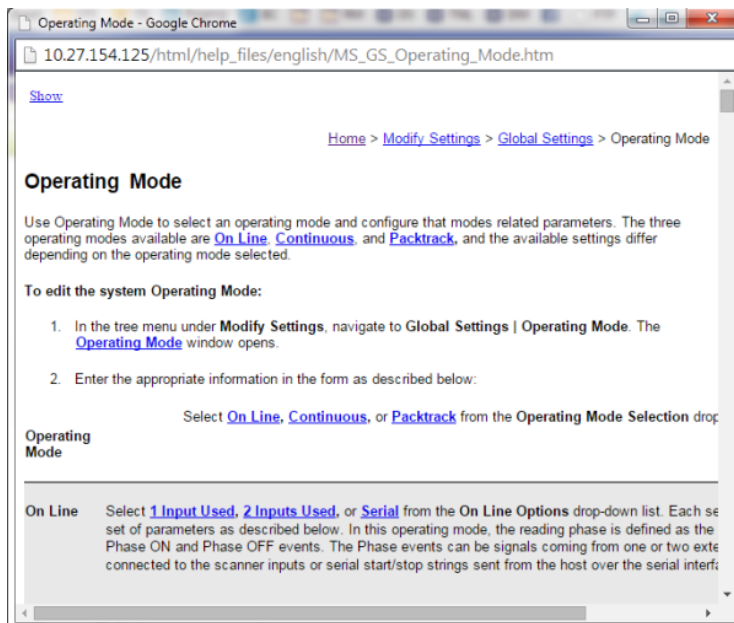
2. Click the **Show** link in the upper left corner of the help window to access Contents, Index, and Search options.

4.3 MODIFY SETTINGS

Use the Modify Settings Menu Tree selections during initial setup to configure your scanning system. If necessary, you can later make modifications to the configuration using the same menu selections.
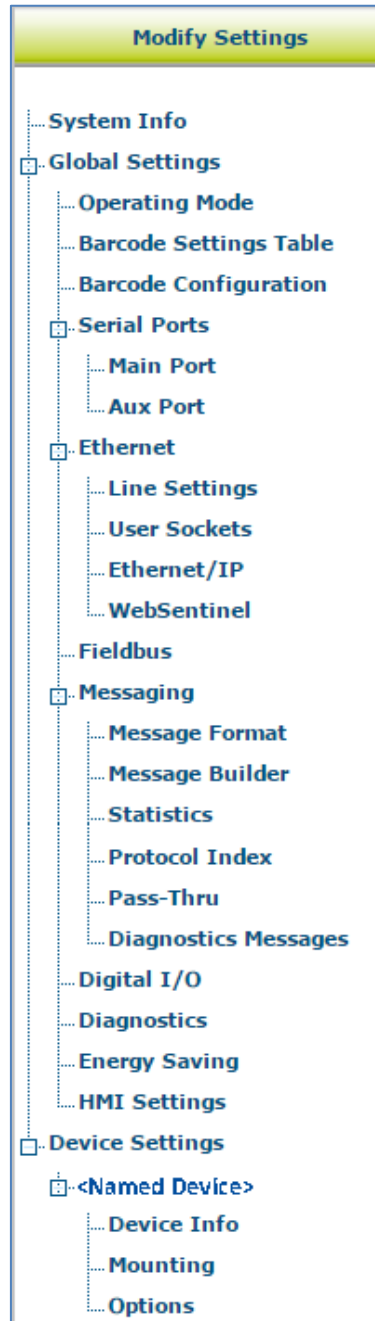
4.4 MODIFY SETTINGS | SYSTEM INFO

Use **System Info** to identify and name the scanning system (whether it includes one scanner or an array), indicate Master or Standalone systems, discover the scanners included in the system, and distribute software from the Master scanner to Slave scanners in the system.

To view and edit system information:

1. In the tree menu under **Modify Settings**, click System Info. The System Info window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
System Info	
System Description	Enter a name to identify this scanning system in the text field.
Role	Select **Standalone** or **Master** from the drop-down list. **Standalone** (not controllers) indicates a scan point with a single barcode scanner. **Master** indicates that the system is made up of more than one barcode scanner in a master and slave configuration. **NOTE**: The SC5000 Controller will always be shown as Master and cannot be changed.

Field Name	Action/Definition
Enable Automatic Slave Replace	There are two ways to replace a defective scanner : • If the check box **is not** selected: The replacement will be done only pressing the RESTORE *(see section 5.5.2)* key on the scanner or using the **Edit** drop-down. • If the check box **is** selected: The replacement will be completely automatic. This will work also as Hot-Automatic-Replacement without turning the system power off and on.
Force Operation as a Standalone/Master	Select the check box to allow a scanner to operate as a Master without a CBX attached.
Master Tools	These options are shown if Master is selected and is the default option for the SC5000
Discover Scanners	Click **Discover Scanners** to automatically find all of the scanners in an array. The discovered scanners will be listed in the **Device Information** portion of the window. This step is only done during initial configuration and is not a troubleshooting option.

Distribute Software	Click **Distribute Software** to send the current software residing on the master scanner to all of the slave scanners listed in the **Device Information** section of the window.

Device Information	
Status	**Green** = No errors and ready to read Gray = Unit not connected (unit not seen by master) **Red** = Error. If you click on the red circle it will take you to the status viewer page for more info on the error
Model	Displays an image of the scanner/controller model
Dev	Displays the system designation for the device
MAC Address	Displays the MAC Address (Media Access Control Address) for the device
Software version	Displays the device installed software version.
Description	Enter a user-defined description of the device.
ID	Click **ID** to visually identify a scanner in an array/tunnel. When clicked, all the scanner lasers will turn off except for the selected scanner, whose laser will blink for 20 seconds.

Field Name	Action/Definition
Edit	Select to **Remove, Reassign, Add,** or **Replace** from the **Edit** drop-down list to complete the following actions: • **Remove:** When selected, you can select the scanner to remove from the Dev/MAC Address drop-down list. Click **OK** to remove the selected scanner from the system. • **Reassign:** When selected, the Dev column of the selected slave scanner (selected with ID) presents a drop-down list of Dev numbers. Select a different number to reassign the scanner. • **Add:** This is an option under the **Edit** drop-down list in the **Unconfigured Devices** section of the screen. Click **OK** to add the selected device to the system. • **Replace:** This is an option under the **Edit** drop-down list in the **Unconfigured Devices** section of the screen. When selected, you can select from a list of slave scanners *(Those with a gray indicator, meaning the unit is not connected)* in the system using **MAC Address** and **Dev** drop-down lists. Click **OK** to replace the selected scanner with the **Unconfigured Device**.
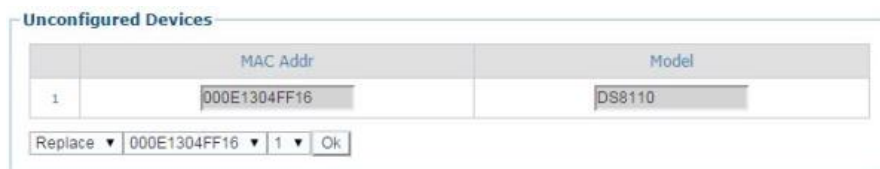
Additional Devices	
Send Barcodes to Non-Singulated Dimensioning System	Select the checkbox to enable **Non-Singulated Dimensioning System Info** options. (currently not available for Standalone or Multi-head DM3610 systems)
IP Address	Enter the device IP Address.
Port Number	Enter a port number for the device.
Enable Tach Sync	Select the checkbox to enable encoder/tachometer syncing between system devices.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.5 MODIFY SETTINGS | GLOBAL SETTINGS

Use the Global Settings menu tree selections during initial setup to configure your **DS8110/DX8210 Barcode Scanning System**. Global settings are applied to the system Master, and then distributed by the Master Scanner to the Slave devices. If necessary, you can later make modifications to the global system settings using the same menu selections.

4
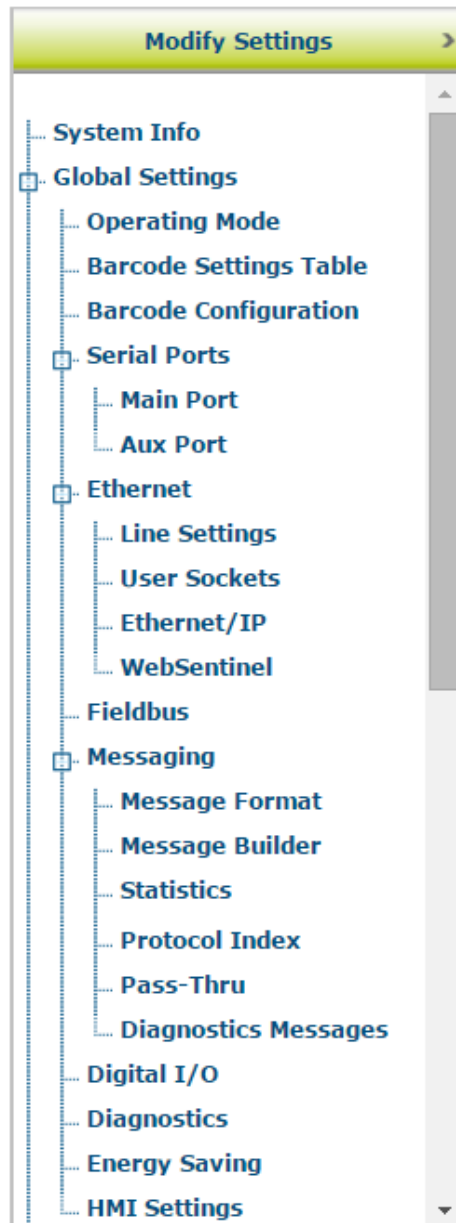
4.5.1 Modify Settings | Global Settings | Operating Mode

Use Operating Mode to select an operating mode and configure that modes related parameters. The three operating modes available are **On Line**, **Continuous**, and **PackTrack,** and the available settings differ depending on the operating mode selected.

To edit the system Operating Mode:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Operating Mode**. The Operating Mode window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Operating Mode	**Select On Line, Continuous, or PackTrack from the Operating Mode Selection drop-down list.**
On Line	Select **1 Input Used**, **2 Inputs Used**, or **Serial** from the **On Line Options** drop-down list. Each selection has a different set of parameters as described below. In this operating mode, the reading phase is defined as the time between the **Phase ON** and **Phase OFF** events. The Phase events can be signals coming from one or two external presence sensors connected to the scanner inputs or serial start/stop strings sent from the host over the serial interface or Ethernet input.
	1 Input Used The reading phase takes place during the active phase of the presence sensor, when the scanner tries to acquire and correctly decode the code. If the operation is successful, the barcode characters are transmitted on the serial interface or Ethernet input in the format defined by the current configuration and the right output event is raised at the end of the photoelectric sensor's active phase. If a code cannot be decoded, a no read message is sent and the no read event is raised at the end of the photoelectric sensor's active phase.
	Trigger Source
	Start Input from Bus This parameter is available only for Fieldbus Hosts and if checked, allows the Fieldbus Master to drive the Reading Phase. For Profinet or Profibus interfaces, it allows the Fieldbus Master to drive the reading phase via bit 7 in Byte 0 (LSB) of the Output Area. For Ethernet/IP, it allows the Ethernet/IP Client to drive the reading phase via bit 7 in Byte OutputBits of the DL_OutputStruct.
	Start Input Active Level Select **Active Open** or **Active Closed** from the drop-down list. • **Active Open:** The input is active when there is no current flowing through IN pins. The input from the trigger source is normally closed. The scanner goes into trigger mode when the input source is opened.

Field Name	Action/Definition
	• **Active Closed:** The input is active when current flows through IN pins. The input from the trigger source is normally opened. The scanner goes into trigger mode when the input source is closed.
Reading Phase Timeout	Select the check box to define a timeout for the **On Line Serial** mode and the **On Line 1** Input mode.
Timeout (ms)	Enter a timeout in milliseconds (from 40 to 15000 ms) in the field provided. The **Timeout** represents the period of time for the reading phase.
Timeout Counting From	Select **Start** or **Stop** from the drop-down list. • When **Start** is selected, the **Timeout** used to determine the reading phase will begin from the **Start Input** or **Serial Start String** (normal operation) • When **Stop** is selected, the **Timeout** used to determine the reading phase will begin from the **Stop Input** or **Serial Stop String** (effectively extending the reading phase).
	Verifier Settings
Verifier Enable	Select the check box to enable the **Code Verifier** operating mode.
Verifier Code	Click ✎ to activate the Text Entry Tool and create the string text used as the match code to the decoded codes. Use characters from **NUL** (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Store Input	Select an option from the drop-down list to define the number of the input used to automatically store the verifier code. This input must be activated before the reading phase starts, the verifier code must be read and then after the end of the reading phase the input must be deactivated.
Active Level	Select **Active Open** or **Active Closed** from the drop-down list to choose the active state of the input. • **Active Open:** The input is active when there is no current flowing through IN pins. The input from the verify mode source is normally closed. The scanner goes into trigger mode when the input

Field Name	Action/Definition
	source is opened.
	• **Active Closed:** The input is active when current flows through IN pins. The input from the verify mode source is normally opened. The scanner goes into trigger mode when the input source is closed.
Wrong Code Tx	Select the check box to enable the transmission of the Wrong Code (Non-Valid Code).
Wrong String Tx	Select the check box to enable the transmission of the Wrong String (Non-Valid String) message.
Wrong String (max. 128 chars)	Enter a text string to be sent in case of a mismatch (wrong code read/non-valid code).
	Beam Shutter Settings
Beam Shutter	Select **Disabled**, **Triggered**, or **Enabled** from the drop-down list. The Beam Shutter turns the laser off. The Beam Shutter option can be used to increase the overall laser diode life when used in high ambient temperature applications (over 35° C); reduce power consumption; and to turn off the laser for safety purposes. • **Disabled:** The laser is always on. • **Triggered:** The laser is turned off as soon as the code(s) are read or when the reading phase ends. The laser is turned on again when the next reading phase starts. • **Enabled:** The laser is always off and all operations are suspended.
2 Inputs Used	The reading phase is defined by 2 inputs. It starts when the **Start Input** is activated and stops when the **Stop Input** is deactivated (unless the **Extended Phase** is enabled).
	Trigger Source
Extended Phase	Available only for the **On Line/2 Inputs** option. If checked, it allows the **Stop Input** to end the reading phase only if the **Start Input** is also deactivated.
Start Input Number	Select an input from the drop-down list to define the number of the input starting the reading phase.

Field Name	Action/Definition

		Start Input Active Level	Select **Active Open** or **Active Closed** from the drop-down list.

<table>
<tr><td></td><td></td><td>Start Input Active Level</td><td>Select Active Open or Active Closed from the drop-down list.

Active Open: The input is active when there is no current flowing through IN pins. The input from the trigger source is normally closed. The scanner goes into trigger mode when the input source is opened.
Active Closed: The input is active when current flows through IN pins. The input from the trigger source is normally opened. The scanner goes into trigger mode when the input source is closed.</td></tr>
<tr><td></td><td></td><td>Stop Input Number</td><td>Select an input from the drop-down list to define the input ending the reading phase.</td></tr>
<tr><td></td><td></td><td>Stop Input Active Level</td><td>Select Active Open or Active Closed from the drop-down list to define the active state of the input.

Active Open: The input is active when there is no current flowing through IN pins. The input from the trigger source is normally closed. The scanner goes into trigger mode when the input source is opened.
Active Closed: The input is active when current flows through IN pins. The input from the trigger source is normally opened. The scanner goes into trigger mode when the input source is closed.</td></tr>
<tr><td></td><td></td><td>Reading Phase Timeout</td><td>If checked, it allows defining a timeout for the Serial On Line mode and the On Line 1 Input mode.</td></tr>
<tr><td></td><td></td><td>Stop Phase Edge</td><td>Select Trailing or Leading from the drop-down list to define the signal edge of the stop input used by the scanner as reference for ending the reading phase:

Trailing: The reading phase ends when the package has completely passed by the stop input.
Leading: The reading phase ends as soon as the stop input detects the front edge of the package.</td></tr>
</table>

Field Name	Action/Definition	
		Beam Shutter Settings
	Beam Shutter	Select **Disabled**, **Triggered**, or **Enabled** from the drop-down list. The Beam Shutter turns the laser off. The Beam Shutter option can be used to increase the overall laser diode life when used in high ambient temperature applications (over 35° C); reduce power consumption; and to turn off the laser for safety purposes. • **Disabled:** The laser is always on. • **Triggered:** The laser is turned off as soon as the code(s) are read or when the reading phase ends. The laser is turned on again when the next reading phase starts. • **Enabled:** The laser is always off and all operations are suspended.
	Serial	In **Serial/On-Line** mode the reading phase starts when the **Serial Start String** is received on the serial interface and ends when the **Serial Stop String** is received or when a programmed **Reading Phase Timeout** expires. If decoding is correct, the data is transmitted on the serial port as defined by the configuration. The output line selected for the right output event is activated and the relative message is transmitted on the serial interface or Ethernet input. In case of a bad read, a no read message is transmitted on the serial interface. The output line selected for the no read event is activated and the relative message is transmitted on the serial interface or Ethernet input.
		Trigger Source
	Serial Start String (max. 32 chars)	Click ✎ to activate the **Text Entry Tool** and create the string text used to signal the beginning of the reading phase. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text. The **Serial Start** string must be different from the **Serial Stop** string and **Motor ON/OFF** strings. When **ACK/NAK Protocol** or **Energy Saving** is enabled, the **Serial Start/Stop Strings** cannot contain ACK/NAK characters.

Field Name	Action/Definition
Serial Stop String (max. 32 chars)	Click 🖉 to activate the **Text Entry Tool** and create the string text used to signal the end of the reading phase. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text. The **Serial Stop** string must be different from the **Serial Start** string and **Motor ON/OFF** strings. When **ACK/NAK Protocol** or **Energy Saving** is enabled, the **Serial Start/Stop Strings** cannot contain ACK/NAK characters.
Reading Phase Timeout	Select the check box to define a timeout for the **Serial On Line mode**.
Timeout (ms)	Enter a timeout in milliseconds (from 40 to 15000 ms) in the field provided. The **Timeout** represents the period of time for the reading phase.
Timeout Counting From	Select **Start** or **Stop** from the drop-down list. • When **Start** is selected, the **Timeout** used to determine the reading phase will begin from the **Start Input** or **Serial Start String** (normal operation) • When **Stop** is selected, the **Timeout** used to determine the reading phase will begin from the **Stop Input** or **Serial Stop String** (effectively extending the reading phase).
	Beam Shutter Settings
Beam Shutter	Select **Disabled**, **Triggered**, or **Enabled** from the drop-down list. The Beam Shutter turns the laser off. The Beam Shutter option can be used to increase the overall laser diode life when used in high ambient temperature applications (over 35° C); reduce power consumption; and to turn off the laser for safety purposes. • **Disabled:** The laser is always on. • **Triggered:** The laser is turned off as soon as the code(s) are read or when the reading phase ends. The laser is turned on again when the next reading phase starts. • **Enabled:** The laser is always off and all operations are suspended.

Field Name	Action/Definition
Continuous	The reading phase is always active and allows reading two or more codes when placed along the same scan line. Code transmission is identical to the other operating modes except that there is no transmission on the serial port in case of a No Read condition.

<table>
<tr><td></td><td colspan="2" align="center">Mode Setting</td></tr>
<tr><td></td><td>Code Filter</td><td>Select Disable, Timeout, Encoder Steps, or Tx Line from the On Line Options drop-down list. This parameter determines criteria for flushing entries from the code filtering list depending on the type of list management:</td></tr>
</table>

- The **Code Filter Depth** parameter, when not = 0, manages a FIFO (First In First Out) list of codes which are compared for filtering. The **Timeout** and **Encoder Steps** values are in addition to the cyclical flushing of entries when the FIFO list depth is exceeded.

- When **Code Filter** is set to **Tx Line** an internal list is managed where each entry is flushed when the **Tx Line** distance is exceeded.

  The application program inherently compares codes based on content and code length.

Each Code Filter criteria has its own relative value parameter.

- **Disable:** No additional criteria are applied. If code filtering is enabled through the Code Filter Depth parameter, the FIFO list is only modified by new code entries (FIFO list depth exceeded).

- **Timeout:** A timeout measured in milliseconds is also applied to each code entry. The current code entry will be flushed from the list when the timeout expires.

- **Encoder Steps:** a threshold measured in encoder steps is also applied to each code entry. The current code entry will be flushed from the list when the number of encoder steps is exceeded.

- **Tx Line:** The distance measured in mm to the transmit line is applied to each code entry. The current code entry will be flushed from the list when the distance in mm is exceeded. When Tx Line is selected, all the networked scanners must have been calibrated using PackTrack *(See section 5.7 PackTrack).*

NOTE: When Code Filter = Tx Line:

The Code Filter Depth parameter is no longer available because the application program manages an internal list which depends solely on the number of codes decoded before the Tx Line is reached.

Any code which is determined to be identical to

Field Name	Action/Definition

a code in the list by comparing the filter conditions will be discarded, and to increase precision the code in the list will have its x, y, z position coordinates adjusted as the average between the two readings.

$$x=x1+x2/2 \ , \ \ y=y1+y2/2 \ , \ \ z=z1+z2/2$$

Code Filter Depth	In **Continuous mode**, **Code Filter Depth** is used to avoid multiple reads of the same code. The entered value (other than zero) defines the number of codes to memorize in a FIFO (First In First Out) list.

When a code is read, it is compared to the list. The application program inherently compares codes based on content and code length. If the list contains a code identical to the current code being read, the current code is discarded. If not, the current code is accepted and added to the list in the first position; the remaining codes in the list are shifted. If the list is full the oldest code in the list will be flushed.

When = 0, there is no FIFO list and there is no filtering.

Selection: a value from 0 to 127

Example:

Code Filter Depth = 3

List	Code Read	Accepted
xxx (no codes in list)	A	Yes
Axx	B	Yes
BAx	B	No
BAx	C	Yes
CBA	D	Yes
DCB	A	Yes
ADC	A	No

Filter Number of Encoder Steps	Enter a number of encoder steps from 1 to 15000. This parameter sets the number of Encoder Steps after which the **FIFO (First In First Out)** list entry is flushed.
Replicate same code when symbologies don't match	Select the check box to enable a further code filter condition according to which a read code is added to the list or discarded. This parameter is available if the **Code Filter Depth** value is other than zero or if the Code Filter value is Tx Line.

In addition to the inherent content and code length comparison, this parameter compares the code type (symbology). If the current code being read is identical to any code contained in the list by: content, length and type, the current code is discarded. If not, the current code is accepted and added to the list in the first position; the remaining codes in the list are shifted. If the list is full the oldest code in the list will be flushed.

Field Name	Action/Definition
Replicate same code when X positions don't match	Select the check box to enable a further code filter condition according to which a read code is added to the list or discarded. This parameter is available if the **Code Filter Depth** value is other than zero or if the Code Filter value is Tx Line. In addition to the inherent content and code length comparison, this parameter compares the X coordinate code position. If the current code being read is identical to any code contained in the list by: content, length and X coordinate code position, the current code is discarded. If not, the current code is accepted and added to the list in the first position; the remaining codes in the list are shifted. If the list is full the oldest code in the list will be flushed.
Replicate same code when Y positions don't match	Select the check box to enable a further code filter condition according to which a read code is added to the list or discarded. This parameter is available if the Code Filter **Depth** value is other than zero or if the Code Filter value is Tx Line. In addition to the inherent content and code length comparison, this parameter compares the Y coordinate code position. If the current code being read is identical to any code contained in the list by: content, length and Y coordinate code position, the current code is discarded. If not, the current code is accepted and added to the list in the first position; the remaining codes in the list are shifted. If the list is full the oldest code in the list will be flushed.
Replicate same code when Z positions don't match	Select the check box to enable a further code filter condition according to which a read code is added to the list or discarded. This parameter is available if the **Code Filter Depth** value is other than zero or if the Code Filter value is Tx Line In addition to the inherent content and code length comparison, this parameter compares the Z coordinate code position. If the current code being read is identical to any code contained in the list by: content, length and Z coordinate code position, the current code is discarded. If not, the current code is accepted and added to the list in the first position; the remaining codes in the list are shifted. If the list is full the oldest code in the list will be flushed.
Continuous Threshold (number of scans)	Enter an *N* number of scans without a code allowed in order to assure code identification in the reading zone. Enter a value from 10 to 32665.
Encoder Settings	
Encoder Source	Select **Constant Speed (Internal)** or **Physical Encoder (Tachometer)** from the drop-down list: • **Constant Speed (Internal):** Allows the user to specify the tach rate to be used (from .05 - 3.05 m/sec [from 10 - 600 ft/min]). No external hardware is used. • **Physical Encoder (Tachometer):** A physical encoder is connected to the Encoder input and is enabled

Field Name	Action/Definition	
	Encoder Step (hundredths of millimeter)	Enter the step value of the encoder. See *section 1.8.1* for a table of **Encoder Step** values.
	Conveyor Speed (mm/sec)	This parameter is available only when the Physical Encoder is disabled. It defines the constant speed of the conveyor in mm/sec.
PackTrack		**Refer to *section 5.7* for physical PackTrack installation procedures.** **Trigger Source**
	Start Input from Bus	This parameter is available only for Fieldbus Hosts and if checked, allows the Fieldbus Master to drive the Reading Phase. For Profinet or Profibus interfaces, it allows the Fieldbus Master to drive the reading phase via bit 7 in Byte 0 (LSB) of the Output Area. For Ethernet/IP, it allows the Ethernet/IP Client to drive the reading phase via bit 7 in Byte OutputBits of the DL_OutputStruct.
	Start Input Number	Select an input from the drop-down list to define the number of the input starting the reading phase.
	Start Input Active Level	Select **Active Open** or **Active Closed** from the drop-down list to define the active state of the input. • **Active Open:** The input is active when there is no current flowing through IN pins. The input from the trigger source is normally closed. The scanner goes into trigger mode when the input source is opened. • **Active Closed:** The input is active when current flows through IN pins. The input from the trigger source is normally opened. The scanner goes into trigger mode when the input source is closed.
	Transmission Edge	Select **Trailing** or **Leading** from the drop-down list to define the signal edge of the stop input used by the scanner as reference for ending the reading phase: • **Trailing:** The reading phase ends when the pack has completely passed by the stop input. • **Leading:** The reading phase ends as soon as the stop input detects the front edge of the pack.

Field Name	Action/Definition
	Mode Setting

<table>
<tr><td>Distance from PS Line to Tx Line</td><td>Enter the distance along the Y axis from the PS (photoelectric sensor) to the TX Line (transmit).</td></tr>
</table>
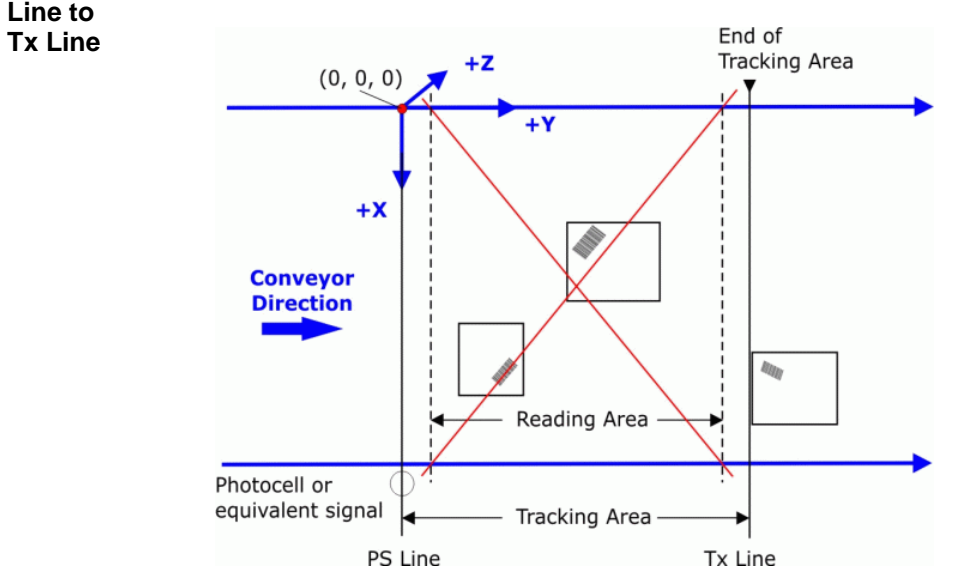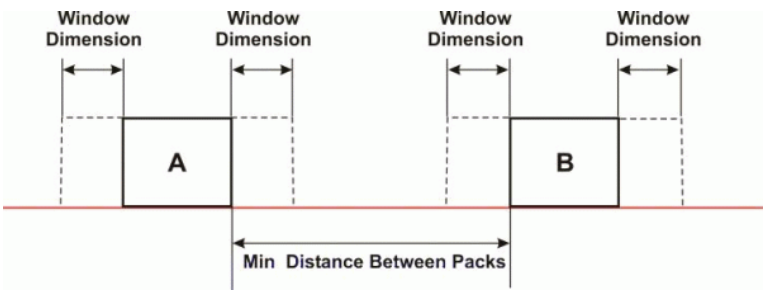
NOTE: Tracking starts 10 cm [4 inches] before and stops 10 cm [4 inches] after the Reading Area in order to ensure the barcode is assigned to the correct package.

PS Line	This parameter defines the read signal Y coordinate (mm) referred to the origin of co-ordinates used for PackTrack configuration *(see below)*.

Example:

Normally the PS Line coincides with the PackTrack reference where X, Y, Z = 0.

If the presence sensor (photocell or Host PS signal) is moved, you must set the PS Line accordingly and recalculate the Tx Line.

1. PS Line = 0; Distance from PS Line to Tx Line = 2500

2. PS Line = 500; Distance from PS Line to Tx Line = 2000

Field Name	Action/Definition
Minimum Pack Length	Enter the minimum length of a pack in the space provided (mm [in]).
Minimum Distance Error Behavior	Select **Ignore Error, Compose,** or **Discard Last** from the drop-down list. • **Ignore Error:** the error is ignored • **Compose:** Enter the **Minimum Distance Between Packages** in the field provided. • **Discard Last:** discards all received packages
Minimum Distance Between Packages	Enter the minimum distance (mm, in) between consecutive packages. This field is only available when **Compose** or **Discard Last** is selected for the **Minimum Distance Error Behavior.**
Window Dimension	Enter a **Window Dimension** in the field provided. The measurement of a barcode position in absolute coordinates performed by the scanners may be affected by an error. PackTrack evaluation can fail in assigning the barcode for this reason. With the **Window Dimension** parameter, the Y coordinates that delimit the pack can be virtually extended to improve the assigning success rate *(see the following figure).* If the minimum distance between two consecutive packs is less than twice the value of the **Window Dimension**, the window is dynamically resized (dynamic window) to half the distance between the two packs. The code will be assigned within the **Window Dimension** of the closest pack. If the minimum distance between two consecutive packs is more than twice the value of the **Window Dimension**, the code will be assigned within the **Window Dimension** itself.
	Encoder Settings
Physical Encoder	Select **Disable** or **Enable** from the drop-down list: • **Disable:** No encoder is enabled • **Enable:** A physical encoder is connected to the Encoder input and is enabled

Field Name	Action/Definition
Encoder Step (hundredths of millimeter)	Enter the step value of the encoder. See *section 1.8.1* for a table of **Encoder Step** values.
Conveyor Speed (mm/sec)	This parameter is available only when the **Physical Encoder** is **Disabled**. It defines the constant speed of the conveyor in mm/sec.

| **Beam Shutter Settings** ||

Field Name	Action/Definition
Beam Shutter	Select **Disabled**, **Triggered**, or **Enabled** from the drop-down list. The Beam Shutter turns the laser off. The Beam Shutter option can be used to increase the overall laser diode life when used in high ambient temperature applications (over 35° C); reduce power consumption; and to turn off the laser for safety purposes. • **Disabled:** The laser is always on. • **Triggered:** The laser is turned off as soon as the code(s) are read or when the reading phase ends. The laser is turned on again when the next reading phase starts. • **Enabled:** The laser is always off and all operations are suspended.
PackTrack Beam Shutter Timeout	Select a time value from the drop-down list. This parameter is available only when **Operating Mode = PackTrack** and **Beam Shutter = Triggered.** By setting this parameter the laser is turned off as soon as the selected timeout expires.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4

4.5.2 Modify Settings | Global Settings | Barcode Settings Table

Use **Barcode Settings Table** to select and configure barcodes to be read in your application. Each barcode type

To edit the **Barcode Settings**:

1. In the tree menu under Modify Settings, navigate to **Global Settings | Barcode Settings Table. The Barcode Settings** window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Top Panel	Displays a list of barcodes that have been added to the system with the following columns:
Idx	Select an option button for the row/barcode you wish to edit. • If a barcode type is displayed in the selected row, its configuration can then be edited. • If a row displaying disabled is selected, a barcode type can be selected and configured for that row.
Symbology	Displays the name of the barcode symbology for that row. If no symbology has been added for a row, **disabled** is displayed.
Minimum Length	Displays the minimum barcode character length for that row's symbology.

Field Name	Action/Definition
Maximum Length	Displays the maximum barcode character length for that row's symbology.
Barcode *n*	NOTE: Input fields will vary depending on the selected symbology.
Enable	Select the **Enable** check box to activate the selected barcode. Deselect the **Enable** check box to disable the selected barcode. When the check box has been selected, configuration and code type options are displayed.
Code Symbology	Select a barcode symbology from those available in the **Code Symbology** drop-down list.
EAN Add On	Select **No Add On, 2 digits Add On,** or **5 digit Add On** from the **EAN Add On** drop-down list. Selecting **2 digit Add On** or **5 digit Add On** adds that many digits as a supplement to the barcode. **EAN** is the acronym for **International Article Number**, previously known as **European Article Number**.
Minimum Label Length	Enter the minimum character length for the selected barcode.
Maximum Label Length	Enter the maximum character length for the selected barcode.
Match String Rule	Select **Match** or **Do Not Match** from the drop-down list. This parameter defines the matching rule, according to which a code can be transmitted. • **Match**: All codes matching the Pattern Match String will be transmitted • **Do Not Match:** All codes not matching the Pattern Match String will be transmitted
Pattern Match String (max. 200 chars)	Click ✎ to activate the Text Entry Tool and create a pattern match string. A code can also be identified by its content. A pattern matching string is programmable for each code and if the read codes do not match the defined string, a No Read Event will be returned. It is possible to define the matching string by inserting: • all printable characters • non printable ASCII characters available in the list which appears by right-clicking on the parameter edit box • * = defining any string consisting of an undefined number of characters (it may be empty) • ? = identifying any character to be found in the position indicated within the string If your application requires inserting ?, * and NUL as characters, it is necessary to use the following syntax: • ? character = <NUL>? • * character = <NUL>* • NUL character = <NUL>00 • other extended ASCII characters = <NUL>xy, where xy identifies the character hex value

Field Name	Action/Definition

Examples:

Match a code starting with 123 string and followed by any string of characters:

- Match String = 123*
- Example Code = 123aC53

Match a code ending with 123 string preceded by any string of characters:

- Match String = *123
- Example Code = 41pO123

Match a code having 123 string in any position:

- Match String = *123*
- Example Code = 41pO123253

Match a code starting with 123 string followed by three generic characters and an undefined string of characters, in this case no character:

- Match String = 123???*
- Example Code = 123ad2

Match any code of four characters:

- Match String = ????
- Example Code = gT6k

Match a code with 6 characters in any position having 12 as central characters:

- Match String = *??12??*
- Example Code = datal12og35

The following is an example of a very complex string where ? and* are used both as commands and as characters:

- Match String = *45<NUL>??*??AC<NUL>*251?*
- Example Code = GEN45?3iusdsAC*2516300

NOTE: For **Codabar** codes the start/stop characters must be considered in the match conditions.
For all codes which use check digits, if the **Check Digit** is transmitted, it must be considered in the match conditions.

Options	**NOTE:** Input fields will vary depending on the selected symbology.
Decoding Safety	Enter a number from **1** to **100** (**1** = control disabled) in the field provided. It verifies that an *N* number of decodes are performed with the same result before code reading is accepted as valid.

Field Name	Action/Definition
Check Digit	Select the check box to improve decoding safety: it is generally the last digit aligned to the right of the code and verifies the validity of the preceding digits. The calculation technique and number of check digits depend on the code selected. It is advised to enable the check digit whenever correct code identification is difficult. The following barcode symbologies include check digits in their definitions: • Code 128 • EAN/UPC • Code 93 For these symbologies the check digit control is not allowed.
Check Digit Type	Select a customized check digit for **Standard, German, DHL, Daimler-Chrysler,** or **Bosch** from the drop-down list.
Check Digit Tx	Select the check box to include the Check Digit in the code transmitted.
Bar Count	Select **Variable** or an available value from the drop-down list. The Bar Count allows to further specify the number of elements in the read code for Code 128, GS1-128, Code 93, ISBT 128 or Code 39 Full ASCII. For these codes, the same number of barcode elements (bars + spaces) can be associated with a different number of characters. • **Variable:** to select the correct number of characters, set Label Length to the desired fixed value and Bar Count to Variable

12
Code 128
Subset A

12
Code 128
Subset C

Digit Number 2, Bar Count variable

• **Code 128 or GS1-128:** from 25 to 499 - a variable number of characters in steps of 6.
• **Code 93 or ISBT 128:** from 25 to 385 - a variable number of characters in steps of 6.
• **Code 39 Full ASCII:** from 29 to 619 - a variable number of characters in steps of 10.

To select a particular barcode length in elements, set Bar Count to the desired fixed value and Label Length to Variable.

12
Code 128
Subset A

1234
Code 128
Subset C

Digit Number variable, Bar Count 31

Field Name	Action/Definition
Match Direction Rule	Select **Disable, Forward,** or **Reverse** from the drop-down list. This parameter defines the direction, according to which a code can be transmitted. The direction refers to the code direction with respect to the scan line, in particular: **Forward** = the code start character precedes the stop character in the scan line (Start Ch + Code + Stop Ch); Reverse = the code stop character precedes the start character in the scan line (Stop Ch + Code + Start Ch) • **Disable:** All codes are transmitted no matter what the direction is • **Forward:** All codes having a forward direction are transmitted • **Reverse:** All codes having a reverse direction are transmitted
Start Char Tx	Select **Disabled, Lower Case,** or **Upper Case** from the drop-down list. This parameter is available only for **Codabar** code symbologies. It allows transmitting the code start character: • **Disabled:** The character is not selected; • **Lower Case:** The character is transmitted in lower case; • **Upper Case:** The character is transmitted in upper case.
Stop Char Tx	Select **Disabled, Lower Case,** or **Upper Case** from the drop-down list. This parameter is available only for **Codabar** code symbologies. It allows transmitting the code stop character: • **Disabled:** The character is not selected; • **Lower Case:** The character is transmitted in lower case; • **Upper Case:** The character is transmitted in upper case.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.5.3 Modify Settings | Global Settings | Barcode Configuration

Use **Barcode Configuration** to configure how the system defines a no read barcode, and configure and filter NOREAD messages.

To edit the Barcode Configuration:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Barcode Configuration**. The **Barcode Configuration** window opens.

```
┌─Barcode Configuration───────────────────────────────┐
│                                                     │
│  Code Combination              Single Label      ▼  │
│                                                     │
│  No Read Message               Global No Read Mess ▼│
│                                                     │
│  No Read String (max. 128 chars)   NOREAD        ✎ │
│                                                     │
│  Multi Filters                                   ▣  │
│                                                     │
│          Update All   Reset All   Reset Page        │
└─────────────────────────────────────────────────────┘
```

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Code Combination	Select **Single Label, Standard Multi Label, Logical Combination,** or **Code Collection** from the drop-down list. The Code Combination parameter selects the decoding mode for the scanner.

- **Single Label:** In this mode only one barcode can be read in each reading phase; however it can be determined automatically from up to 10 enabled codes. The scanner stops decoding as soon as a code is read.

  If the code is not read during the reading phase, the No Read message is produced.

- **Standard Multi Label:** In Multi Label mode the barcodes selected (up to 10), will all be read in the same reading phase. If the reading phase terminates before all the codes are read, a Global No Read message will be produced, unless it is disabled, in which case a Local No Read will be produced.

  > **NOTE:** In case of Multi Label, the codes will be distinguishe EITHER by their symbology, OR by their contents. If two (o more) codes share the same symbology and content, th scanner will perceive them as a unique code.

- **Logical Combination:** In Logical Combination mode the codes of the groups defined by the Logical Combination Rule are read in the same reading phase.

- **Code Collection:** In Code Collection mode expected codes are collected within a single reading phase in the order in which they are read. The No Read message is produced only if none of the codes are read. Up to 50 codes can be collected.

Barcode Configuration > Single Label

When **Single Label** has been selected from the **Code Combination** drop-down list, the Barcode Configuration window reveals related input fields.

Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Code Combination	**Single Label** has been selected.
No Read Message	Select **Disable No Read Message, Global No Read Message,** or **Local No Read(s) Message** from the drop-down list. The No Read condition occurs whenever a code cannot be read or decoded. • **Disable No Read Message:** The No Read Message is not transmitted. • **Global No Read Message:** The No Read String will be sent if the scanner is unable to decode one or more barcodes in the reading phase. • **Local No Read(s) Message:** Do not use this option when working in Single Label mode.
Use 'Global No Read String' when No Codes Read	Select the check box to allow the **Global No Read String** to be used if no codes at all are read. This option is **not** available when **Global No Read Message** is selected from the **No Read Message** drop-down list.
Global No Read String (max. 128 chars)	Click ✎ to activate the Text Entry Tool and create a string to be displayed when **Global No Read Message** is selected from the **No Read Message** drop-down list.
Multi Filters	Select the check box to display the **Multi-Filter Settings** options.

Field Name	Action/Definition
	Multi-Filter Settings
Contained Filter	Select the check box to reveal the **Max Number of Different Characters** field. When checked, this filter attempts to eliminate false multiple reads by determining if a short code read is "contained in" (is a sub-string of), another longer code read. This condition implicates that the short code is probably a misread of the same longer code and therefore should be ignored, (should not be considered as a multiple read of a different code). This filter is based upon the following rules: • a multiple read condition occurs • all decoded codes of the same type are compared with each other **Rule 1:** the shorter code is considered contained in the longer code if the character string is found in the same order; the longer code may have a single block of characters in any position (before, after or in between the compared strings) **Example:** The code **123456** is considered contained in the following codes: 00**123456**, **123456**00, **123**78**456**. The code **123456** is not considered contained in the following codes: 1234**65**07 (string out of order), 12345**700** (string not complete), 12**0**378456 or **00**123456**00** (multiple blocks in the string). **Rule 2:** the shorter code is not filtered by rule 1. In the longer code, all possible sub-strings of the same length as the shorter code string are compared with the shorter code string. The shorter code is considered contained in the longer code if the number of different characters between the compared codes is less than or equal to the Max Number of Different Characters. The shorter code will be filtered by rule 2. **Example:** If Max Number of Different Characters = 1: The code 123456 is considered contained in the following codes: 1230**5**600, 00123**0**56, 8812305688 because there is only one different character in the compared string. The code 123456 is not considered contained in 123066789 because there are two different characters in the compared string. **CAUTION:** If the **Contained Filter** parameter is used when **Message Tx Selection** *(see section 4.5.7)* is set to **On Decoding**, the filter conditions may be satisfied before the reading phase ends resulting in possible successive multiple read errors.

Field Name	Action/Definition

Max Number of Different Characters

Enter a value from 0 to 5 in the field provided to define the maximum number of different characters allowed to still consider a code as being included in another one and therefore to be filtered.

If the number of different characters between the compared codes exceeds the value of this parameter, the codes are considered as different and will not be filtered (a multiple read of a different code occurs).

If the number of different characters between the compared codes is less than or equal to the value of this parameter, the short code is considered as a sub-string of the longer code and will be filtered (no multiple read occurs).

Examples:

If Max Number of Different Characters = 2:
The code **123456** read once, is considered the same as the following codes read multiple times: 1**33**056, 123**54**6, 12345**7** because there are two or less different characters by position in the compared codes.

The code **123456** read once, is not considered the same as the following codes read multiple times: 1**53**2**4**6, 1**03**05**7**, **654321** because there are at least three different characters by position in the compared codes.

Voting Filter

Select the check box to reveal the **Max Number of Different Characters** field.

When checked, this filter attempts to eliminate false multiple reads by comparing the number of different characters by position between two codes of the same type and length. This condition implicates that reading a code of the same type and length having very few different characters is probably a misread of the code itself and therefore the code read the least number of times should be ignored, (should not be considered as a multiple read of a different code).

This filter is based upon the following rules:

- a multiple read condition occurs;
- the two codes are of the same type;
- the two codes have the same length;
- the number of different characters by position is equal to or less than the number defined by the Max Number of Different Characters parameter;
- **Message Tx Selection** *(see section 4.5.7)* must be set to **After Reading Phase Off.**

Filter Out Low Height Codes

Select the check box to reveal the **Minimum Readings Difference Between Scanners** field.

Background: This option was developed for the airports systems where there are often tall bar height codes and low bar height codes with the same content attached to baggage. Travelers will often remove the large, tall bar height code, while leaving the smaller, low bar height codes attached to the bag. The next time they travel they may have multiple low bar height codes on their baggage plus the new tall bar height and low bar height codes for the new trip.

This option instructs the system to ignore low bar height codes, which are likely read only once or twice, in favor of tall bar height codes, which will likely be read multiple times.

Field Name	Action/Definition
	This is used in tunnel applications where multiple barcodes are read and there is a need to filter out one of the barcodes. If less than x number of scanners read the barcode, then it will be considered a NOREAD for that code.
Minimum Readings Difference Between Scanners	Enter the minimum number of scanners that must read a barcode for it to be considered a valid read.
Filter Out Single Readings	With the check box selected, if only 1 scanner reads a code it will be considered a NOREAD.
Strip Filter	Select the check box to display the **Strip Filter Settings** options. This is a second level filter that when enabled allows eliminating characters not managed by the host.

Strip Filter Settings	
Strip All Non Printable Chars	Select the check box to remove all non- printable ASCII characters from the code (000-020 and 127).
Char(s) to be Stripped	Click ✎ to activate the Text Entry Tool and enter specific characters to be stripped from the code. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Strip Filter Collapse	Select the check box to remove the stripped characters from the code and, therefore, reduce the code length (collapsed). It can even be null.
Replacement Char	Click ✎ to activate the Text Entry Tool and enter the substitution character to replace all the stripped ones. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Barcode Configuration > Standard Multi Label

When **Standard Multi Label** has been selected from the **Code Combination** drop-down list, the Barcode Configuration window reveals related input fields.

NOTE: In case of Multi Label, the codes will be distinguished EITHER by their symbology, OR by their contents. If two (or more) codes share the same symbology and content, the scanner will perceive them as a unique code.

1. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Code Combination	Standard Multi Label has been selected.
No Read Message	Select **Disable No Read Message, Global No Read Message,** or **Local No Read(s) Message** from the drop-down list. The No Read condition occurs whenever a code cannot be read or decoded. • **Disable No Read Message:** The No Read Message is not transmitted. • **Global No Read Message:** The No Read String will be sent if the scanner is unable to decode one or more barcodes in the reading phase. • **Local No Read(s) Message:** This option is useful when one or more codes are not read in the reading phase or when more codes than the expected number set by the configuration parameters are read.

Field Name	Action/Definition
	If working in **Standard Multi Label** mode, this option activates the **Code Label Local No Read String** and the **Code Label Local Multiple Read String** parameters which allow setting a **Local No Read String** and a **Local Multiple** string for each defined code symbology.
Use 'Global No Read String' when No Codes Read	Select the check box to allow the **Global No Read String** to be used if no codes at all are read. This option is **not** available when **Global No Read Message** is selected from the **No Read Message** drop-down list.
Global No Read String (max. 128 chars)	Click ✎ to activate the **Text Entry Tool** and create a string to be displayed when **Global No Read Message** is selected from the **No Read Message** drop-down list. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Multiple Read Message	Select **Disable** or **Enable** from the drop-down list. This string will be sent if, during the reading phase, the scanner reads more than the number of the expected barcodes set by the configuration parameters.
Multiple Read String (max. 128 chars)	Click ✎ to activate the **Text Entry Tool** and create a string to be displayed in case of **Multiple Read Message**. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

This parameter is only available when **Multiple Read Message** is enabled and the **No Read Message** selection is different from Local No Read(s) String. It is possible to select either the ASCII or HEX value. If disabled, the scanner transmits the first code read. |
| Send All Multiple Read Labels | **For Advanced Data Format only**, by enabling this parameter all multiple read labels will be included in the output message. They can be separated by the **Multiple Read Separator**.

Multiple Read Label Separator String (max. 128 chars):

• The Multiple Read Label Separators (up to 128 bytes) are used to separate multiple read barcodes in the reading phase.

• This is meaningful when the Code Combination parameter is set to Multi Label or Logical Combination and the Send All Multiple Read Labels parameter has been enabled.

• If selected, they occur within the Code Field and are transmitted after each decoded multiple read barcode. |
| Multi Filters | Select the check box to display the **Multi-Filter Settings** options. |

Field Name	Action/Definition
	Multi-Filter Settings
Contained Filter	Select the check box to reveal the **Max Number of Different Characters** field. When checked, this filter attempts to eliminate false multiple reads by determining if a short code read is "contained in" (is a sub-string of), another longer code read. This condition implicates that the short code is probably a misread of the same longer code and therefore should be ignored, (should not be considered as a multiple read of a different code). This filter is based upon the following rules: • a multiple read condition occurs • all decoded codes of the same type are compared with each other **Rule 1:** the shorter code is considered contained in the longer code if the character string is found in the same order; the longer code may have a single block of characters in any position (before, after or in between the compared strings) **Example:** The code **123456** is considered contained in the following codes: 00**123456**, **123456**00, **123**78**456**. The code **123456** is not considered contained in the following codes: 1234**6**5**07** (string out of order), 12345**700** (string not complete), 12**0**378456 or **00**123456**00** (multiple blocks in the string). **Rule 2:** the shorter code is not filtered by rule 1. In the longer code, all possible sub-strings of the same length as the shorter code string are compared with the shorter code string. The shorter code is considered contained in the longer code if the number of different characters between the compared codes is less than or equal to the Max Number of Different Characters. The shorter code will be filtered by rule 2. **Example:** If Max Number of Different Characters = 1: The code 123456 is considered contained in the following codes: 1230560, 001230056, 88123056 88 because there is only one different character in the compared string. The code 123456 is not considered contained in 123066789 because there are two different characters in the compared string. ⚠️ **CAUTION:** If the Contained Filter parameter is used when **Message Tx Selection** *(see section 4.5.7)* is set to **On Decoding**, the filter conditions may be satisfied before the reading phase ends resulting in possible successive multiple read errors.
Max Number of Different Characters	Enter a value from 0 to 5 in the field provided to define the maximum number of different characters allowed to still consider a code as being included in another one and therefore to be filtered. If the number of different characters between the compared codes exceeds the value of this parameter, the codes are considered as different and will not be filtered (a multiple read of a different code occurs).

Field Name	Action/Definition
	If the number of different characters between the compared codes is less than or equal to the value of this parameter, the short code is considered as a sub-string of the longer code and will be filtered (no multiple read occurs).
	Examples:
	If **Max Number of Different Characters** = 2:
	The code **123456** read once, is considered the same as the following codes read multiple times: 1**33**0**5**6, 1235**4**6, 12345**7** because there are two or less different characters by position in the compared codes.
	The code **123456** read once, is not considered the same as the following codes read multiple times: 1**5**3**24**6, 1**03**0**5**7, **654321** because there are at least three different characters by position in the compared codes.
Voting Filter	Select the check box to reveal the **Max Number of Different Characters** field.
	When selected, this filter attempts to eliminate false multiple reads by comparing the number of different characters by position between two codes of the same type and length. This condition implicates that reading a code of the same type and length having very few different characters is probably a misread of the code itself and therefore the code read the least number of times should be ignored, (should not be considered as a multiple read of a different code).
	This filter is based upon the following rules:
	• a multiple read condition occurs;
	• the two codes are of the same type;
	• the two codes have the same length;
	• the number of different characters by position is equal to or less than the number defined by the **Max Number of Different Characters** parameter;
	• **Message Tx Selectio**n *(see section 4.5.7)* must be set to **After Reading Phase Off**.
Filter Out Low Height Codes	Select the check box to reveal the **Minimum Readings Difference Between Scanners** field**.**
	Background: This option was developed for the airports systems where there are often tall bar height codes and low bar height codes with the same content attached to baggage. Travelers will often remove the large, tall bar height code, while leaving the smaller, low bar height codes attached to the bag. The next time they travel they may have multiple low bar height codes on their baggage plus the new tall bar height and low bar height codes for the new trip.
	This option instructs the system to ignore low bar height codes, which are likely read only once or twice, in favor of tall bar height codes, which will likely be read multiple times.
	This is used in tunnel applications where multiple barcodes are read and there is a need to filter out one of the barcodes. If less than *x* number of scanners read the barcode, then it will be considered a NOREAD for that code.

Field Name	Action/Definition
Minimum Readings Difference Between Scanners	Enter the minimum number of scanners that must read a barcode for it to be considered a valid read.
Filter Out Single Readings	With the check box selected, if only 1 scanner reads a code it will be considered a NOREAD.
Strip Filter	Select the check box to display the **Strip Filter Settings** options. This is a second level filter that when enabled allows eliminating characters not managed by the host.

Strip Filter Settings	
Strip All Non Printable Chars	Select the check box to remove all non- printable ASCII characters from the code (000-020 and 127).
Char(s) to be Stripped	Click ✎ to activate the Text Entry Tool and enter specific characters to be stripped from the code. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Strip Filter Collapse	Select the check box to remove the stripped characters from the code and, therefore, reduce the code length (collapsed). It can even be null.
Replacement Char	Click ✎ to activate the Text Entry Tool and enter the substitution character to replace all the stripped ones. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

2. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Barcode Configuration > Logical Combination

When **Logical Combination** has been selected from the **Code Combination** drop-down list, the Barcode Configuration window reveals related input fields.

1. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Code Combination	**Standard Multi Label** has been selected.
Logical Combination Rule	Click ✎ to activate the code group selection dialog box.

Select the number of groups you wish to use from the Number of Groups drop-down list. Then select the check box next to the Group/Code you wish to define. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Groups and their order define the output message format, while each group identifies an expected code.

When editing the logical combination rule, proceed as follows:

1. Define the Barcode Settings indicating the type of expected code labels. It is possible to define up to 10 different code types;

2. Define how many code types (groups) are expected by editing the combination rule through the following logical operators. Each group may include one or more selected code types.

   & = AND operator which separates a group from the previous/following one;

   ^ = XOR operator to be used to combine different code labels within the same group. It allows reading one of the defined code labels.
   The maximum number of groups to be defined for each rule string is 15.

If Local No Read Message is selected from the No Read Message drop-down list, the Group No Read Messages parameter group is displayed requiring the definition of a Local No Read String for each group.

Field Name	Action/Definition
	Examples: Logical Combination Rule

For all the following examples the **No Read Message** parameter is set to **Global No Read Message**.

Example 1

Code label setting#1 = Code 128
Logical Combination Rule = 1&1
Defines 2 groups, each of them expecting a Code 128 label.

Decoded Code Symbology		Output Message
First Label #1	Second Label #1	
---	---	<Header><Global No Read Message><Terminator>
X	---	<Header><Global No Read Message><Terminator>
---	X	<Header><Global No Read Message><Terminator>
X	X	<Header><Code 128 data><Data Packet Separator><Code 128 data><Terminator>

NOTE: If **Multiple Read Message** is enabled and a third label belonging to the Code 128 symbology is decoded, the **Multiple Read** string is transmitted instead. If the **Multiple Read Message** is disabled, the third code label is ignored and only the first two codes are transmitted.

For advanced formatting, if the **Send All Multiple Read Labels** parameter is enabled, then all three labels are sent in the output message; the multiple read label is separated by its own **Multiple Read Label Separator String** which should be different from the **Data Packet Separator** (DPS).

Example 2

Code label setting#1 = Code 39
Code label setting#2 = Code 128
Logical Combination Rule = 1^2
Defines a single group expecting a Code 128 label OR a Code 39 label.

Decoded Code Symbology		Output Message
Label #1	Label #2	
---	---	<Header><Global No Read Message><Terminator>
X	---	<Header><Code 39 data><Terminator>
---	X	<Header><Code 128 data><Terminator>
X	X	<Header><First decoded code/Multiple Read Message string ><Terminator>

Field Name	Action/Definition

<div align="center"><u>**Example 3**</u></div>

Code label setting#1 = EAN 8
Code label setting#2 = UPC-A
Logical Combination Rule = 1&1&1^2
Defines three different groups. The first two groups expect an EAN 8 label while the third one expects an EAN 8 label OR an UPC-A label.

Decoded Code Symbology				Output Message
First Label #1	Second Label #1	Third Label #1	Label #2	
---	---	---	---	\<Header>\<Global No Read Message>\<Terminator>
X	---	---	---	\<Header>\<Global No Read Message>\<Terminator>
---	X	---	---	\<Header>\<Global No Read Message>\<Terminator>
---	---	X	---	\<Header>\<Global No Read Message>\<Terminator>
---	---	---	X	\<Header>\<Global No Read Message>\<Terminator>
X	X	X	---	\<Header>\<EAN 8 data>\<DPS>\<EAN 8 data>\<DPS>\<EAN 8 data>\<Terminator>
X	X	---	X	\<Header>\<EAN 8 data>\<DPS>\<EAN 8 data>\<DPS>\<UPC-A data>\<Terminator>
X	X	X	X	\<Header>\<EAN 8 data>\<DPS>\<EAN 8 data>\<DPS>\<First decoded code/Multiple Read Message string>\<Terminator>

Field Name	Action/Definition

Example 4

Code label setting#1 = Code 93
Code label setting#2 = Interleaved 2/5
Code label setting#3= EAN-8
Code label setting#4= UPC-A

Logical Combination Rule = 1^2&3^4

Defines 2 groups, each of them expecting one of the defined code types. The first group may expect a Code 93 label or an Interleaved 2/5 label. The second group may expect an EAN-8 label or an UPC-A label.

Decoded Code Symbology				Output Message
Label #1	Label #2	Label #3	Label #4	
---	---	---	---	\<Header>\<Global No Read Message>\<Terminator>
X	---	---	---	\<Header>\<Global No Read Message>\<Terminator>
---	X	---	---	\<Header>\<Global No Read Message>\<Terminator>
---	---	X	---	\<Header>\<Global No Read Message>\<Terminator>
---	---	---	X	\<Header>\<Global No Read Message>\<Terminator>
X	X	---	---	\<Header>\<Global No Read Message>\<Terminator>
X	---	X	X	\<Header>\<Code93>\<DPS>\< First decoded code/Multiple Read Message string>\<Terminator>
X	X	X	---	\<Header>\<First decoded code/Multiple Read Message string>\<DPS>\<EAN 8 data>\<Terminator>
---	X	X	X	\<Header>\< Interleaved 2/5 data>\<DPS>\< First decoded code/Multiple Read Message string >\<Terminator>
X	---	X	---	\<Header>\<Code 93 data>\<DPS>\<EAN 8 data>\<Terminator>
X	---	---	X	\<Header>\<Code 93 data>\<DPS>\<UPC-A data>\<Terminator>
---	X	X	---	\<Header>\<Interleaved 2/5 data>\<DPS>\<EAN 8 data>\<Terminator>
---	X	---	X	\<Header>\<Interleaved 2/5 data>\<DPS>\<UPC-A data>\<Terminator>
X	X	X	X	\<Header>\<First decoded code/Multiple Read Message string>\<DPS>\< First decoded code/Multiple Read Message string >\<Terminator>

Field Name	Action/Definition
No Read Message	Select **Disable No Read Message, Global No Read Message,** or **Local No Read(s) Message** from the drop-down list. The **No Read** condition occurs whenever a code cannot be read or decoded. • **Disable No Read Message:** The No Read Message is not transmitted. • **Global No Read Message:** The No Read String will be sent if the scanner is unable to decode one or more barcodes in the reading phase. • **Local No Read(s) Message:** This option is useful when one or more codes are not read in the reading phase or when more codes than the expected number set by the configuration parameters are read. If working in **Logical Combination** mode, this option reveals Group No Read Messages fields, which allows entering group no read strings for each defined code symbology.
Use 'Global No Read String' when No Codes Read	Select the check box to allow the **Global No Read String** to be used if no codes at all are read. This option is **not** available when **Global No Read Message** is selected from the **No Read Message** drop-down list.
Global No Read String (max. 128 chars)	Click ✎ to activate the **Text Entry Tool** and create a string to be displayed when **Global No Read Message** is selected from the **No Read Message** drop-down list. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Multiple Read Message	Select **Disable** or **Enable** from the drop-down list. This string will be sent if, during the reading phase, the scanner reads more than the number of the expected barcodes set by the configuration parameters. If **Disable No Read Message** or **Global No Read Message** is selected from the **No Read Message** drop-down list, this string will be sent if, during the reading phase, the scanner reads more than the number of the expected barcodes set by the configuration parameters. If **Local No Read(s) Message** is selected from the **No Read Message** drop-down list, the **Group Multiple Read Messages** fields appears, allowing the user to enter strings for each Group.
Multiple Read String (max. 128 chars)	Click ✎ to activate the **Text Entry Tool** and create a string to be displayed in case of Multiple Read Message. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text. This parameter is only available when **Multiple Read Message** is enabled and the **No Read Message** selection is different from Local No Read(s) String. It is possible to select either the ASCII or HEX value. If **disabled**, the scanner transmits the first code read.
Send All Multiple Read Labels	For **Advanced Data Format** only, by enabling this parameter all multiple read labels will be included in the output message. They can be separated by the **Multiple Read Separator**. **Multiple Read Label Separator String (max. 128 chars):** The Multiple Read Label Separators (up to 128 bytes) are used to separate multiple read barcodes in the reading phase.

Field Name	Action/Definition
	This is meaningful when the Code Combination parameter is set to Multi Label or Logical Combination and the Send All Multiple Read Labels parameter has been enabled.

If selected, they occur within the Code Field and are transmitted after each decoded multiple read barcode. |
WebSentinel - Partial Read Is Treated As	Select **No Read, Good Read,** or **Partial Read** from the drop-down list. This determines how WebSentinel will treat the partial read.
Multi Filters	Select the check box to display the **Multi-Filter Settings** options.
	Multi-Filter Settings
Contained Filter	Select the check box to reveal the **Max Number of Different Characters** field.

When checked, this filter attempts to eliminate false multiple reads by determining if a short code read is "contained in" (is a sub-string of), another longer code read. This condition implicates that the short code is probably a misread of the same longer code and therefore should be ignored, (should not be considered as a multiple read of a different code).

This filter is based upon the following rules:

- a multiple read condition occurs
- all decoded codes of the same type are compared with each other

Rule 1: the shorter code is considered contained in the longer code if the character string is found in the same order; the longer code may have a single block of characters in any position (before, after or in between the compared strings)

Example: The code **123456** is considered contained in the following codes: 00**123456**, **123456**00, **123**78**456**.

The code **123456** is not considered contained in the following codes: 1234**6**5**0**7 (string out of order), 12345**700** (string not complete), 12**0**3**78**456 or **00**123456**00** (multiple blocks in the string).

Rule 2: the shorter code is not filtered by rule 1. In the longer code, all possible sub-strings of the same length as the shorter code string are compared with the shorter code string. The shorter code is considered contained in the longer code if the number of different characters between the compared codes is less than or equal to the Max Number of Different Characters. The shorter code will be filtered by rule 2.

Example:

If Max Number of Different Characters = 1:

The code 123456 is considered contained in the following codes: 123**0**5600, 00123**0**56, 88123**0**5688 because there is only one different character in the compared string.

The code 123456 is not considered contained in 123**06**6789 because there are two different characters in the compared string. |

Field Name	Action/Definition
	CAUTION: If the Contained Filter parameter is used when **Message Tx Selection** *(see section 4.5.7)* is set to **On Decoding**, the filter conditions may be satisfied before the reading phase ends resulting in possible successive multiple read errors.
Max Number of Different Characters	Enter a value from 0 to 5 in the field provided to define the maximum number of different characters allowed to still consider a code as being included in another one and therefore to be filtered. If the number of different characters between the compared codes exceeds the value of this parameter, the codes are considered as different and will not be filtered (a multiple read of a different code occurs). If the number of different characters between the compared codes is less than or equal to the value of this parameter, the short code is considered as a sub-string of the longer code and will be filtered (no multiple read occurs). **Examples:** If Max Number of Different Characters = 2: The code **123456** read once, is considered the same as the following codes read multiple times: 1**33**056, 123**54**6, 12345**7** because there are two or less different characters by position in the compared codes. The code **123456** read once, is not considered the same as the following codes read multiple times: 1**532**46, 1**03**05**7**, **654321** because there are at least three different characters by position in the compared codes.
Voting Filter	Select the check box to reveal the **Max Number of Different Characters** field. When checked, this filter attempts to eliminate false multiple reads by comparing the number of different characters by position between two codes of the same type and length. This condition implicates that reading a code of the same type and length having very few different characters is probably a misread of the code itself and therefore the code read the least number of times should be ignored, (should not be considered as a multiple read of a different code). This filter is based upon the following rules: • a multiple read condition occurs; • the two codes are of the same type; • the two codes have the same length; • the number of different characters by position is equal to or less than the number defined by the **Max Number of Different Characters** parameter; • **Message Tx Selection** *(see section 4.5.7)* must be set to **After Reading Phase Off.**

Field Name	Action/Definition	
Filter Out Low Height Codes	Select the check box to reveal the **Minimum Readings Difference Between Scanners** field**.**	
	Background: This option was developed for the airports systems where there are often tall bar height codes and low bar height codes with the same content attached to baggage. Travelers will often remove the large, tall bar height code, while leaving the smaller, low bar height codes attached to the bag. The next time they travel they may have multiple low bar height codes on their baggage plus the new tall bar height and low bar height codes for the new trip.	
	This option instructs the system to ignore low bar height codes, which are likely read only once or twice, in favor of tall bar height codes, which will likely be read multiple times.	
	This is used in tunnel applications where multiple barcodes are read and there is a need to filter out one of the barcodes. If less than x number of scanners read the barcode, then it will be considered a NOREAD for that code.	
Minimum Readings Difference Between Scanners	Enter the minimum number of scanners that must read a barcode for it to be considered a valid read.	
Filter Out Single Readings	With the check box selected, if only 1 scanner reads a code it will be considered a NOREAD.	
Strip Filter	Select the check box to display the **Strip Filter Settings** options. This is a second level filter that when enabled allows eliminating characters not managed by the host.	
Strip Filter Settings	**Strip All Non Printable Chars**	Select the check box to remove all non- printable ASCII characters from the code (000-020 and 127).
	Char(s) to be Stripped	Click 🖉 to activate the **Text Entry Tool** and enter specific characters to be stripped from the code. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
	Strip Filter Collapse	Select the check box to remove the stripped characters from the code and, therefore, reduce the code length (collapsed). It can even be null.
	Replacement Char	Click 🖉 to activate the **Text Entry Tool** and enter the substitution character to replace all the stripped ones. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Field Name	Action/Definition
Priority Filter Enable	Select the check box to display the Priority Filter options. This function allows the user to prioritize barcodes. **Example:** If there is a message with a field that should contain one of multiple code types (for example, Code128, Code39 and I2of5). In this field, the user wants: • If Code 128 is read, it goes in the field (any code39 and I2of5 are ignored) • If Code 128 is not read – if Code39 is read, it goes in the field (and I2of5 is ignored) • If Code 128 and Code30 are not read – if i2of5 is read, it goes in the field.

Priority Filter Group List	Enter the Group List in the field provided. This field defines the specific Logical Combination groups to which the Priority Filter will apply. The groups are numbered according to the order in which they are listed (from left to right) in the Logical Combination Rule parameter.
	
	Format: Group Number(s) separated by the comma character
	
	    Example:
	
	    1,3 means the Priority Filter is applied to Logical Groups 1 and 3. Logical Group 2 will not have the Priority Filter applied, however it will follow the normal rules of code analysis, and if selected, the Strip Filter parameters will apply.

Priority Filter Type	Select Normal or Advanced from the drop-down list.
	
	Description:
	• Normal: Uses the Logical Combination Rule string to define the priority
	
	• Advanced: Uses the Priority Filter Advanced String to define the priority. Advanced type allows the priority filter to essentially take "priority" over the Logical Combination Rule string.
	
	<u>NORMAL</u>
	
	When the **Priority Filter Type** is set to **Normal**, the operators used in the **Logical Combination Rule** string have the following meaning:
	
	    & = AND operator which separates a group from the previous/following one;
	
	    ^ = The priority is given to the code label indicated to the left of the operator. If this code is read, the group is in Good Read independent from any other code in the same group.

Field Name	Action/Definition

Example:

Logical Combination Rule = 1^2&5^3^4&6^7 (3 groups)

Results Without Priority Filter:

Group 1 - read either code 1 or 2 = Good Read; read both code 1 and 2 = Multiple Read

Group 2 - read either code 5 or 3 or 4 = Good Read; read any combination = Multiple Read

Group 3 - read either code 6 or 7 = Good Read; read both code 6 and 7 = Multiple Read

Results With Priority Filter:

Filter Enabled on Groups = 1,2

Group 1 - read code 1 = Good Read independent from reading code 2

Group 2 - read code 5 = Good Read independent from reading code 3 or 4; read code 3 = Good Read independent from reading code 4

Group 3 - read either code 6 or 7 = Good Read; read both code 6 and 7 = Multiple Read

ADVANCED

When the **Priority Filter Type** is set to **Advanced**, the **Priority Filter Advanced String** applies to the Logical Combination Groups. This string must correspond to the order of the groups defined in the Logical Combination Rule string.

The following operators can be used:

& = Code group separator. This operator separates a group from the previous/following one;

^ = The priority is given to the code label indicated to the left of this operator. If this code is read, the group is in Good Read independent from any other code in the same group.

| = Equal priority operator (vertical line). Codes separated by this operator have the same priority and if both codes are read a Multiple Read will result.

The only difference from the implicit pattern string of the Normal (default) case when the Logical Combination Rule string is used, is the Equal Priority operator.

Field Name	Action/Definition
	Example: Logical Combination Rule = 1^2&5^3^4&8^6^7 (3 groups) **Results Without Priority Filter:** **Group 1** - read either code 1 or 2 = Good Read; read both code 1 and 2 = Multiple Read **Group 2** - read either code 5 or 3 or 4 = Good Read; read any combination = Multiple Read **Group 3** - read either code 8 or 6 or 7 = Good Read; read any combination = Multiple Read **Results With Priority Filter:** Filter Enabled on Groups = 1,3 Filter Type =Custom Custom Filter Pattern String = 1^2&8^6|7 (2 groups) **Group 1** - read code 1 = Good Read independent from reading code 2 **Group 2** - read either code 5 or 3 or 4 = Good Read; read any combination = Multiple Read **Group 3** - read code 8 = Good Read independent from reading code 6 or 7; no read on code 8 and read either code 6 or 7 = Good Read; no read on code 8 and read both code 6 and 7 = Multiple Read
Priority Filter Advanced String	Enter the character string (see above).

2. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.
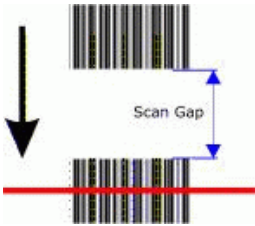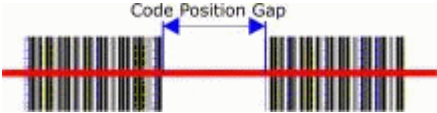
Barcode Configuration > Code Collection

When **Code Collection** has been selected from the **Code Combination** drop-down list, the Barcode Configuration window reveals related input fields.

1. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Code Combination	**Code Collection** has been selected.
No Read Message	Select **Disable No Read Message, Global No Read Message,** or **Local No Read(s) Message** from the drop-down list. The No Read condition occurs whenever a code cannot be read or decoded.

- **Disable No Read Message:** The No Read Message is not transmitted.
- **Global No Read Message:** The No Read String will be sent if the scanner is unable to decode one or more barcodes in the reading phase.
- **Local No Read(s) Message:** This option is useful when one or more codes are not read in the reading phase or when more codes than the expected number set by the configuration parameters are read.

If working in **Standard Multi Label** mode, this option activates the **Code Label Local No Read String** and the **Code Label Local Multiple Read String** parameters which allow setting a **Local No Read String** and a **Local Multiple** string for each defined code symbology.

Field Name	Action/Definition
Use 'Global No Read String' when No Codes Read	Select the check box to allow the **Global No Read String** to be used if no codes at all are read. This option is **not** available when **Global No Read Message** is selected from the **No Read Message** drop-down list.
Global No Read String (max. 128 chars)	Click ✏ to activate the **Text Entry Tool** and create a string to be displayed when **Global No Read Message** is selected from the **No Read Message** drop-down list. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Multi Filters	Select the check box to display the **Multi-Filter Settings** options.
Code Collection Settings	
Associate Same Codes When Read By Different Scanners	Select the check box to enable this function. This parameter is available only when the **Code Combination** parameter is set to *Code Collection* and the scanner role is *Master*. If enabled, it allows transmitting all codes belonging to the same programmed Slot (same symbology and content) but read by different scanners (including the Master) in a single instance. **Scanner Role:** • **Master SYNCHRONIZED:** The scanner is connected as a Master in a master/slave synchronized configuration. • **Slave SYNCHRONIZED:** The scanner is connected as a Salve in a master/slave synchronized configuration. (See note below.) • **Other:** This selection is for a stand-alone scanner.
Code Different When Scan Gap Is Greater Than	This parameter is available only when the **Code Combination** parameter is set to **Code Collection**. If the number of scans performed between two consecutive codes read (by the Master or Stand Alone scanner) is greater than the defined number, the codes will be considered as different. The parameter set to 0 means the filter is disabled: when there is no scan gap all the consecutive codes read will be considered as only one code.
Code Different When Code Position Gap Is Greater Than	This parameter is available only when the **Code Combination** parameter is set to Code Collection. If the position gap between two consecutive codes read (by the Master or Stand Alone scanner) on the same scan line is greater than the defined gap number, the codes will be considered as different. The parameter set to 0 means the filter is disabled: when there is no code position gap all the consecutive codes read will be considered as only one code.

Field Name	Action/Definition
	Multi-Filter Settings
Contained Filter	Select the check box to reveal the **Max Number of Different Characters** field. When checked, this filter attempts to eliminate false multiple reads by determining if a short code read is "contained in" (is a sub-string of), another longer code read. This condition implicates that the short code is probably a misread of the same longer code and therefore should be ignored, (should not be considered as a multiple read of a different code). This filter is based upon the following rules: • a multiple read condition occurs • all decoded codes of the same type are compared with each other **Rule 1:** the shorter code is considered contained in the longer code if the character string is found in the same order; the longer code may have a single block of characters in any position (before, after or in between the compared strings) **Example:** The code **123456** is considered contained in the following codes: 00**123456**, **123456**00, **123**78**456**. The code **123456** is not considered contained in the following codes: 1234**65**07 (string out of order), 12345**700** (string not complete), 12**0378**456 or **00**1234560**00** (multiple blocks in the string). **Rule 2:** the shorter code is not filtered by rule 1. In the longer code, all possible sub-strings of the same length as the shorter code string are compared with the shorter code string. The shorter code is considered contained in the longer code if the number of different characters between the compared codes is less than or equal to the Max Number of Different Characters. The shorter code will be filtered by rule 2. **Example:** If Max Number of Different Characters = 1: The code 123456 is considered contained in the following codes: 123**0**5600, 00123**0**56, 88123**0**5688 because there is only one different character in the compared string. The code 123456 is not considered contained in 123**06**6789 because there are two different characters in the compared string. ⚠ **CAUTION:** If the Contained Filter parameter is used when **Message Tx Selection** *(see section 4.5.7)* is set to **On Decoding**, the filter conditions may be satisfied before the reading phase ends resulting in possible successive multiple read errors.
Max Number of Different Characters	Enter a value from 0 to 5 in the field provided to define the maximum number of different characters allowed to still consider a code as being included in another one and therefore to be filtered. If the number of different characters between the compared codes exceeds the value of this parameter, the codes are considered as different and will not be filtered (a multiple read of a different code occurs).

Field Name	Action/Definition
	If the number of different characters between the compared codes is less than or equal to the value of this parameter, the short code is considered as a sub-string of the longer code and will be filtered (no multiple read occurs).
	Examples:
	If Max Number of Different Characters = 2: The code **123456** read once, is considered the same as the following codes read multiple times: 1**33**0**5**6, 123**54**6, 12345**7** because there are two or less different characters by position in the compared codes.
	The code **123456** read once, is not considered the same as the following codes read multiple times: 1**53**2**4**6, 1**03**0**5**7, **654321** because there are at least three different characters by position in the compared codes.
Voting Filter	Select the check box to reveal the Max Number of Different Characters field. When checked, this filter attempts to eliminate false multiple reads by comparing the number of different characters by position between two codes of the same type and length. This condition implicates that reading a code of the same type and length having very few different characters is probably a misread of the code itself and therefore the code read the least number of times should be ignored, (should not be considered as a multiple read of a different code).
	This filter is based upon the following rules:
	• a multiple read condition occurs; • the two codes are of the same type; • the two codes have the same length; • the number of different characters by position is equal to or less than the number defined by the **Max Number of Different Characters** parameter; • **Message Tx Selection** *(see section 4.5.7)* must be set to **After Reading Phase Off**.
Filter Out Low Height Codes	Select the check box to reveal the **Minimum Readings Difference Between Scanners** field**.**
	Background: This option was developed for the airports systems where there are often tall bar height codes and low bar height codes with the same content attached to baggage. Travelers will often remove the large, tall bar height code, while leaving the smaller, low bar height codes attached to the bag. The next time they travel they may have multiple low bar height codes on their baggage plus the new tall bar height and low bar height codes for the new trip.
	This option instructs the system to ignore low bar height codes, which are likely read only once or twice, in favor of tall bar height codes, which will likely be read multiple times.
	This is used in tunnel applications where multiple barcodes are read and there is a need to filter out one of the barcodes. If less than x number of scanners read the barcode, then it will be considered a NOREAD for that code.
Minimum Readings Difference Between Scanners	Enter the minimum number of scanners that must read a barcode for it to be considered a valid read.

Field Name	Action/Definition
Filter Out Single Readings	With the check box selected, if only 1 scanner reads a code it will be considered a NOREAD.
Strip Filter	Select the check box to display the **Strip Filter Settings** options. This is a second level filter that when enabled allows eliminating characters not managed by the host.

Strip Filter Settings	
Strip All Non Printable Chars	Select the check box to remove all non- printable ASCII characters from the code (000-020 and 127).
Char(s) to be Stripped	Click ✎ to activate the **Text Entry Tool** and enter specific characters to be stripped from the code. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Strip Filter Collapse	Select the check box to remove the stripped characters from the code and, therefore, reduce the code length (collapsed). It can even be null.
Replacement Char	Click ✎ to activate the **Text Entry Tool** and enter the substitution character to replace all the stripped ones. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

2. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.5.4   Modify Settings | Global Settings | Serial Ports

Use the Serial Ports menu tree selections during initial setup to configure any serial ports used by your barcode scanning system. If necessary, you can later make modifications to the global system settings using the same menu selections, including:

```
⊟··Serial Ports
    ├···Main Port
    └···Aux Port
```

Modify Settings | Global Settings | Serial Ports | Main Port

Use **Main Port** window to configure communication between the scanner and the Host, or in a multi-sided layout, between several scanners and a Host.

To edit the Main Port settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Serial Ports | Main Port**. The Main Port window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Data Tx	Select the check box to enabled **Data Tx**. If selected, the **Main Serial Port** channel is used by the scanner to transmit data and/or messages.
Heartbeat	Select **Disable, Enable Unconditioned,** or **Enable Conditioned** from the drop-down list. This parameter is available when the **Data TX** parameter is checked. It enables/disables the transmission of the Heartbeat message signaling that the device is still active. • **Disable:** The Heartbeat message is not transmitted • **Enable Unconditioned**: The Heartbeat message is always transmitted, even if communication is still active • **Enable Conditioned:** The Heartbeat message is transmitted only when there is no communication
Heartbeat Settings	
Heartbeat Timeout	Enter a time value in seconds to define the amount of time between two message transmissions. If the input timeout expires and no transmission has occurred, the Heartbeat message will be transmitted.
Heartbeat Message (max. 32 chars)	Click ✎ to activate the Text Entry Tool and create heartbeat header text to signal the beginning of the heartbeat message. Characters from NUL (00H) to ~ (7EH) can be used. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text. The **Heartbeat Message** (header) string must be different from the **Heartbeat Terminator** string.
Heartbeat Terminator (max. 32 chars)	Click ✎ to activate the Text Entry Tool and create **Heartbeat Terminator** text to signal the end of the heartbeat message. Characters from NUL (00H) to ~ (7EH) can be used. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text. The **Heartbeat Terminator** string must be different from the **Heartbeat Message** (header) string.
Line Settings	
Main Port Electrical Interface	Select **RS232** or **RS422 full duplex** from the drop-down list. The Main serial interface is compatible with these available electrical standards.
Handshake	Select **None, Hardware (RTS/CTS),** or **Software (Xon/Xoff)** from the drop-down list. Handshake is a communication control used to protect against data loss, it can be achieved via hardware (RTS\CTS protocol) or software (Xon\Xoff protocol).
Baud Rate	Select a value from **1200** to **115200** from the drop-down list. **Baud Rate** is the transmission speed in a communication line.
Parity	Select **None, Odd,** or **Even** from the drop-down list. **Parity** is a parameter indicating the presence of a control bit in the communication protocol frame.

Field Name	Action/Definition
Data Bits	Select **7** or **8** from the drop-down list. **Data Bits** is a parameter indicating the number of bits composing the data packet of the communication protocol frame.
Stop Bits	Select **1** or **2** from the drop-down list. **Stop Bits** is a parameter indicating the number of stop bits in the data packet of the communication protocol frame.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Modify Settings | Global Settings | Serial Ports | Aux Port

Use the **Aux Port** window to configure communication through the Auxiliary Serial Port. For this communication mode, RS232 interface is automatically selected.

To edit the Aux Port settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Serial Ports | Aux Port**. The Aux Port window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Search for CBX BM100 at Device Startup	Select the check box to automatically search for a BM100 storage module when the scanner is powered on.
Data Tx	Select the check box to enabled **Data Tx**. If selected, the **Aux Serial Port** channel is used by the scanner to transmit data and/or messages.
Heartbeat	Select **Disable, Enable Unconditioned,** or **Enable Conditioned** from the drop-down list. This parameter is available when the **Data TX** parameter is checked. It enables/disables the transmission of the Heartbeat message signaling that the device is still active. • **Disable:** The Heartbeat message is not transmitted • **Enable Unconditioned:** The Heartbeat message is always transmitted, even if communication is still active • **Enable Conditioned:** The Heartbeat message is transmitted only when there is no communication
Heartbeat Settings	
Heartbeat Timeout	Enter a time value in seconds to define the amount of time between two message transmissions. If the input timeout expires and no transmission has occurred, the Heartbeat message will be transmitted.
Heartbeat Message (max. 32 chars)	Click ✎ to activate the **Text Entry Tool** and create heartbeat header text to signal the beginning of the heartbeat message. Characters from NUL (00H) to ~ (7EH) can be used. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text. The Heartbeat Message (header) string must be different from the Heartbeat Terminator string.
Heartbeat Terminator (max. 32 chars)	Click ✎ to activate the **Text Entry Tool** and create **Heartbeat Terminator** text to signal the end of the heartbeat message. Characters from NUL (00H) to ~ (7EH) can be used. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text. The **Heartbeat Terminator** string must be different from the Heartbeat Message (header) string.
Line Settings	
Baud Rate	Select a value from 1200 to 115200 from the drop-down list. **Baud Rate** is the transmission speed in a communication line.
Parity	Select **None, Odd,** or **Even** from the drop-down list. **Parity** is a parameter indicating the presence of a control bit in the communication protocol frame.
Data Bits	Select 7 or 8 from the drop-down list. **Data Bits** is a parameter indicating the number of bits composing the data packet of the communication protocol frame.

Field Name	Action/Definition
Stop Bits	Select 1 or 2 from the drop-down list. **Stop Bits** is a parameter indicating the number of stop bits in the data packet of the communication protocol frame.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.5.5   Modify Settings | Global Settings | Ethernet

Use the **Ethernet** menu tree selections during initial setup to configure the Ethernet settings for your barcode scanning system.

Ethernet is the most popular physical layer LAN technology in use today. It is the IEEE 802.3 series standard, based on the CSMA/CD access method that provides two or more stations to share a common cabling system. This access method, Carrier Sense Multiple Access with Collision Detection, is the basis for Ethernet systems providing a wide range of speed.

The design goals for Ethernet are to create a simply defined topology that makes efficient use of shared resources that are easy to reconfigure and maintain and provides compatibility across many manufacturer and systems.

Ethernet supports many different network protocols; Datalogic scanners support IP plus TCP or UDP over Ethernet and 802.3 frame format as Ethernet protocol low level.

If necessary, you can later make modifications to the global system settings using the same menu selections, including:
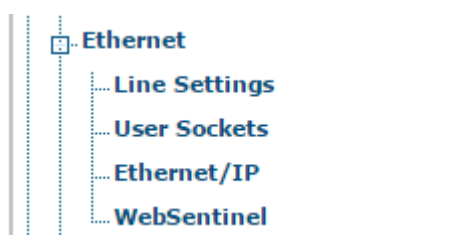
Modify Settings | Global Settings | Ethernet | Line Settings

Use the **Line Settings** window to define and report the fundamental information about the system.

To edit the Line Settings:

1. In the tree menu under Modify Settings, navigate to Global Settings | Ethernet | Line Settings. The Line Settings window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Host Network (ETH1)	
Enable DHCP	Select the check box to cause the IP address parameters to become inactive. They are then used to display the addresses assigned by a DHCP server when getting the scanner configuration.
IP Address	Enter the device Internet Protocol (IP) network address in the field provided. Consult your network administrator to obtain a new address.
IP Netmask	Enter the device subnet mask address in the field provided. Consult your network administrator to obtain a new address.
IP Gateway	Enter the device gateway address in the field provided. Consult your network administrator to obtain a new address.
IP DNS1	Enter the address of the Primary Domain Name System (DNS) in the field provided.
IP DNS2	Enter the address of the Secondary Domain Name System (DNS) in the field provided.

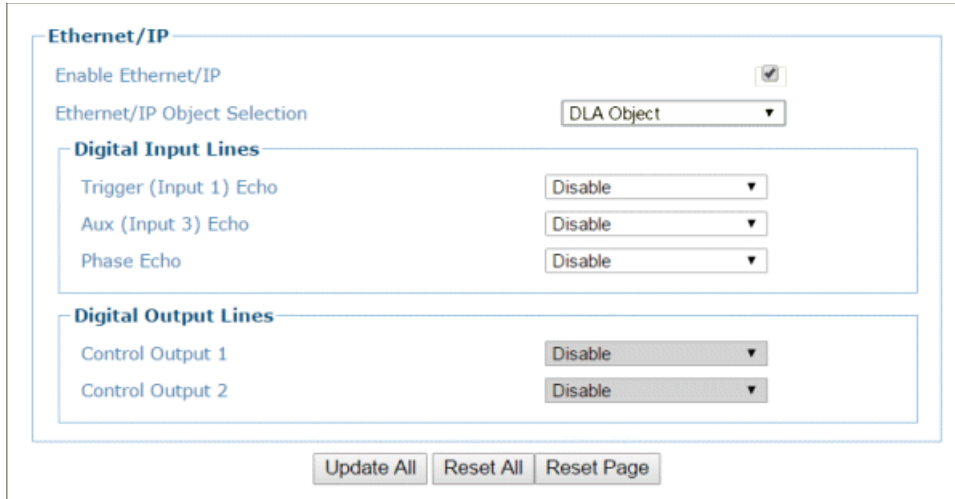| Field Name	Action/Definition
Setup Network (ETH2)	
Setup IP Address	Enter the Internet Protocol (IP) network address for ETH2 (Setup) in the field provided. Consult your network administrator to obtain a new address.
Setup Netmask	Enter the subnet mask address for ETH2 (Setup) in the field provided. Consult your network administrator to obtain a new address.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Modify Settings | Global Settings | Ethernet | User Sockets

Use the **User Sockets** (User Socket Settings) window to setup, edit, and configure numbered user sockets for your barcode scanning system. User sockets are another interface available for the Ethernet communication.

To edit the User Socket settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Ethernet | User Sockets**. The User Sockets window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
User Socket List	Select an option button in the list at the top of this window to create a new user socket, or to edit an existing one.
User Socket *n*	
Enable User Socket	Select the check box to enable **User Sockets** and reveal the related configuration options.
Enable Data Transmission	Select the check box to enable **User Sockets** and reveal the related configuration options. When enabled, **Ethernet User Socket** is selected as the channel to be used by the scanner for transmitting data and/or messages.

Field Name	Action/Definition
Heartbeat	Select **Disable, Enable Unconditioned,** or **Enable Conditioned** from the drop-down list. This parameter is available when the **Data TX** parameter is checked. It enables/disables the transmission of the Heartbeat message signaling that the device is still active. • **Disable:** The Heartbeat message is not transmitted • **Enable Unconditioned:** The Heartbeat message is always transmitted, even if communication is still active • **Enable Conditioned:** The Heartbeat message is transmitted only when there is no communication

Heartbeat Settings	
Heartbeat Timeout	Enter a time value in seconds to define the amount of time between two message transmissions. If the input timeout expires and no transmission has occurred, the Heartbeat message will be transmitted.
Heartbeat Message (max. 32 chars)	Click ✎ to activate the **Text Entry Tool** and create heartbeat header text to signal the beginning of the heartbeat message. Characters from NUL (00H) to ~ (7EH) can be used. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text. The **Heartbeat Message** (header) string must be different from the **Heartbeat Terminator** string.
Heartbeat Terminator (max. 32 chars)	Click ✎ to activate the **Text Entry Tool** and create **Heartbeat Terminator** text to signal the end of the heartbeat message. Characters from NUL (00H) to ~ (7EH) can be used. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text. The **Heartbeat Terminator** string must be different from the **Heartbeat Message** (header) string

Field Name	Action/Definition
	Socket Configuration
Type	Select **Server** or **Client** from the drop-down list to define the type of the socket:

When the Protocol selected is TCP (see below):

- **Server:** The station waits for connections and can communicate with a maximum of 3 clients simultaneously.

- **Client:** The station tries a connection towards the server.

When the Protocol selected is UDP (see below):

- **Server:** Special Datalogic mode in which the station waits to receive a message (content of message does not matter), and then responds with UDP host messages to that client. You must enter a port number, and if using a fixed UDP destination port, you must enter the number for that port as well.

- **Client:** Choose this option for standard UDP protocol. You must define the Server Address that will be receiving the UDP messages and port. If using a fixed UDP source port, you must enter the UDP source port number.

Field Name	Action/Definition
Server Address	Enter the IP address of the server to which the client tries to connect. This parameter is available only when the socket is configured as a **Client**.
Protocol	Select **TCP** (Transmission Control Protocol) or **UDP** (User Datagram Protocol) from the drop-down list to define the protocol to be used for the Ethernet communication. **NOTE:** When using the **UDP** protocol: • The User Socket Client Port is bound to the Server Port. • The maximum size for maintaining a whole datagram is 1436 bytes, messages exceeding this value will be fragmented.
Port	Enter the port number of the socket.
Fixed UDP Destination Port	When using UDP Server, select the check box to enable a fixed UDP destination port.
UDP Destination Port	When using UDP Server with a fixed UDP destination port, enter the port number.
Fixed UDP Source Port	When using UDP Client, select the check box to enable a fixed UDP source port.
UDP Source Port	When using UDP Client with a fixed UDP source port, enter the port number.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Modify Settings | Global Settings | Ethernet | Ethernet/IP

Use the **Ethernet I/P** window to set up digital inputs and outputs for the barcode scanner.

To enable or disable Ethernet/IP:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Ethernet | Ethernet/IP**. The **Ethernet/IP** window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Enable Ethernet/IP	Select the check box to enable **Ethernet/IP** and reveal the related configuration options.
Ethernet/IP Object Selection	Select DLA Object or ASI Object from the drop-down list. **Selection:** • **DLA Object** - Refers to Datalogic Devices • **ASI Object** - Refers to legacy Accu-Sort Devices
Enable ControlLogix On-Demand Messaging	Select the check box to enable **On-Demand Messaging** when **ASI Object** is selected. **On-Demand Messaging** is a special option for communicating with ControlLogix/CompactLogix Controllers. When enabled, you must provide the Controller IP Address, the Slot number of the processor in the Controller and a Tag Name. To use On-Demand messaging, a tag of the same name is then defined on the ControlLogix/CompactLogix Controller and every time a bar code is read, the Bar Code object is transferred to the ControlLogix/CompactLogix Tag.
	Digital Input Lines
Trigger (Input 1) Echo	Select **Disable** or **Enable** from the drop-down list. If enabled, the Scanner Master or SC5000 Controller **Trigger (Input 1)** status is echoed to the Ethernet Client via bit 0 in Byte InputBits of the DL_InputStruct.

Field Name	Action/Definition
Aux (Input 3) Echo	Select **Disable** or **Enable** from the drop-down list. If enabled, the Scanner Master or SC5000 Controller **Input 3** status is echoed to the Ethernet Client via bit 2 in Byte InputBits of the DL_InputStruct.
Phase Echo	This parameter is configurable only if **Start Input from Bus** is enabled. Select **Disable** or **Enable** from the drop-down list. If enabled, the **Reading Phase** status is echoed to the Ethernet Client via bit 7 in Byte InputBits of the DL_InputStruct.

ASI Object: On-Demand Options

Ethernet/IP

Enable Ethernet/IP	☑
Ethernet/IP Object Selection	ASI Object ▼
Enable ControlLogix On-Demand Messaging	☑

On-Demand Options

PLC IP Address	0.0.0.0
Tag Name	ScannerTag
PLC Slot Number	0

Message Options

Message Format	ASCII ▼
ASCII Message Byte Swap	☐

Digital Output Lines

Control Output 1	Disable ▼
Control Output 2	Disable ▼

Update All   Reset All   Reset Page

> **NOTE:** Contact Datalogic Support for information on setting up ASI Objects (legacy Accu-Sort Devices). See Support Through the Website.

PLC IP Address	Enter the IP Address for the PLC Controller (Rockwell Automation: Allen-Bradley Controllogix or CompactLogix).
Tag Name	Enter a tag name (up to 40 characters) in the field provided.
PLC Slot Number	Enter the PLC Slot number in the field provided. This corresponds to the physical slot used on the PLC.

ASI Object: Message Options

Message Format	Select ASCII or Binary from the drop-down list. **Selections:** • **ASCII -** Select to transmit an ASCII barcode message (as defined by the Message Type). The only difference is that the Header and Trailer are omitted from the barcode messages transmitted using Ethernet/IP. When ASCII messages are in use, the Byte Swap ASCII Data selection will swap the high and low byte of data within each 16 bit word. This is useful for processing data on some Programmable Controllers.

Field Name	Action/Definition
	• **Binary -** Select to convert barcode data to a "numeric value" and transferred as a 32 bit word. The user can specify the byte ordering of this word. If any non-numeric (not ASCII '0' to '9' or leading or trailing space) characters are contained in the barcode, the numeric value is zero.
ASCII Message Byte Swap	Select the check box to enable the function. Available when Binary is selected from the **Message Format** drop-down list. When ASCII messages are in use, the ASCII Message Byte Swap selection will swap the high and low byte of data within each 16 bit word. This is useful for processing data on some Programmable Controllers.
Binary Message Byte Order	Select **Little Endian** or **Big Endian** from the drop-down list. Available when Binary is selected from the Message Format drop-down list. **Selection:** • **Little Endian:** The least significant byte (little end) of the data is positioned at the byte with the lowest address. • **Big Endian:** The most significant byte (big end) of the data is positioned at the byte with the lowest address.
Digital Output Lines	
Control Output 1	This parameter is configurable only if **Digital Output 1 Use** is set to Ethernet/IP. Select **Disable** or **Enable** from the drop-down list. If enabled, it allows the Ethernet Client to drive the Scanner Master or SC5000 Controller **Output 1** via bit 0 in Byte OutputBits of the DL_OutputStruct.
Control Output 2	This parameter is configurable only if **Digital Output 2 Use** is set to Ethernet/IP. Select **Disable** or **Enable** from the drop-down list. If enabled, it allows the Ethernet Client to drive the Scanner Master or SC5000 Controller **Output 2** via bit 1 in Byte OutputBits of the DL_OutputStruct.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Modify Settings | Global Settings | Ethernet | WebSentinel

Use the **WebSentinel**™ window to enable and configure the barcode scanner for use with Datalogic WebSentinel.

To enable or disable WebSentinel:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Ethernet | WebSentinel**. The WebSentinel window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Enable	Select the check box to enable **WebSentinel** and reveal the related configuration options.
WebSentinel Socket	Select a socket number for WebSentinel from those available in the drop-down list.
Monitor Settings	
Conveyor Speed Check Type	Select **Percentage** or **Absolute** from the drop-down list to determine how the conveyor speed is evaluated.
Max Conveyor Speed Percent Error (%)	In the text field provided, enter the percentage of discrepancy allowed in the conveyor speed before an error is sent. This option is available when **Percentage is** selected from the **Conveyor Speed Check Type drop-down list.**
Max Conveyor Speed Absolute Error (mm/s)	In the text field provided, enter the milliseconds of discrepancy allowed in the conveyor speed before an error is sent. This option is available when **Absolute** is selected from the **Conveyor Speed Check Type drop-down list.**
Input Timeout (secs)	Enter a time interval in seconds, after which the input will be checked for errors. If an error is found, it will be sent to WebSentinel.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.5.6   Modify Settings | Global Settings | Fieldbus

Use the **Fieldbus** window to configure Fieldbus type communication between the scanner and Host, or, in a multi-sided layout, between several scanners and a Host.

To edit the Fieldbus settings:

1. In the tree menu under Modify Settings, navigate to **Global Settings | Fieldbus**.
    The Fieldbus window opens.

2. Enter the appropriate information in the form as described below:
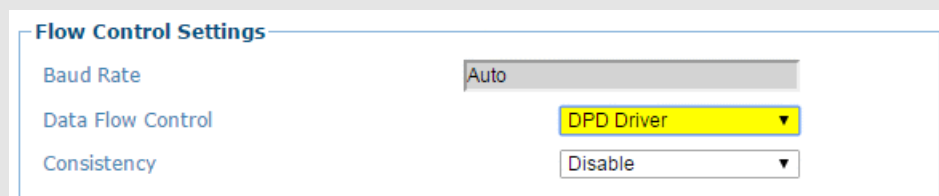
Field Name	Action/Definition
Type	Fieldbus type is displayed. When using the CBX510 with Fieldbus modules, select the correct Fieldbus Type. For SC5000, this option is preset and read-only based on the controller model used.
Data Tx	Select **Enable** or **Disable** from the drop-down list. If enabled, the fieldbus port is used by the scanner to transmit data and/or messages.
Heartbeat	Select **Disable, Enable Unconditioned**, or **Enable Conditioned** from the drop-down list. This parameter is available when the Data TX parameter is checked. It enables/disables the transmission of the Heartbeat message signaling that the device is still active. • Disable: The Heartbeat message is not transmitted • Enable Unconditioned: The Heartbeat message is always transmitted, even if communication is still active • Enable Conditioned: The Heartbeat message is transmitted only when there is no communication

Heartbeat Settings

Field Name	Action/Definition
Heartbeat Timeout	Enter a time value in seconds to define the amount of time between two message transmissions. If the input timeout expires and no transmission has occurred, the Heartbeat message will be transmitted.

Field Name	Action/Definition
Heartbeat Message (max. 32 chars)	Click ✎ to activate the Text Entry Tool and create heartbeat header text to signal the beginning of the heartbeat message. Characters from NUL (00H) to ~ (7EH) can be used. The Heartbeat Message (header) string must be different from the Heartbeat Terminator string.
Heartbeat Terminator (max. 32 chars)	Click ✎ to activate the Text Entry Tool and create Heartbeat Terminator text to signal the end of the heartbeat message. Characters from NUL (00H) to ~ (7EH) can be used. The Heartbeat Terminator string must be different from the Heartbeat Message (header) string.

Flow Control Settings
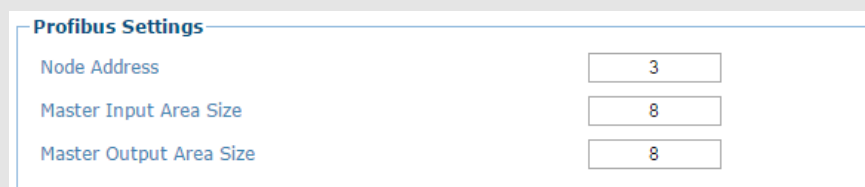
Baud Rate	This is a read-only parameter. The default value **Auto** allows the Host to control the data transmission speed of the Profibus network.
Data Flow Control	Select **Disable, DAD Driver,** or **DPD Driver** from the drop-down list. This implements a reliable transmission protocol between Fieldbus Master (PLC) and Fieldbus Slave (SC5000 or Scanner Master) allowing specific functions such as Synchronization, Fragmentation/Reassembling and Data Consistency.
Consistency	Select **Disable** or **Enable** from the drop-down list. This parameter is available only when the Data Flow Control parameter is set to DAD or DPD Driver. If enabled, it allows improving the overall communication robustness of the Fieldbus network.

Profibus Settings

Node Address	Enter a node value in the field provided, to define the value that distinguishes this node from all other nodes on the same link. Each node identifies a device within the network. Valid values are in the range 0 - 126. Node Address 126 forces the SSA (Set Station Address) service which allows the Fieldbus Master to assign the slave node address.
Master Input Area Size	Enter a value from 8 - 144 bytes to define the size of the message command sent from the Fieldbus module to the Fieldbus Master (Host). The default value is 8 bytes. The maximum Input + Output Area Size for the Profibus interface is 152 bytes.

Field Name	Action/Definition
Master Output Area Size	Enter a value from 8 – 144 bytes to define the size of the message command sent to the Fieldbus module from the Fieldbus Master (Host). The default value is 8 bytes. The maximum Input + Output Area Size for the Profibus interface is 152 bytes.

Profinet Settings

Master Input Area Size	Enter a value from 8 - 56 bytes to define the size of the message command sent from the Fieldbus module to the Fieldbus Master (Host). The default value is 8 bytes. The maximum Input + Output Area Size for the Profinet interface is 64 bytes.
Master Output Area Size	Enter a value from 8 – 56 bytes to define the size of the message command sent to the Fieldbus module from the Fieldbus Master (Host). The default value is 8 bytes. The maximum Input + Output Area Size for the Profinet interface is 64 bytes.
Station Name (max. 32 chars)	This string identifies the node on the network as an alternative to the IP address. If this value is changed by the host application during runtime, a reset is required in order for changes to have effect. The name can be made up only of letters or numbers. The **.** (dot) and **-** (dash) characters can be used but not as the first or last character in the name. The default name is Datalogic.
MAC Address	This is a read-only parameter. It displays the address of the Profinet channel reserved for internal communication.
MAC Address 1	This is a read-only parameter. It displays the address of one of the Profinet channels to be used for Host communication.
MAC Address 2	This is a read-only parameter. It displays the address of one of the Profinet channels to be used for Host communication.

Field Name	Action/Definition
Ethernet Bus Rate	This is a read-only parameter. The bus rate is set to Auto allowing the Host to manage the bus speed.
IP Addressing	**Static:** the IP Address can be set manually through the IP Address, IP Net Mask and IP Gateway parameters. **DHCP:** the IP address is assigned by a DHCP server. In this case the IP Address parameters are read-only and display the DHCP assigned address. **Remote:** the IP Address is assigned by a remote network device (PC) using an IPConfig address configuration application. In this case the IP address parameters are read-only and display the remotely assigned address.
IP Address	Enter the device Internet Protocol (IP) network address in the field provided. Consult your network administrator to obtain a new address.
IP Net Mask	Enter the device subnet mask address in the field provided. Consult your network administrator to obtain a new address.
IP Gateway	Enter the device gateway address in the field provided. Consult your network administrator to obtain a new address.

Digital Input Lines

Digital Input Lines	
Trigger (Input 1) Echo	Disable ▼
Aux (Input 3) Echo	Disable ▼
Phase Echo	Disable ▼

> **NOTE:** If any of the following parameters are enabled, the **Data Flow Control** DAD/DPD Driver starts at Byte 1 (second byte) of the Fieldbus Master Input Area, and Byte 0 (first byte) is reserved for these Digital Input Line Echo parameters.
>
> If none of the following parameters are enabled, the **Data Flow Control** DAD/DPD Driver starts at Byte 0 (first byte) of the Fieldbus Master Input Area.
>
> For more details, refer to the DAD/DPD Driver Reference Manual.

Trigger (Input 1) Echo	Select **Disable** or **Enable** from the drop-down list. If enabled, the Scanner Master or SC5000 Controller **Trigger (Input 1)** status is echoed to the Fieldbus Master via bit 0 in Byte 0 (first byte) of the Input Area.
Aux (Input 3) Echo	Select **Disable** or **Enable** from the drop-down list. If enabled, the Scanner Master or SC5000 Controller **Input 3** status is echoed to the Fieldbus Master via bit 2 in Byte 0 (first byte) of the Input Area.
Phase Echo	This parameter is configurable only if **Start Input from Bus** is enabled. Select **Disable** or **Enable** from the drop-down list. If enabled, the Reading Phase status is echoed to the Fieldbus Master via bit 7 in Byte 0 (first byte) of the Input Area.

Field Name	Action/Definition
Digital Output Lines	

	NOTE: If any of the following parameters are enabled, the **Data Flow Control** DAD/DPD Driver starts at Byte 1 (second byte) of the Fieldbus Master Output Area, and Byte 0 (first byte) is reserved for these Digital Output Line parameters.
	If none of the following parameters are enabled, the **Data Flow Control** DAD/DPD Driver starts at Byte 0 (first byte) of the Fieldbus Master Output Area.
	For more details, refer to the DAD/DPD Driver Reference Manual.
Control Output 1	This parameter is configurable only if **Digital Output 1 Use** is set to Profibus/Profinet. Select **Disable** or **Enable** from the drop-down list. If enabled, it allows the Fieldbus Master to drive the Scanner Master or SC5000 Controller **Output 1** via bit 0 in Byte 0 (first byte) of the Output Area.
Control Output 2	This parameter is configurable only if **Digital Output 2 Use** is set to Profibus/Profinet. Select **Disable** or **Enable** from the drop-down list. If enabled, it allows the Fieldbus Master to drive the Scanner Master or SC5000 Controller **Output 2** via bit 1 in Byte 0 (first byte) of the Output Area.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.5.7 Modify Settings | Global Settings | Messaging

Use the Messaging selections during initial setup to configure system messaging for your **DS8110/DX8210 barcode scanner**. If necessary, you can later make modifications to the configuration using the same menu selections, including:

- Messaging
  - Message Format
  - Message Builder
  - Statistics
  - Protocol Index
  - Pass-Thru
  - Diagnostics Messages
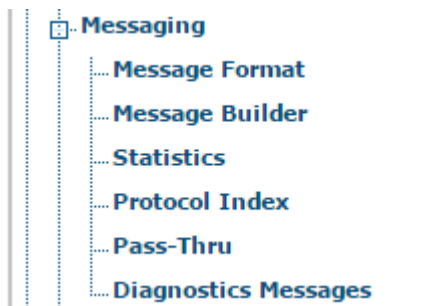
Modify Settings | Global Settings | Messaging | Message Format

Use the **Message Format** window to configure Standard or Advanced system messages.

To edit the Message Format settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Messaging | Message Format**. The **Message Format** window opens.

Messaging Formatting

Special Host Protocol	None
Message Format	Standard
Message Tx Selection	After Reading Phase C
Max. Tx Delay after Phase Off	100 msec
Header Tx Start	With Data
Termination After No Read Message	Enable

Standard Format

Header String (max. 128 chars)	<STX>
Termination String (max. 128 chars)	<CR><LF>
Data Packet Separators (max. 128 chars)	;
Code Position Tx	
Code Direction Identifier Enable	
Code Field Length Setting	Variable Length
Code Identifier	Disabled

Update All   Reset All   Reset Page

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Messaging Formatting	
Special Host Protocol	Select **None** or a specific custom protocol from the drop-down list. In some cases, a customer specific protocol may have been created. When selected, a group of options specific to that protocol are made available.
Crisplant Protocol	
Port to Use	Select **Aux Serial Port, Main Serial Port,** or a **User Socket** from the drop-down list.
Crisplant Device Type/Error Definition	Select **DLA Device/Errors** or a **ASI-Axiom/Errors** from the drop-down list. This allows selection of different device types, as the error codes required by Crisplant vary from device to device. **DLA Device/Errors:** select when using current Datalogic devices **ASI-Axiom/Errors:** Select when using legacy Accu-Sort devices
Crisplant Manufacturer ID	This field is determined by the **Crisplant Device Type/Error Definition** selected above and cannot be edited. This defines the "Scanner Identity" byte of the Error and Heartbeat messages of the Crisplant Protocol.
Heartbeat Message Enable	Select the check box to enable the transmission of the Heartbeat message.
Heartbeat Message Timing	Enter a value in milliseconds to define the amount of time between two code transmissions. If the selected timeout expires and no transmission has occurred, the Heartbeat message will be transmitted.
Crisplant Protocol Type	Select **CSC, CMC,** or **P10** from the drop-down list. This defines the type of Crisplant protocol to be used: **CSC:** the <CR><LF> characters do not appear at the end of transmitted/received telegrams **CMC:** the <CR><LF> characters appear at the end of transmitted/received telegrams **P10:** • the <CR><LF> characters appear at the end of transmitted/received telegrams • the Parameter Crisplant Manufacturer ID is forced to the Value 'a' (61H) and cannot be modified for this selection • the error messages are modified with respect to CSC and CMC protocols
Discard Read on Missing Index	Select the check box to enable. When selected, if a Missed Index error occurs, an empty telegram is sent to the Crisplant Host. If not selected, and a Missed Index error occurs, the telegram contains the codes that were read relative to the pack.

Field Name	Action/Definition

	Mettler Toledo Protocol
Conveyer Direction Input	Select **Trigger (Input 1)** or **Aux (Input 3)** from the drop-down list. The selection defines which digital input transmits information about the conveyor direction. The conveyor direction is Forward when the selected input is active (default active closed). If Input 1 is used the scanner Phase On LED also signals the direction state.
SW Divide Encoder Frequency	Select the check box to enable. If selected, the encoder frequency value is divided by two before it is transmitted to the Host. This parameter only effects the value contained in the <Encoder> field of the messages sent from the scanner to the Host.

	Message Definition	
	Header	Enter a message header in the field provided. A Header (up to 128 bytes) can be defined and transmitted as a block preceding all messages sent from the scanner. Character from NUL (00H) to ~ (7EH) can be used.
	Trailer	Enter a message trailer in the field provided. A Trailer (up to 128 bytes) can be defined and transmitted as a block following all messages sent from the scanner. Character from NUL (00H) to ~ (7EH) can be used.
	Heartbeat Enable	Select the check box to enable heartbeat.
	Heartbeat Timeout	Enter a value in milliseconds. This parameter is available when the Heartbeat parameter is enabled. It defines the amount of time between two message transmissions. If the selected timeout expires and no transmission has occurred, the Heartbeat message will be transmitted.
	Heartbeat Message	Click ✎ to activate the **Text Entry Tool** and create a heartbeat message in the field provided. This parameter is available only when the Heartbeat parameter is enabled. This defines the Heartbeat message.
		Click **Submit** to save your changes, or click **Cancel** to return to previous.

Field Name	Action/Definition
Code Field Length Setting	Select **Fixed Length** or **Variable Length** from the drop-down list. This parameter is applied only to the <Barcode> field contained in two specific messages (Barcode information and Diagnostics) of the protocol. The code field length (in number of characters/digits) can be specified in order to be transmitted: **Selections:** • **Variable: All possible code field lengths (in number of characters/digits) allowed for the code selected are accepted** • **Fixed: The code is entirely transmitted even if it is longer than the defined length. If shorter, it will be transmitted with the addition of the Fill Character.**
Data Justification	Select **Left** or **Right** from the drop-down list. This parameter is applied only to the <Barcode> field contained in two specific messages (Barcode information and Diagnostics) of the protocol. It is available when the **Code Field Length** Setting is set to **Fixed**. This defines the position of the Fill Character within the code: **Selections:** • **Left: Fill Character is left aligned and precedes the <Barcode> field** • **Right: Fill Character is right aligned and follows the <Barcode> field**
Code Field Length	Enter a length in the field provided. This parameter is applied only to the <Barcode> field contained in two specific messages (Barcode information and Diagnostics) of the protocol. It is available when the **Code Field Length** Setting is set to **Fixed**. This defines (in number of characters/digits) the length of the <Barcode> field to be transmitted in a value range from 0 to 48.
Fill Character	Click ✎ to activate the **Text Entry Tool** and create a fill character in the field provided. This parameter is applied only to the <Barcode> field contained in two specific messages (Barcode information and Diagnostics) of the protocol. It is available when the **Code Field Length** Setting is set to **Fixed**. The **Fill Character** is inserted into each character position of a code field that has more characters (as defined in the **Code Field Length**) than exist in the barcode read. A character from NUL (00H) to ~ (7EH) can be used. Click **Submit** to save your changes, or click **Cancel** to return to previous.

Field Name	Action/Definition	
	Add AIM Prefix	Select check box to enable. If enabled, it adds the AIM standard prefix to the barcode to be sent to the host. No separator character will be added between the AIM prefix and the barcode.
	AM/PM Behavior	Select the check box to enable. If enabled, the Host is ready to receive the following message: **<STX><COMMAND><ETX>** **where:** **<COMMAND>** = 'A' indicates that the Host starts working in AM mode / 'P' indicates that the Host starts working in PM (default) mode **When working in AM mode:** • **each code is only filtered by the Encoder Timeout parameter;** • **the Purolator Custom Check parameter is not effective;** • **the Heartbeat message will never be transmitted;** • **the transmitted message is not subject to padding with the Fill Character.** **and the output message format is the following:** **<STX><scanner_nr><space><barcode><ETX><CR><LF>** **where:** **<scanner_nr>** = 2-digit number in the range 00-31
	AM Message Target	**Select Main Serial Port, Aux Serial Port, or a User Socket from the drop-down list.**

Field Name	Action/Definition
	Multi-Tx Transport Disable	**This parameter manages the message transmission through the different communication channels.** **If unchecked (check box not selected), messages are transmitted through all the communication channels having the Data Tx parameter enabled.** **If checked (check box selected), messages are sent through all the communication channels having the Data Tx parameter enabled until the scanner receives one of the three possible communication messages (Status Request, Encoder Counter Request, Initialization Command). As soon as this condition occurs, all messages will be transmitted only through the specific channel sending one of the three possible communication messages while other channels are ignored. In this way, the last channel sending one of the possible communication messages will become the one used for transmission.**
	Spontaneous Status Message	**Select check box to enable. In case of diagnostic errors, this message is sent every 40 seconds.**
	Purolator Custom Check	**Select the check box to enable. If enabled, all service labels sharing the following characteristics will not be filtered by the Code Filter Depth and Encoder Timeout parameters:** • **all service labels containing 2 characters only (e.g. "F1", "F2", ecc);** • **all service labels of 8 characters starting with "ENP";** • **all service labels of 9 characters starting with "OSNR".**

Code Filter	
Enable UPS Code Filter	**Select the check box to enable. If selected, the UPS Code Filters, PTN Code Filters, and Postal Code Filters panels open.**

UPS Code Filters	
Tracking Label - Starts with '1Z'	**Select check box to enable. If selected, function allows the transmission of codes belonging to the Code 128 and Code 39 families starting with '1Z', '3Z', '1B' or '3B'. The length of these codes is 18 digits.**

Field Name	Action/Definition

	Service Upgrade Label - Starts with'403', Length is 8	Select check box to enable. If selected, function allows the transmission of codes belonging to the Code 128 and Code 39 families starting with '403'. The length of these codes is 8 digits.
	PTN Code Filters	
	Select all codes of PTN type, except codes below (that must be selected)	Select check box to enable. If selected, it is possible to transmit all Code 128 and Code 39 codes belonging to this type having a length of 11 digits with the exception of those starting with: - **'400', '420', '421', '51L', '52L', '54L', '55L'**
	Starts with...	Select each check box to enable/include that prefix.
	Postal Code Filters	
	Starts with...	Select each check box to enable/include that prefix. This allows the transmission of codes belonging to the Code 128 and Code 39 families having any of the following selected characteristics: • **starting with '420' and with length 8 or 12 digits** • **starting with '421' and with length from 6 to 15 digits** • **starting with '51L' and with length 8, 9 or 12 digits** • **starting with '52L' and with length 8, 9 or 12 digits** • **starting with '54L' and with length from 6 to 19 digits** • **starting with '55L' and with length from 6 to 19 digits**
Enable DPD Code Filter	Select the check box to enable the DPD Code Filters panel.The DPD Code Filters panel allows selection of the DPD code to be transmitted. All codes different from the selected DPD will also be transmitted.

Field Name	Action/Definition
Enable SSCC-18 Code Filter	**Select the check box to enable. If selected, only the GS1-128 code, type SSCC-18, of the Code 128 family is transmitted. All codes different from the GS1-128, type SSCC-18, will also be transmitted.**
Enable German Post 2/5 IL Code Filter	**Select the check box to enable. If selected, only the German Post codes of the 2/5 Interleaved code family are transmitted. All code families different from the 2/5 Interleaved will also be transmitted.**
Diagnostic Messages	**Select the check boxes as needed to enable. If selected, these parameters allow selecting the desired communication channel (Main, Aux, User Socket#n) to be used for transmitting barcode messages coming from slaves.** **The selection is available only if the desired communication channel is free (Data TX parameter disabled).** **The diagnostic data format can be defined through the commands provided by a terminal interface.**
Debug Messages	**Select the check boxes as needed to enable. If selected, these parameters allow selecting the desired communication channel (Main, Aux, User Socket#n) to be used for transmitting debug messages coming from slaves.** **The selection is available only if the desired communication channel is free (Data TX parameter disabled).**
DPD Code Filters	**If DPD Code Filter is enabled, the user can select the DPD code to be transmitted by selecting its check box. All codes different from the selected DPD will also be transmitted.** **This group allows selecting the DPD code type(s) to be transmitted. These codes belong to the Interleaved 2/5 or Code 128 family and have one of the following characteristics:** • **I2of5 Code, Length is 10** • **I2of5 Code, Length is 12** • **I2of5 Code, Starts with '0', Length is 4** • **I2of5 Code, starts with '90',Length is 4** • **Code 128, Length is 28** **All codes belonging to code families other than Interleaved 2/5 and Code 128 will be also transmitted.**

Field Name	Action/Definition
Message Format	Select <u>**Standard**</u> or <u>**Advanced**</u> from the Format Type drop-down list.
Message Tx Selection	Select **On Decoding** or **After Reading Phase Off** from the drop-down list. **Message Tx** selects the transmission of the output message on decoding or after the reading phase as illustrated below.

Data TX on decoding   Data TX after Reading Phase Off

NOTE: This option is only available when an **Operating Mode** of **On Line** is selected in **Modify Settings | Global Settings | Operating Mode.**

Max. Tx Delay after Phase Off	Select **Disabled** or a millisecond value (50 to 500 msec) from the drop-down list. This parameter defines a timeout, which is the maximum delay allowable for message transmission after the reading phase is closed. If this timeout expires before message transmission, the message will be discarded.

NOTE: This option is only available when an **Operating Mode** of **On Line** is selected in **Modify Settings | Global Settings | Operating Mode.**

Header Tx Start	**Select With Data** or **After Reading Phase On** from the drop-down list. If **With Data** is selected, the header will be transmitted with data. If **After Reading Phase On** is selected, the header will be transmitted after the reading phase activation. See illustration below:
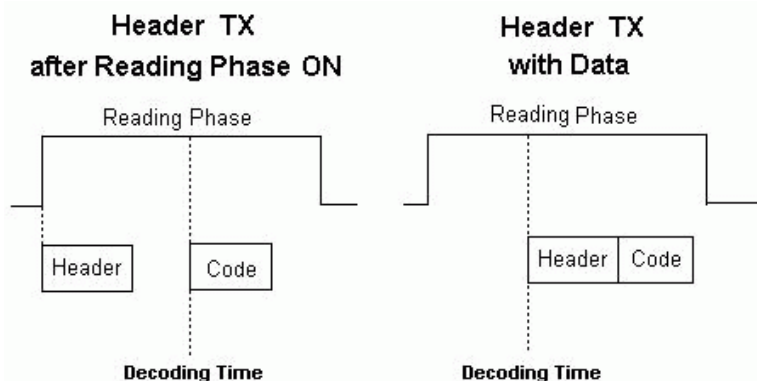
Header TX after Reading Phase ON   Header TX with Data

NOTE: This option is only available when an **Operating Mode** of **On Line** is selected in **Modify Settings | Global Settings | Operating Mode.**

Field Name	Action/Definition

Termination After No Read Message — Select **Enable** or **Disable** from the drop-down list. If **Enable** is selected, a termination string is added to the No Read message string.

> **NOTE:** This option is only available when an **Operating Mode** of **On Line** is selected in **Modify Settings | Global Settings | Operating Mode.**

Format Type: Standard

Header String — Click 🖉 to activate the **Text Entry Tool** and create a **Header String** in the text field provided. Headers (up to 128 bytes) can be defined and transmitted as a block preceding the barcode(s). Use characters from NUL (00H) to ~ (7EH).

Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Termination String — Click 🖉 to activate the **Text Entry Tool** and create a **Termination String** in the text field provided. Terminators (up to 128 bytes) can be defined and transmitted as a block following the barcode(s). Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Data Packet Separators — Click 🖉 to activate the **Text Entry Tool** and create a **Data Packet Separators** in the text field provided. The **Data Packet Separators** (up to 128 bytes) are used to separate barcodes in the reading phase. Use characters from NUL (00H) to ~ (7EH).

For this reason, it is very useful when the **Standard Multi Label, Code Collection or Code Combination** parameters have been selected in the **Barcode Configuration**. If selected, they occur within the **Code Field** and are transmitted after each decoded code.

Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Code Position Tx — Select the check box to enable. If enabled, the code position information is included in the output data format.

Code Direction Identifier Enable — Select the check box to enable. If enabled, it allows you to define the forward and reverse strings indicating the scanning direction with respect to the code direction.

Forward Direction String — Click 🖉 to activate the **Text Entry Tool** and create a **Forward Direction String** in the text field provided. A **Forward Direction String** can be included in the output message to indicate that the current code has been scanned in the forward direction (scanning from left to right).

This string ("+" is the default value) can be customized by the user including up to 32 characters.

Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Field Name	Action/Definition
Reverse Direction String (max. 32 chars)	Click ✎ to activate the **Text Entry Tool** and create a **Reverse Direction String** in the text field provided. A **Reverse Direction String** can be included in the output message to indicate that the current code has been scanned in the reverse direction (scanning from right to left). The string ("-" is the default value) can be customized by the user including up to 32 characters. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Unknown Direction String	Click ✎ to activate the **Text Entry Tool** and create an **Unknown Direction String** in the text field. An **Unknown Direction String** can be included in the output message when it is not possible to determine the scanning direction of a code. The string ("?" is the default value) can be customized by the user including up to 32 characters. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Code Field Length Setting	Select **Variable** or **Fixed** from the drop-down list. If **Variable** is chosen, all possible code field lengths (in number of characters/digits) allowed for the code selected are accepted. If **Fixed** is chosen, only the length defined by the Code Field Length parameter is accepted.
Code Field Length	This parameter is only available when **Fixed** is selected as the **Code Field Length Setting**. Enter length of the code field to be transmitted (in number of characters/digits) in the field provided.
Data Justification	This parameter is only available when **Fixed** is selected as the **Code Field Length Setting**. Select **Left** or **Right** from the drop-down list to define the position of the Fill Character within the code.
Fill Character	This parameter is only available when **Fixed** is selected as the **Code Field Length** Setting. Click ✎ to activate the **Text Entry Tool** and create a **Fill Character(s).** The **Fill Character** is inserted into each character position of a code field that has more characters (as defined in the **Code Field Length**) than exist in the barcode read. Use characters from NUL (00H) to ~ (7EH). **Example:** For barcode "12345" with Fill Character "-" (2DH) and Code Field Length of 10 characters, the result of the different alignment will be: Left aligned = ...<Code Identifier><12345----->... Right aligned = ...<Code Identifier><-----12345>... Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Field Name	Action/Definition
Code Identifier	Select **Disable, Standard AIM ID,** or **User Specified** from the drop-down list. A **Code Identifier** string can be included in the output message. • If **Disable** is selected, no code identifier is included in the output message. • If **Standard AIM ID** is selected, the AIM standard identifier is included in the output message • If **User Specified** is selected, the **Code Identifier Strings** group is activated at the bottom of the window, allowing you to define an identifier string for each code symbology. The string will be included in the output message.

Code Identifier Strings

This section of the Message Format window is only available when **User Specified** is

selected as the **Code Identifier**. Click ✎ to activate the Text Entry Tool and create a custom code identifier string for any listed code symbology. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Field Name	Action/Definition
	Format Type: Advanced

Select a Message Number to Modify	Select a numbered message you wish to modify from the drop-down list.

	Advanced Format: Message Definition _n_
Message Destination	Select the check box for each port or socket that should receive the message.
Message Destination Bitmap	Indicates the destination of the message.
Message Alignment	Select **None, Left,** or **Right** from the drop-down list.
Align Length	Enter the number of characters by which to extend the message when **Left** or **Right** is selected from the **Message Alignment** drop-down box.

Field Name	Action/Definition
Align Filler Char	Click ✎ to activate the **Text Entry Tool** and create a filler character in the text field provided. This filler is used to extend the **Align Length**.
Header	Click ✎ to activate the **Text Entry Tool** and create a **Header** in the text field provided. Headers (up to 128 bytes) can be defined and transmitted as a block preceding the barcode(s). Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Terminator	Click ✎ to activate the Text Entry Tool and create a **Terminator** in the text field provided. Terminators (up to 128 bytes) can be defined and transmitted as a block following the barcode(s). Use characters from **NUL** (00H) to **~** (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Message Location for Global No Read	Select **Only No Read Message, Before No Read Message,** or **After No Read Message** from the drop-down list.
Global Scale Type (Units)	Select **Metric (mm)** or **Imperial (0.1 in)** from the drop-down list.
Code Identifier	Select **Disable, AIM,** or **Custom** from the drop-down list. A **Code Identifier** string can be included in the output message. • If **Disable** is selected, no code identifier is included in the output message. • If **AIM** is selected, the AIM standard identifier is included in the output message • If **Custom** is selected, the **Code Identifier Strings** group is activated at the bottom of the window, allowing you to define an identifier string for each code symbology. The string will be included in the output message. **Code Identifier Strings** This section of the Message Format window is only available when **Custom** is selected as the **Code Identifier**. Click ✎ to activate the **Text Entry Tool** and create a custom code identifier string for any listed code symbology. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Modify Settings | Global Settings | Messaging | Message Builder

Use the **Message Builder** window to create Standard or Advanced system messages.

To use the Message Builder:

1. In the tree menu under Modify Settings, navigate to **Global Settings | Messaging | Message Builder**. The **Message Builder** window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Message Number to Modify	Select the number of the message you want to modify from the drop-down list.
Message *n* Item List	
Idx	Displays the index number of the messages.
Type	Displays the message type including various **Text String, Code Related Item, or Package Related** Item messages.
Qualifier	Displays relevant qualifiers for the message item if needed.
Add	Click to add a message item to the bottom of the list.
Add before	Click to add a message item above the currently selected message.
Add after	Click to add a message item below the currently selected message.

Field Name	Action/Definition
Move up	Click to move the selected message item up one level in the list.
Move down	Click to move the selected message item down one level in the list.
Remove	Click to remove the selected message item.

Item n Definition	
Item Type	Select **Text String, Code Related Item,** or **Package Related Item** from the drop-down list. Each selection reveals a unique set of options.
String Field	Click ✎ to activate the **Text Entry Tool** and create a text string message. This option is available when Item **Type > Text String** has been selected. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Code Related Items	Select a code related item from those available in the drop-down list. This option is available when Item **Type > Code Related Item** has been selected. The **Code Related Items** can be associated to a specific programmed code or group label depending on the Code Combination selection. **Selections Include:** • **Barcode:** Barcode data • **Barcode Length:** Number of characters in code • **Read Bitmap:** 32-bit mask indicating which scanner in the network has read the code (when character <1> is present in the related position) • **Total Read Count:** Indicates how many times the code has been read by all scanners present in the network during the same reading phase • **Read Count (by device):** Indicates the number of times the code has been read by one specific scanner present in the network during the reading phase (selectable among those present) • **X Position:** X coordinate for the code that was read • **Y Position:** Y coordinate for the code that was read • **Z Position:** Z coordinate for the code that was read • **Code Identifier:** Indicates type of code that was read • **Code Direction:** Indicates if the code has been read either from either the start character or the stop character • **Code Distance:** Indicates the distance to the code that was read • **Decode Mode:** Indicates if the code has been read using Linear or Reconstruction (ACR) reading mode

Field Name	Action/Definition
	• **Decode Scans Number:** Indicates the minimum number of decoded scans referred to the single characters in a code when the device is reading in Reconstruction mode. This Item can be used as Code Quality Index
	• **Average Code Position:** Average position of the code in the scan line (Average of Minimum and Maximum Code Position)
	• **Minimum Code Position:** Minimum position of the code in the scan line (closest to the left side/connector side of the scanner)
	• **Maximum Code Position:** Maximum position of the code in the scan line (farthest from the left side/connector side of the scanner)
	• **Ink Spread:** Indicates the calculated Ink Spread value
	• **Encoder Value:** Indicates the encoder/tachometer pulse value from trigger to the code being read
	• **Laser Number:** If more than one laser is present in the working device, this item indicates the laser used to read the code
	• **Reading Persistence:** Indicates how many times the laser beam has crossed the complete code during the reading phase
Package Related Item	Select a package related item from those available in the drop-down list. This option is available when Item Type > Package Related Item has been selected. **Selections Include:** • **Package Sequence Number:** Indicates the sequential number assigned to the package. • **Total Read Bitmap:** Indicates the complete reading mask related to all codes read during the reading phase • **Failure Bitmap:** 32-bit mask indicating which devices in the network are in fault (when character <1> is present in the related position) • **Total Read Count:** Indicates the sum of all Code-related Total Reading Counts of each code read during the reading phase • **Read Count (by device):** Indicates the number of codes read during the reading phase by the device • **Minimum Code Distance:** Indicates the distance of the code closest to the device read during the reading phase • **Maximum Code Distance:** Indicates the distance of the code most distant from the scanner that has been read during the reading phase • **Decode Mode (Master):** Indicates the programmed Reading Mode, either Linear or Reconstruction • **Number of Rejected Codes:** Indicates the number of codes rejected during the internal analysis (unexpected code, multiple read, discarded by the programmed logical rule)

Field Name	Action/Definition
	• **Package Length:** Indicates the approximate length of the package
	• **Start Trigger Encoder Value:** Indicates the encoder/tachometer pulse value when the package first hits the trigger PS
	• **End Trigger Encoder Value:** Indicates the encoder/tachometer pulse value when the package exits the trigger PS
	• **Transmit Encoder Value:** Indicates the encoder/tachometer pulse value when the data transmit occurs
	• **Current Trigger Count:** Indicates the number of trigger cycles that have occurred
	• **Working Hours (By Device):** Indicates the total number of hours the device has been active
	• **Total Good Reads:** Indicates the total number of barcodes successfully read
	• **Total No Reads:** Indicates the total number of barcodes that were not read
	• **Total Multi Reads:** Indicates the number of times packages carried more codes than the scanner is programed to read
	• **Total Partial Reads:** Indicates the total number of barcodes only partially read
	• **Protocol Index:** Indicates the programmed protocol index string data
Code/Group Selection	Select a Code/Group from those available in the drop-down list. This option is available when Item **Type > Code Related Item** has been selected.
Device Index	Select a device index number from the drop-down list. This option is available when Item **Type > Code Related Item > Read Count (By Device)** or **Type > Package Related Items > Read Count (By Device)/Working Hours (By Device)** has been selected.
Text String: Options	
Link to Code	Select **Disabled, Previous Code,** or **Next Code** from the drop-down list. • **Disabled:** A code will not be linked to this text string • **Previous Code**: The text string will be linked to the previous generated code • **Next Code:** The text string will be linked to the next generated code
Package Related Item: Options	
Item Alignment	Select **None, Left,** or **Right** from the drop-down list.
Item Alignment Length	Enter an **Item Alignment Length** in the field provided.
Item Alignment Filler	Click 🖉 to activate the **Text Entry Tool** and create filler text. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Item Data Size	Select **Variable** or a number of digits to use from the drop-down list.

Field Name	Action/Definition
Item Data Format	Select **Decimal (ASCII), Hexadecimal (ASCII), Bitmap (ASCII),** or **Numeric (Binary)** from the drop-down list.

Code Related Item: Options	
Code Cutting	Select None, Simple, or Pattern from the drop-down list. **Selections:** • **Simple:** Allows cutting a programmable part of the code either at the beginning or at the end of the code. • **Pattern:** Allows cutting a part of the code according to a particular prefixed pattern.
Number of Leading Chars to Cut	Enter the number of leading characters to cut from the barcode in the field provided (available when **Simple** is selected from the **Code Cutting** drop-down list).
Number of Trailing Chars to Cut	Enter the number of trailing characters to cut from the barcode in the field provided (available when **Simple** is selected from the **Code Cutting** drop-down list).
Pattern Delimiting Chars to Cut	Enter the pattern delimiting characters in the field provided (available when **Pattern** is selected from the **Code Cutting** drop-down list).
Pattern Mode	Select Keep Before, Keep After, or Keep Middle from the drop-down list (available when Pattern is selected from the Code Cutting drop-down list). **Selections:** • **Keep Before:** Cuts the part of the code that starts with the pattern string (databefore the string remains). • **Keep After:** Cuts the part of the code that precedes and includes the pattern string (data after the string remains). • **Keep Middle:** Cuts the part of the code before and after (including) the two pattern strings (data between the two strings remains) **Example:**

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Field Name	Action/Definition
	Referring to the window image above, if the read code is SDFR**123**5689**123**ASER the transmitted code (depending on the selected Pattern Mode) will be: • **Keep Before:** SDFR • **Keep After:** 5689123ASER • **Keep Middle:** 5689
Item Alignment Filler	Click ✎ to activate the **Text Entry Tool** and create filler text. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Item Data Size	Select **Variable** or a number of digits to use from the drop-down list.
Item Data Format	Select **Decimal (ASCII), Hexadecimal (ASCII), Bitmap (ASCII),** or **Numeric (Binary)** from the drop-down list.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Modify Settings | Global Settings | Messaging | Statistics

Use the **Statistics** window to select the desired statistical counters, making up the statistics field, and relative statistics field separator string to be sent to the system by the Stand Alone or Master scanner.

To edit the Statistics settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Messaging | Statistics**. The Statistics window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Enable	Select the check box to reveal and edit statistic message options. The selections correspond to the message as shown below:

Separator	Click ✎ to activate the **Text Entry Tool** and create a **Separator** in the text field provided. **Separator** strings (up to 32 bytes) can be created and will be inserted between the last item in the *Data* field and the first item in the *Statistics* field.

> **NOTE:** A fixed <space> character separates all items within the Statistics field.

Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Field Name	Action/Definition
Time	Select the check box to include the time counter in the statistical message, reporting the time elapsed in hours and minutes (H MM) from the last hardware reset.
Trigger Counter	Select the check box to reports the total number of trigger sessions (reading phases) from the last hardware reset.
Good Read Counter	Select the check box to report the total number of good reads from the last hardware reset.
No Read Counter	Select the check box to report the total number of no reads from the last hardware reset.
Multiple Read Counter	Select the check box to report the total number of multiple reads from the last hardware reset.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Modify Settings | Global Settings | Messaging | Protocol Index

Use the **Protocol Index** window to configure Protocol Index parameters. Protocol Index allows the Host to transmit a string that it has associated to a pack contained within the tracking area.

It is possible to manage several different Protocol Index messages (one per available communication interface), within the same reading phase (for the same pack). If more than one Index message is received on the <u>same</u> communication interface, only the last one will be accepted.

These strings will be received by the DS8110/DX8210 Master or SC5000 and included within its output message according to the following order:

1. Built-In Ethernet User Socket 1
2. Built-In Ethernet User Socket 2
3. Built-In Ethernet User Socket 3
4. Auxiliary Serial Port
5. Main Serial Port

The general output format is: <Header>Index1<Data Packet Separator>...IndexN<Data Packet Separator>Standard Message<Terminator>

The Index field has the following format: <Index Header>Index Message<Index Terminator>

> **NOTE:** This parameter is only available for scanners configured as **Standalone** or as **Master** when working in **On Line** or **PackTrack** operating modes.
>
> In **On Line** mode, the Protocol Index must arrive during the active reading phase otherwise it will be discarded.
>
> - If the Distance from Protocol Index to Trigger Line parameter = 0, the Protocol Index must arrive during the active reading phase otherwise it will be discarded.
>
> In **PackTrack** mode:
>
> - If the Distance from Protocol Index to Trigger Line parameter is not = 0, the Protocol Index will arrive at the specified distance.

To edit the Protocol Index settings:

1. In the tree menu under Modify Settings, navigate to Global Settings | Messaging | Protocol Index. The Protocol Index window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Protocol Index/ Aux Message Enable	Select the check box to reveal and edit **Protocol Index/Aux Message** options.
Receive on (com channel)	Select **Disable, Enable without Request Message,** or **Enable with Request Message** from the drop-down list.
	• **Disable:** The selected communication channel is not used for Protocol Index string communication.
	• **Enable without Request Message:** The Host sends the Protocol Index string autonomously on the selected communication channel.
	• **Enable with Request Message:** The Host waits for the Protocol Index Request Message sent by the scanner, when the trigger detects the presence of a pack, before transmitting the Protocol Index string associated to the pack itself on the selected communication channel.
Request Message	Click ✎ to activate the **Text Entry Tool** and create a Request Message (up to 128 bytes) to be defined and transmitted. Use characters from NUL (00H) to ~ (7EH). Click Submit to save your changes, or click Cancel to return to previous window.
Message Header	Click ✎ to activate the **Text Entry Tool** and create a **Header** (up to 128 bytes) to be defined and transmitted as a block preceding the **Protocol Index** string sent by the Host. Use characters from NUL (00H) to ~ (7EH).

Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text. |

Field Name	Action/Definition
Message Terminator	Click ✎ to activate the **Text Entry Tool** and create a **Terminator** to be defined and transmitted as a block following the Protocol Index string sent by the Host. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Message Length	Select **Length in Message**, **Variable Length**, or a length of **3** through **12** from the drop-down list. • **Length in Message:** The first byte of the scanner output message indicates the length of the Protocol Index string sent by the Host. • **Variable Length:** The length of the Protocol Index string sent by the Host is variable. • **3...12:** The Protocol Index string has a fixed length from 3 to 12 characters.
No Index/Message Character	Click ✎ to activate the **Text Entry Tool** and create a **No Index Char.** Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Distance from Message Receipt to Trigger	Enter the distance of travel between when a package hits the trigger (presence sensor) to when it should receive an expected message from, for example, a scale or other device. When the Receive on Main Serial Port parameter of the selected interface port is set to Enable without Request Message, this parameter specifies the distance from the Trigger Line (i.e. Presence Sensor) to the expected receiving point of the Protocol Index/Aux Message. If set to 0 the Protocol Index/Aux Message must arrive during the active reading phase otherwise it will be discarded.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Modify Settings | Global Settings | Messaging | Pass-Thru

Use the **Pass-Thru** window to pass a message received on ANY port (serial or user socket connection) to any other port(s).

Applications can also be implemented to connect a device such as a hand-held reader to any serial or network port for additional manual code reading capability.

When using Pass-Thru mode, follow these programming notes:

- When using serial ports - Program receiving port same way regarding baud rate, data bits, stop bits and parity to the device sending the data.

- The Termination string must be configured in the same way as the message terminator on the device sending the data. The terminator will be forwarded with the message.

To edit the Pass-Thru settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Messaging | Pass-Thru**. The Pass-Thru window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Source	Select the check box(es) following the **Main Serial Port, Aux Serial Port,** or numbered **User Socket** you wish to modify.
String Length	Enter the maximum length of the expected string to be received. If the string is longer than the one expected, it will be discarded.
Termination String	Click ✏ to activate the Text Entry Tool to define the characters terminating the expected string. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Destination	Select the check box next to the destination(s) to be used for the Pass-Thru.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

Modify Settings | Global Settings | Messaging | Diagnostics Messages

Use the **Diagnostic Message** window to select the parameters managing diagnostic message transmission by the **Stand Alone** or **Master** scanner.

To edit the Diagnostic Message settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Messaging | Diagnostic Message**. The Diagnostic Message window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Transmit Mode	Select **On Timeout** or **With Code** from the drop-down list. The diagnostic message can be transmitted to the system by the **Stand Alone** or **Master** barcode scanner either asynchronously (at programmed intervals), or synchronously with the code.
Tx Refresh	Select a **TX Refresh** rate in seconds or minutes from the drop-down list to define the time interval in which the diagnostic messages will be transmitted if **Tx Mode** is asynchronous (On Timeout).

Field Name	Action/Definition
Message Position	Select **Append to Code** or **Replace Code** from the drop-down list. If **Transmit Mode** is synchronous (With Code), the diagnostic messages will be transmitted on the same interface used for code transmission. This selection determines if the messages will replace the code or be appended to it.

Error Messages

| Transmit Mode | With Code ▼ |
| Message Position | Append to Code ▼ |

Message Format	
Header String	Click ✎ to activate the **Text Entry Tool** to define the header string (up to 128 characters) as a block preceding the diagnostic message. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Terminator String	Click ✎ to activate the **Text Entry Tool** to define the terminator string (up to 128 characters) as a block following the diagnostic message. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Error Message Type	Select **Numeric** or **Global String** from the drop-down list to define how the message will be sent.
Global String (max. 32 chars)	Click ✎ to activate the **Text Entry Tool** to define the **Global String** message (up to 32 bytes) that will be sent as a diagnostic message for any detected diagnostic error. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Destination	Select the check box next to the destination(s) to be used for the diagnostic messages.
PackTrack Messages	
PackTrack Debug Message Enable	Select the checkbox to enable debug messages for PackTrack. If selected, this parameter allows transmitting messages concerning the system functioning.
PackTrack Debug Message Port	Select **Main Serial, Aux Serial,** or **Socket *n*** from the drop-down list. The debug message will be transmitted through the selected port.
PackTrack Debug Message Digital Input	Select **None, Trigger (Input 1), Aux (Input 3),** or **I/O 4 (Input 4)** from the drop-down list. This selection defines which digital input will be used to trigger debug message transmission.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.5.8 Modify Settings | Global Settings | Digital I/O

Use the **Digital I/O** window to configure the digital inputs and outputs for your barcode scanning system.

To edit the Digital I/O settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Digital I/O**. The Digital I/O window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Digital Input Lines	
Trigger (Input 1) Active Level	Select **Active Closed** or **Active Open** from the drop-down list. • **Active Closed:** Input 1 is active when current flows through (IN1) EXT_TRIG pins. • **Active Open:** Input 1 is active when there is no current flowing through (IN1) EXT_TRIG pins. **NOTE:** This parameter setting is not valid, if the input has already been defined in **On Line** or **PackTrack Operating Modes**.

Field Name	Action/Definition
Aux (Input 3) Active Level	Select **Active Closed** or **Active Open** from the drop-down list. • **Active Closed:** Input 3 is active when current flows through IN3 pins. • **Active Open:** Input 3 is active when there is no current flowing through IN3 pins. **NOTE:** This parameter setting is not valid, if the input has already been defined in **On Line** or **PackTrack Operating Modes**.

	Digital Output Lines
Select Digital Output Number to View/ Modify	Select the number of the output you will view or modify from the drop-down list.

	Digital Output *n*
Digital Output *n* Use	Select **Local, EthernetIP,** or **Profibus/Profinet** from the drop-down list. This parameter selects the source that drives the digital output. Local output is driven by the device application program. EithernetIP is driven by the EtherNet/IP Host and Profibus/Profinet is driven by the relative Fieldbus Host.
Digital Output *n* Line State	Select **Normally Open** or **Normally Closed** from the drop-down list. Each output can be represented with an **NPN** transistor; this transistor acts like a switch: so, when the transistor is **OFF**, it acts like an **OPEN** switch. On the contrary, when the transistor is **ON**, it acts like a **CLOSED** switch. • **Normally Open:** The idle state of the output line is open, that is, the **NPN** transistor is **OFF** (like an open switch).When the output is activated, the transistor goes **ON** (like a closed switch). • **Normally Closed:** The idle state of the output line is closed, that is, the **NPN** transistor is **ON** (like a closed switch).When the output is activated, the transistor goes **OFF** (like an open switch).

		Activation
	Primary Activation Event	Select a **Primary Activation Event** from the drop-down list (see below). • **None:** The output is always in line state. • **Complete Read**: The event occurs, if all selected codes are read. • **Partial Read:** The event occurs, if less than the selected codes are read. • **No Read:** The event occurs, if no code is read. • **Trigger On:** The event occurs, when a start event takes place starting the reading phase. • **Trigger Off:** The event occurs, when a stop event takes place ending the reading phase. • **Multiple Read:** The event occurs, if a code is read more than once consecutively. • **Right/Match:** The event occurs, if a code is successfully decoded and matches the Match Code (Verifier Code). • **Wrong/No Match:** The event occurs, if a code is successfully decoded but does not match the Match Code (Verifier Code).

Field Name	Action/Definition
Secondary Activation Event	Select a **Secondary (Alternate) Activation Event** from the drop-down list (see below). • **None:** The output is always in line state. • **Complete Read:** The event occurs, if all selected codes are read. • **Partial Read:** The event occurs, if less than the selected codes are read. • **No Read:** The event occurs, if no code is read. • **Trigger On:** The event occurs, when a start event takes place starting the reading phase. • **Trigger Off:** The event occurs, when a stop event takes place ending the reading phase. • **Multiple Read:** The event occurs, if a code is read more than once consecutively. • **Right/Match:** The event occurs, if a code is successfully decoded and matches the Match Code (Verifier Code). • **Wrong/No Match:** The event occurs, if a code is successfully decoded but does not match the Match Code (Verifier Code).
Activate On Error	Select **Disable** or **Enable** from the drop-down list. If this parameter is enabled, the output will activate when a diagnostic error message is sent. **NOTE:** When using this parameter, all other activation events should be set to **None**.
Deactivation	
Primary Deactivation Event	Select a **Primary Deactivation Event** from the drop-down list (see below). • **None:** A deactivation event is NOT defined. • **Timeout:** Indicates the maximum duration of the output pulse. When selected, the Deactivation Timeout text field is revealed. • **Trigger On:** The event occurs, when a start event takes place starting the reading phase. • **Trigger Off:** The event occurs, when a stop event takes place terminating the reading phase.
Secondary Deactivation Event	Select a **Secondary (Alternate) Deactivation Event** from the drop-down list (see below). • **None:** A secondary deactivation event is NOT defined. • **Trigger On:** The event occurs, when a start event takes place starting the reading phase. • **Trigger Off:** The event occurs, when a stop event takes place terminating the reading phase.
Deactivate On Clear Error	Select **Disable** or **Enable** from the drop-down list. If this parameter is enabled, the output will deactivate when the error is no longer present.
Deactivation Timeout	Enter the maximum duration of the output pulse in the text field provided. Input a value from **40** to **15000 milliseconds.**

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.5.9 Modify Settings | Global Settings | Diagnostics

Use the **Diagnostics** window to configure error reporting for your barcode scanning system.

To edit the Diagnostics settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Diagnostics**. The Diagnostics window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Sampling Time	Select a **Sampling Time** in seconds or minutes from the drop-down list. This selection indicates the time lapse between system diagnostic queries.
Report Slave Scanner Diagnostics	Select the check box to report diagnostic information from the slave scanners in the system.
Errors To Report	Select the check box next to each error type the system should report.
Presence Sensor Failure	Select the check box to report presence sensor failure errors.
Presence Sensor Stuck Timeout	Select a Disable or a time interval in seconds or minutes from the drop-down list.
No Phase Timeout	Select Disable or a time interval in seconds or minutes from the drop-down list. If a time interval is selected, a stuck sensor will report an error after the selected interval.
Protocol Index Alarms	Select the check box to enable protocol index alarm messages.

Field Name	Action/Definition
Maximum Consecutive Lost Protocol Indexes	Enter the number of consecutive lost protocol indexes allowed before an error is reported.
Maximum % Of Lost Protocol Indexes	Enter the maximum percentage of lost protocol indexes allowed before an error is reported.
PTP Time Synchronization Failure	Select the check box to report PTP (Precision Time Protocol) Time Synchronization Errors.
Encoder Failure	Select the check box to report encoder (tachometer) errors.
Encoder Timeout	Select Disable or a time interval in seconds or minutes from the drop-down list. If a time interval is selected, a stuck encoder will report an error after the selected interval.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

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4.5.10 Modify Settings | Global Settings | Energy Saving

Use the **Energy Saving** window to activating/deactivate energy saving feature. In particular, it allows turning network scanner motors and lasers on or off according to specific conditions. It is suggested to use this parameter for example when the conveyor is stopped for a lengthy period.

To view and edit the Energy Saving settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | Energy Saving**. The **Energy Saving** window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
Energy Saving Configuration	Select the check box to reveal **Energy Saving Configuration** options.
Use Encoder For	Select None, Deactivation, Activation, or Activation and Deactivation from the drop-down list. This parameter allows defining the function to be performed by an Encoder: • **None:** No function is performed by the digital input. • **Deactivation:** The digital input is used to deactivate the Energy Saving. Thus, the motor and laser of all network scanners will be turned on.

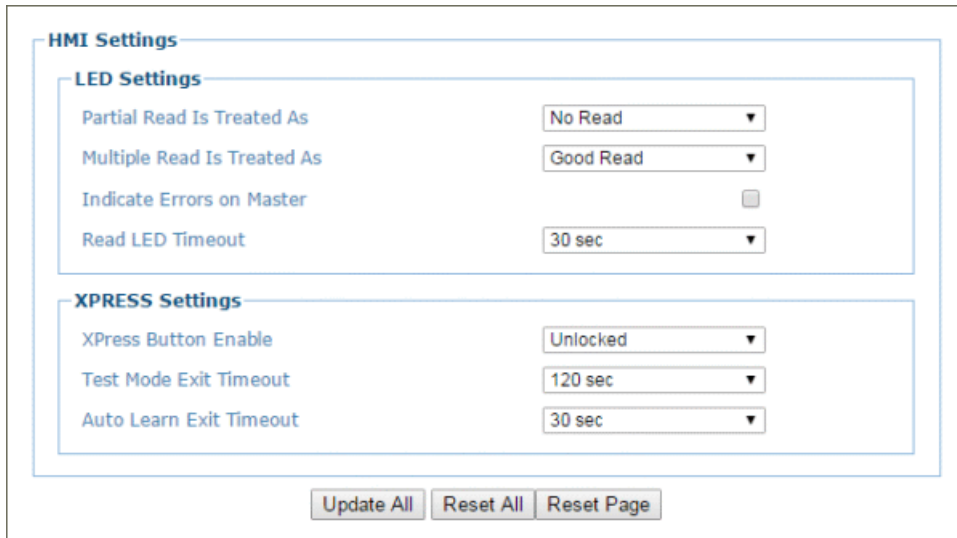| Field Name	Action/Definition
	• **Activation:** The digital input is used to activate the Energy Saving. Thus, the motor and laser of all network scanners will be turned off. • **Activation and Deactivation:** The digital input is used to both activate and deactivate the Energy Saving. Thus, the motor and laser of all network scanners will be turned on/off.
Activation Encoder Timeout	Select a minute value from the drop-down list. This parameter is available only when the encoder is used for the Energy Saving activation. If the encoder is stopped for more than the programmed timeout, the Energy Saving will be activated.
Deactivation Encoder Timeout	Select a second or minute value from the drop-down list. This parameter is available only when the encoder is used for the Energy Saving deactivation. If the encoder runs for at least the programmed timeout, the Energy Saving will be deactivated.
Use Digital Input For	Select **None, Deactivation, Activation,** or **Activation and Deactivation** from the drop-down list. This parameter allows defining the function to be performed by a digital input: • **None:** No function is performed by the digital input. • **Deactivation:** The digital input is used to deactivate the Energy Saving. Thus, the motor and laser of all network scanners will be turned on. • **Activation:** The digital input is used to activate the Energy Saving. Thus, the motor and laser of all network scanners will be turned off. • **Activation and Deactivation:** The digital input is used to both activate and deactivate the Energy Saving. Thus, the motor and laser of all network scanners will be turned on/off.
Select Digital Input	Select a digital input from the drop-down list. This parameter defines the digital input to be used for activating/deactivating the Energy Saving.
Select Input Type	Select **Edge** or **Level** from the drop-down list.
Use Main Serial Port For	Select **None, Deactivation, Activation,** or **Activation and Deactivation** from the drop-down list. This parameter allows defining the function to be performed by Main Serial Port: • **None:** No function is performed by the digital input. • **Deactivation:** The digital input is used to deactivate the Energy Saving. Thus, the motor and laser of all network scanners will be turned on. • **Activation:** The digital input is used to activate the Energy Saving. Thus, the motor and laser of all network scanners will be turned off. • **Activation and Deactivation:** The digital input is used to both activate and deactivate the Energy Saving. Thus, the motor and laser of all network scanners will be turned on/off
Header	**NOTE:** This parameter is available only when a communication channel has been selected to perform a specific function. Click ✎ to activate the **Text Entry Tool** and create a **Header** (up to 128 bytes) to define a header (1 byte) and transmit it as a block preceding the activation/deactivation string sent to a Master or Stand Alone scanner. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Field Name	Action/Definition
Terminator	**NOTE:** This parameter is available only when a communication channel has been selected to perform a specific function. Click ✎ to activate the **Text Entry Tool** and create a **Terminator** to define a terminator (1 byte) and transmit it as a block following the activation/deactivation string sent to the Master or Stand Alone scanner. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Activation String	**NOTE:** This parameter is available only when a communication channel has been selected to perform the Activation or Activation & Deactivation function. Click ✎ to activate the **Text Entry Tool** and create a string that defines the characters to be transmitted within the output message to activate the **Energy Saving**. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Deactivation String	**NOTE:** This parameter is available only when a communication channel has been selected to perform the Deactivation or Activation & Deactivation function. Click ✎ to activate the **Text Entry Tool** and create a character string to be transmitted within the output message to deactivate the **Energy Saving**. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Use Aux Serial Port For	Select **None, Deactivation, Activation,** or **Activation and Deactivation** from the drop-down list. This parameter allows defining the function to be performed by the Aux Serial Port: • **None:** No function is performed by the digital input. • **Deactivation:** The digital input is used to deactivate the Energy Saving. Thus, the motor and laser of all network scanners will be turned on. • **Activation:** The digital input is used to activate the Energy Saving. Thus, the motor and laser of all network scanners will be turned off. • **Activation and Deactivation:** The digital input is used to both activate and deactivate the Energy Saving. Thus, the motor and laser of all network scanners will be turned on/off.
Header	**NOTE:** This parameter is available only when a communication channel has been selected to perform a specific function. Click ✎ to activate the **Text Entry Tool** and create a **Header** (up to 128 bytes) to define a header (1 byte) and transmit it as a block preceding the activation/deactivation string sent to a Master or Stand Alone scanner. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Terminator	**NOTE:** This parameter is available only when a communication channel has been selected to perform a specific function. Click ✎ to activate the **Text Entry Tool** and create a Terminator to define a terminator (1 byte) and transmit it as a block following the activation/deactivation string sent to the Master or Stand Alone scanner. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Field Name	Action/Definition
Activation String	**NOTE:** This parameter is available only when a communication channel has been selected to perform the **Activation** or **Activation and Deactivation** function. Click ✎ to activate the **Text Entry Tool** and create a string that defines the characters to be transmitted within the output message to activate the Energy Saving. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Deactivation String	**NOTE:** This parameter is available only when a communication channel has been selected to perform the **Deactivation** or **Activation and Deactivation** function. Click ✎ to activate the **Text Entry Tool** and create a character string to be transmitted within the output message to deactivate the Energy Saving. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
User Socket _n_ For	Select **None, Deactivation, Activation,** or **Activation and Deactivation** from the drop-down list. This parameter allows defining the function to be performed by a numbered **Socket**: • **None:** No function is performed by the digital input. • **Deactivation**: The digital input is used to deactivate the Energy Saving. Thus, the motor and laser of all network scanners will be turned on. • **Activation:** The digital input is used to activate the Energy Saving. Thus, the motor and laser of all network scanners will be turned off. • **Activation and Deactivation:** The digital input is used to both activate and deactivate the Energy Saving. Thus, the motor and laser of all network scanners will be turned on/off.
Header	**NOTE:** This parameter is available only when a communication channel has been selected to perform a specific function. Click ✎ to activate the **Text Entry Tool** and create a **Header** (up to 128 bytes) to define a header (1 byte) and transmit it as a block preceding the activation/deactivation string sent to a Master or Stand Alone scanner. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Terminator	**NOTE:** This parameter is available only when a communication channel has been selected to perform a specific function. Click ✎ to activate the **Text Entry Tool** and create a **Terminator** to define a terminator (1 byte) and transmit it as a block following the activation/deactivation string sent to the Master or Stand Alone scanner. Use characters from NUL (00H) to ~ (7EH). Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.
Activation String	**NOTE:** This parameter is available only when a communication channel has been selected to perform the **Activation** or **Activation and Deactivation** function. Click ✎ to activate the **Text Entry Tool** and create a string that defines the characters to be transmitted within the output message to activate the Energy Saving. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

Field Name	Action/Definition
Deactivation String	**NOTE:** This parameter is available only when a communication channel has been selected to perform the **Deactivation** or **Activation and Deactivation** function. Click ✎ to activate the **Text Entry Tool** and create a character string to be transmitted within the output message to deactivate the Energy Saving. Click **Submit** to save your text to the origin window text field, or click **Cancel** to return to origin window without transferring text.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.5.11 Modify Settings | Global Settings | HMI Settings (Human-Machine Interface)

Use the **HMI Settings** window to configure some aspects of the scanner LEDs and X-Press interface.

To view and edit the HMI Settings:

1. In the tree menu under **Modify Settings**, navigate to **Global Settings | HMI Settings**. The HMI Settings window opens.

2. Enter the appropriate information in the form as described below:

Field Name	Action/Definition
LED Settings	
Partial Read Is Treated As	Select **No Read** or **Good Read** from the drop-down list.
Multiple Read Is Treated As	Select **No Read** or **Good Read** from the drop-down list.
Indicate Errors on Master	Select the check box to indicate errors from all Slave scanners also on the Master scanner's GOOD LED as described in the Scanner Reference Manual – LED Diagnostic Indication. See also **Modify Settings	Global Settings	Diagnostics**.
Read LED Timeout	Select **Disable** or a second value from the drop-down list.
XPRESS Settings	
XPress Button Enable	Select Unlocked, Partially Locked, or Locked from the drop-down list. • **Unlocked:** When selected, the XPress button is active • **Locked:** When selected, the XPress button is inactive

Test Mode Exit Timeout	Select **Disable** or a second value from the drop-down list. This indicates how long the scanner will stay in **Test** mode.
Auto Learn Exit Timeout	Select **Disable** or a second value from the drop-down list. This indicates how long the scanner will stay in **Learn** mode.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.6 DEVICE SETTINGS

Use the **Device Settings Menu Tree** selections during initial mounting and setup to view device information and configure your **DS8110/DX8210 barcode scanner(s)**. If multiple scanners are used in a tunnel or array, each named scanner will be listed under Device Settings with the sub-menus **Device Info, Mounting,** and **Options**. If necessary, you can later make modifications to the configuration using the same menu selections, including:
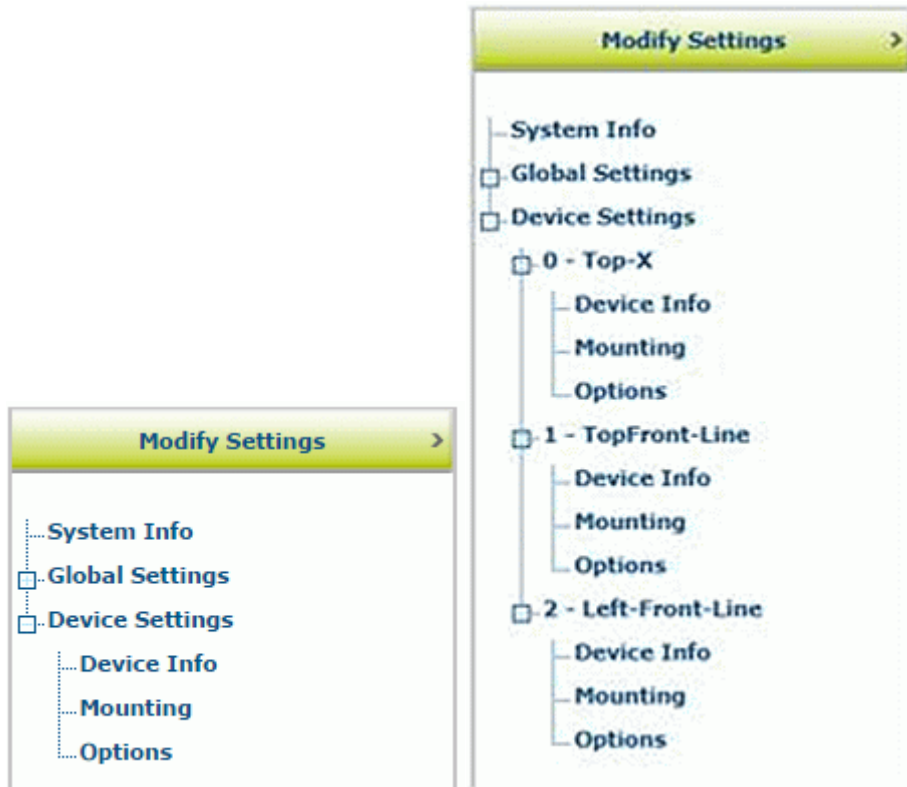
Single Scanner Menu Trees   **Tunnel/Array Menu Tree**

4.6.1   Device Settings | Device Name | Device Info

Use the **Device Info** window to information about each device in the system including description, serial number, and address.

To view the Device Info window:

1. In the tree menu under **Modify Settings**, navigate to **Device Settings | Device Name (if applicable) | Device Info**. The **Device Info** window opens.

NOTE: If more than one device is included in the scanning system, the device name will be listed in the menu tree after the Device Settings level.

2. View the following scanner information:

Field Name	Definition
Description	Displays the scanner description entered in the System Info window.
Device Address	Displays the system address.
Serial Number	Displays the serial number sent by the device.
MAC Address	Displays the MAC (media access control) address of the device.
Model Name	Displays the Model name sent by the device.

Field Name	Definition
Model Number	Displays the Model number sent by the device.
Hardware Release	Displays the hardware release number of the device.
Number Legs	Displays the number of laser legs (beams) produced by the device. Each DS8110 (Line) scanner has 1 leg, while each DX8210 (X) scanner has 2 legs.
Number Lasers	Displays the number or lasers used by the scanner.
Number Facets	Displays the number of facets in the mirror wheel.
Scan Rate (scans/sec)	Displays the scans/per second achieved by the scanner.
Software Versions	
Software Version	Displays the currently installed version of the **ARM** (anonymizing relay monitor) software.
DSP Version	Displays the currently installed version of the decoder software.
FPGA Version	Displays the currently installed version of the **field-programmable gate array** software.

4.6.2   Device Settings | Device Name | Mounting

Use the **Mounting** window to configure some aspects of the scanner LEDs and X-Press interface.

To view and edit the Mounting settings:

1. In the tree menu under **Modify Settings**, navigate to **Device Settings | Device Name (if applicable) | Mounting**. The Mounting window opens.

NOTE: If more than one device is included in the scanning system, the device name will be listed in the menu tree after the Device Settings level.

2. Enter the appropriate information in the form as described below:

Field Name	Definition
Leg *N*	Select a laser leg for calibration from the drop-down list.
Calibration Method	Select **PackTrack Calibration** or **Use Built-in Calibration** from the drop-down list. If **PackTrack Calibration** is selected, use the wizard to automatically enter most of the data. If **Use Built-in Calibration** is selected, you can use it to quickly calibrate a top mount DX8210.

NOTE: Use Built-in Calibration, is the only available with the DX8210. |

Field Name	Definition
	PackTrack Calibration
PackTrack Calibration Wizard	Click **Launch Wizard** to open the **PackTrack Calibration Wizard**. See section *5.7 PackTrack* for the complete procedure for using the wizard to set up your barcode scanner.
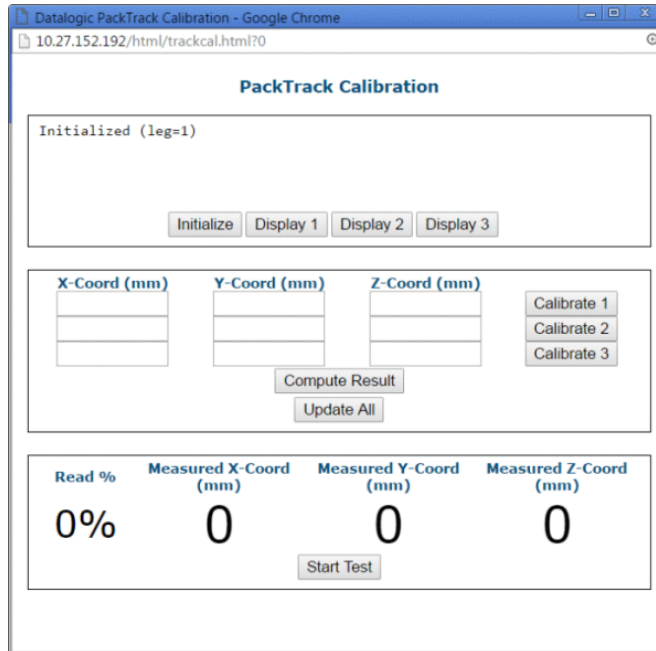
PackTrack Calibration Coefficients	**Y Adjustment**	Enter the scanner adjustment from **Y** axis in millimeters in the field provided. This is used to make fine adjustments to the tested calibration *(see section 4.5.7).*
	Calibration Item 1-9	These non-editable fields display the PackTrack calculations.
	Use Built-in Calibration	
Built-in Calibration	If **Use Built-in Calibration** is selected from the **Calibration Method** drop-down list. The **Scanner Orientation** window appears. See section 5.6 ***Alternate Built-In Calibration for Top Mount*** for the complete procedure for setting up your barcode scanner with built-in calibration.
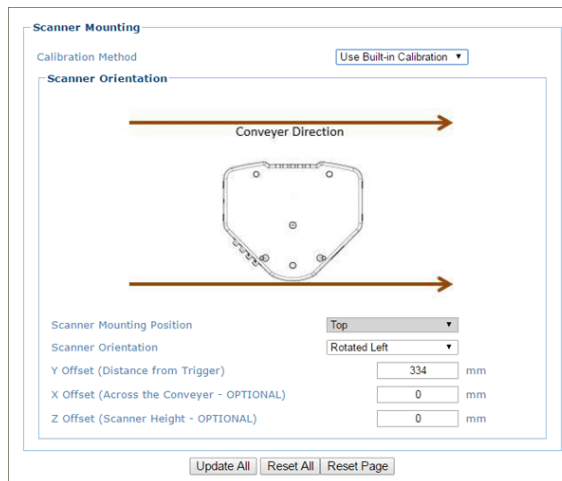
Field Name	Definition
Scanner Mounting Position	Select **Top** or **Side** from the drop-down list. NOTE: **Top** is the only available option with this manual release.
Scanner Orientation	Select **Rotated Right, Forward, Rotated Left,** or **Backward** from the drop down list.
Y Offset (Distance from Trigger)	Enter the distance value in the field provided.
X Offset (Across the Conveyer - OPTIONAL)	Enter the distance value in the field provided.
Z Offset (Scanner Height - OPTIONAL)	Enter the height value in the field provided.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

PackTrack Calibration Wizard

PackTrack is a patented operating mode for **Datalogic Omni-Directional Reading Stations** used to read and correctly assign codes read on different packs when placed in the scanner Reading Area at the same time.

See *section 5.7 **PackTrack*** for the complete procedure for using the wizard to set up your barcode scanner.

4.6.3   Device Settings | Device Name | Options

Use the **Options** window to configure some aspects of the scanner LEDs and X-Press interface.

To view and edit the Options settings:

1. In the tree menu under **Modify Settings**, navigate to **Device Settings | Device Name (if applicable) | Options**. The **Options** window opens.

> **NOTE:** If more than one device is included in the scanning system, the device name will be listed in the menu tree after the Device Settings level.

2. Enter the appropriate information in the form as described below:

Field Name	Definition
Leg 1 (or 2) - Scan Adjust Start	Enter percentages of the total scan area (100%) for each leg of the DX8210 as illustrated in the image below. Make adustments to narrow the reading area of each leg of the X pattern as needed for your application.
Leg 1 (or 2) - Scan Adjust Stop	
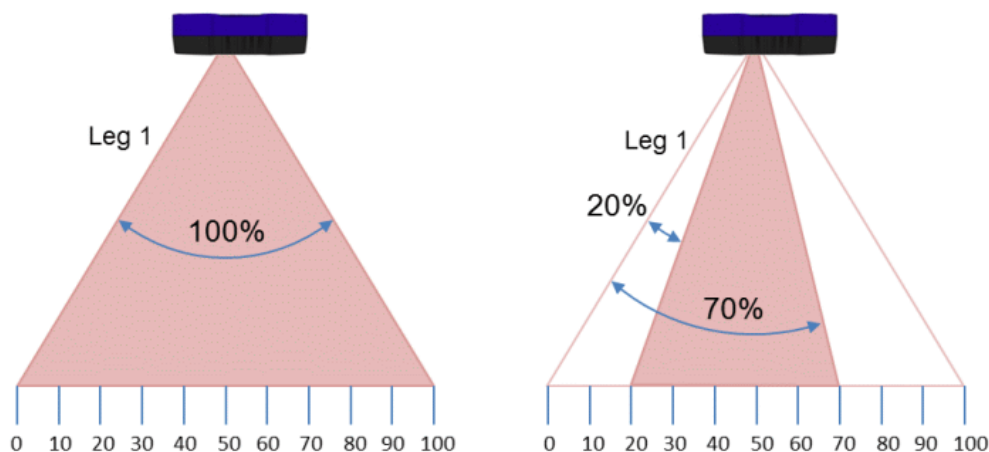
> **NOTE:** The scan lines of the DX8210 are not completely symmetrical, so specifying the same start/end adjustments for both legs may not produce the results expected. Adjust each leg individually according to the read zone it must cover.

Barcode Reconstruction	Select the check box to enable Advanced Code Reconstruction (ACR™) when reading the code. If not checked, standard linear reading mode will be used.
Enable Stacked Codes	Select the check box to improve code reconstruction when two or more codes (of the same or different symbologies) are stacked one on top of the other with little or no space between them.
Configure ETH-2 for Dedicated Setup/Aux	In a master/slave system (scanner as master, not an SC5000), this option is available for slave scanners. Select the check box to enable. This option applies to the last slave scanner in the daisy-chain system, allowing the open Ethernet port to work as a dedicated setup port. In practice, you can always communicate using this port, but selecting the check box turns off all of the other EBC traffic on that port. ⚠️ **CAUTION:** This option must only be applied to the last slave scanner in the EBC network. Applying this option to the other slaves will disrupt the EBC network.

Advanced Reading Settings	
Overflow Start Ratio	Enter the minimum expected width of the barcode starting quiet zone, expressed in number of modules from 1 to 50.
Overflow Stop Ratio	Enter the minimum expected width of the barcode stopping quiet zone, expressed in number of modules from 1 to 50.

Field Name	Definition

Digitizer Settings

⚠️ **WARNING: Field-Programmable Gate Array (FPGA)** patches are intended for special cases only, and must only be applied with the guidance of Datalogic Support.

Number of FPGA Registers to Patch	Select a number from the drop-down list.
FPGA Register *n* Offset	Enter the register offset in the field provided.
FPGA Register *n* Value	Enter the register value in the field provided.
FPGA Register *n* Side to Patch	Select **A+B Side, A Side,** or **B Side** from the drop-down list. "Side" refers to the laser leg of the DX8210, and allow you to choose both legs or either one.

3. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

4.7 DIAGNOSTICS

Use the **Diagnostics** menu tree selections to monitor your barcode scanning system performance, view system messages, and access online help. The **Diagnostic** windows include:
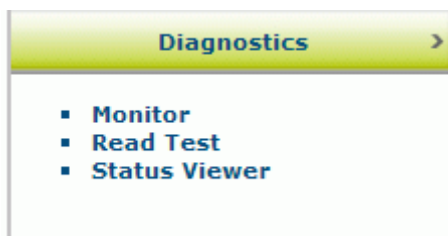
4.7.1 Diagnostics | Monitor

Use the **Diagnostics > Monitor** as the primary tool to monitor the reader's operation and bar code readability in real-time. Status indicators and vital statistics appear on a single screen, enabling you to effectively and efficiently detect and troubleshoot any problems that may occur.

To open the Monitor window:

In the tree menu under **Diagnostics,** navigate to **Monitor**. The **Monitor** window opens.
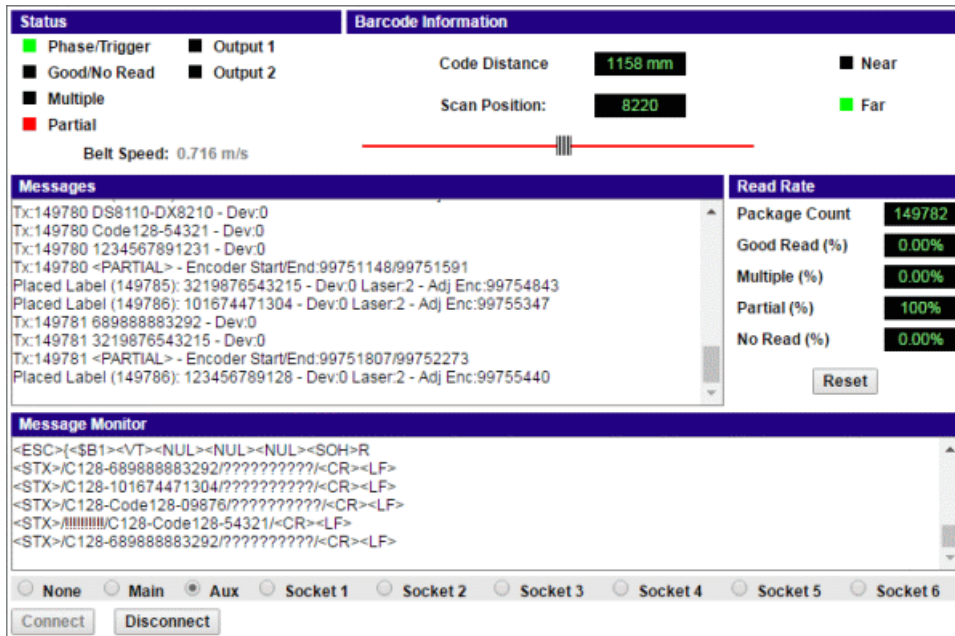
The status indicators in **Diagnostics > Monitor** indicate the following conditions:

Field	Definition
Status	
Phase/Trigger	GREEN indicates trigger input. The LED is activated upon trigger input regardless of trigger source (including software trigger).
Good/No Read	GREEN indicates a good (valid) bar code has been decoded. RED indicates a no-read (or incomplete decode).
Multiple	RED indicates more codes than desired were read.
Partial	RED indicates a partial read.
Output 1 / Output 2	RED indicates activity on that output.
Belt Speed	Indicates the current speed of the belt indicated by the encoder (tachometer).

Barcode Information	
Code Distance (cm)	Displays the distance from the laser origin to the scanned barcode.
Scan Position	Displays the position of the code in the scan line.
Near	**GREEN** indicates the barcode has been scanned by the near-focus laser.
Far	**GREEN** indicates the barcode has been scanned by the far-focus laser.
Messages	
Message Field	Displays message data being returned by the scanner for each barcode scanned.
Read Rate	
Package Count	Displays the number of packages detected since the last reset.
Good Read (%)	Displays the number of good barcode reads since the last reset.
Multiple (%)	Displays the number of multiple barcodes detected since the last reset.
Partial (%)	Displays the number of partially read barcodes since the last reset.
No Read (%)	Displays the number of no reads (no barcode read on package) since the last reset.
Reset	Click to reset the above counters.
Message Monitor	
Message Monitor Field	Select the option button beside **Main, Aux, Socket 1, Socket 2, Socket 3, Socket 4, Socket 5,** or **Socket 6** to display messages for that host port. Select the option button beside **None** to stop displaying messages.
Connect/ Disconnect	Click **Disconnect** to stop (freeze) the **Monitor** window, or click **Connect** to start the **Monitor** window.

4.7.2   Diagnostics | Read Test

Use the Read Test window to check how well a scanner is operating.

To test a scanner's operation:

1. In the tree menu under **Diagnostics**, navigate to **Read Test**. The **Read Test** window opens.
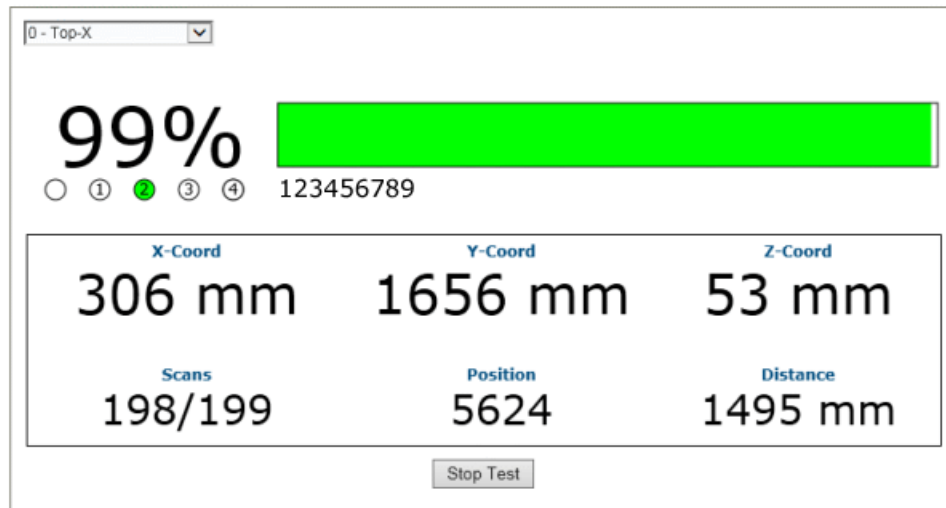
2. If there are multiple scanners in the system, select the scanner to test from the drop-down list at the top of the **Read Test** window.

3. Click the **Start/Stop Test** toggle button to run or stop the real-time performance display of the scanner.

The Read Test displays the following information:

*   **Read Rate:** This is the percentage readout and bar at the top of the window, displaying the read rate since the start of the test.

    The numbered circle indicators below the read-rate percentage indicate in **GREEN**, which of the scanner's lasers is reading the barcode.

    The alpha numeric text following the numbered circle indicators is the barcode data.

*   **Laser Identifiers:** These circles below the Read Rate percentage identify the number of lasers in the scan head as well as highlighting in GREEN the laser that is reading the barcode. In the example above, the scanner has four lasers and laser 2 is identified as reading the code. If the first circle is highlighted in RED, this indicates a NOREAD.

*   **XYZ Coord:** This displays the real-time coordinates of the barcodes being read.

*   **Scans:** Displays the number of times the scanner decoded the test barcode out of the number of opportunities it had to decode the test barcode during a test cycle.

*   **Position**: Displays the position of the barcode in the scan line.

*   **Distance:** Displays the distance from the laser origin to the last barcode read.

4

4.7.3   Diagnostics | Status Viewer

Use the **Status Viewer** to check up on your scanner health.

To access and use the Status Viewer:

1. In the tree menu under Diagnostics, navigate to Status Viewer. The Status Viewer window opens.

```
0 - Top-X                    ▼

SYSTEM WARNING AND ERROR CODES
Warning Codes: None
Error Codes:   None

HARDWARE STATUS
Motor:      No Errors or Warnings
Lasers:     No Errors or Warnings
Acquisition: No Errors or Warnings

Powered On Time: 0-00:20:44.052

Total Power On Time:  225 years  130 days   0 hours
Total Operating Time:  0 years  129 days  23 hours




              [Status] [Read Rate] [H/W Info] [Counters] [Message Log] [Clear]

┌─Command──────────────────────────────────────────────────┐
│                                                  [Send Command] │
│  Use this field to enter and send commands                │
└────────────────────────────────────────────────────────┘
```

2. Select a device to view from the drop-down list at the top-left corner of the window.

3. Click on a button at the bottom of the display window to select the type of information you want to view:

   • **Status:** displays system warnings or errors.

```
SYSTEM WARNING AND ERROR CODES
Warning Codes: None
Error Codes:   None

HARDWARE STATUS
Motor:      No Errors or Warnings
Lasers:     No Errors or Warnings
Acquisition: No Errors or Warnings


Total Power On Time:  225 years  172 days   8 hours
Total Operating Time:  0 years  172 days   7 hours
```

- **Read Rate**: displays read rate and package count information.

```
READ RATE
Total Packages:        34204
Good Reads:            25086      73%
No Reads:                837       2%
Partial:                8281      24%
Multiple:                  0       0%
```

- **H/W Info:** displays information about the selected hardware, including model, serial number, scans/second, laser information, and more.

```
CONFIGURATION
Model Type:  DS8110-2100
Serial Num:  C14C03507
Mac Address: 00-07-be-00-ef-8a
Num Lasers:  2
Num Legs:    1
Num Facets:  7

CURRENT STATUS
Scan Rate:         1000 scans/sec
Current APD DAC:   469


                Temp        VCC
Laser 1:        40.59 C     3.2790
Laser 2:        40.89 C     3.2722
Logic Board:    39.00 C
APD Board:      41.50 C
```

- **Counters:** displays cumulative data about scans, triggers, errors, and much more.

```
SYSTEM INFO
Scan Rate (scans/sec):  999     Belt Speed (m/s):      1.55
Tach Rate (cnts/sec) : 2429     Belt Speed (ft/min):    306

DECODER COUNTERS
Scan Ints:              14796    DSP Codes:            59214
Triggers:               59548    DSP Triggers:           960
Process L0:             25824    Process L1:               0
Max Elements L0:          310    Max Elements L1:          0
Queue Size:                 1    Queue Max:                9
Mem Alloc Err:              0    Memory Full:              0

SCAN DATA EXCEPTION COUNTERS
Missed DMA:                 0    Missed QDMA:              0
Xfer Overflow:              0    Xfer Bad Length:          0
ASTRA Seg Err:              0    Invalid Leg No:           0
Low Term Count:             0    High Term Count:          0
Motor Var Cnt:              0

ARM Restarts:               0    DSP Restarts:             0
```

- **Message Log:** displays messages logged since the last clear command.

```
0-00:00:00.723: APD Read:  DAC/Temp Ref: 243/6400
0-00:00:00.723: APD Read:  Gain/Offset/Min/Max/Type: -1/-1/-1/-1/-1
0-00:00:00.725: APD DAC Initialized.
0-00:00:00.852: ADC Configuration Complete.
0-00:00:00.959: Loading FPGA file XLC_v20_0_0_0.fpga.
0-00:00:03.938: FPGA device id: 4c55.
0-00:00:03.938: FPGA version: 6.0(0).
0-00:00:06.378: Loading DSP file Decoder_release_v1_8_17_0.dsp.
0-00:00:06.678: DSP load complete.
0-00:00:06.678: Scan Engine Started.
0-00:00:06.679: FPGA Buffer Export Task Started
0-00:00:14.664: Motor Speed Threshold set to 0xFFFF.
0-00:00:14.664: FIR Filter Coefficients Loaded.
0-00:00:14.664: Scan FOV set to 88 deg (off=1562 len=21420)
0-00:00:15.263: Ethernet Initialzation Complete.
0-00:00:15.263: Web Server Initialization Complete.
0-00:00:16.665: DSP Version 1.8.17 Started.
0-00:00:16.665: Scan Engine Initialized.
0-00:00:16.686: IsAlone=0 IsMaster=0 NumDevices=3
Powered On Time: 0-00:38:22.825
```

4. Click **Clear** to clear out the **Message Log**.

You can also enter a specific system command in the field provided at the bottom of the window. Click **Send Command** to execute.

4.8 UTILITIES

Use the **Utilities** menu tree selections to backup, restore, and update system firmware, or to reboot the scanner. The **Utilities** windows include:

4.8.1 Utilities | Backup or Restore

Use **Backup or Restore** to save all the settings to the scanner and backup the settings to the backup module and/or file.

To use the Backup or Restore functions:

1. In the tree menu under **Utilities**, click **Backup or Restore** Info. The **Backup or Restore** window opens.
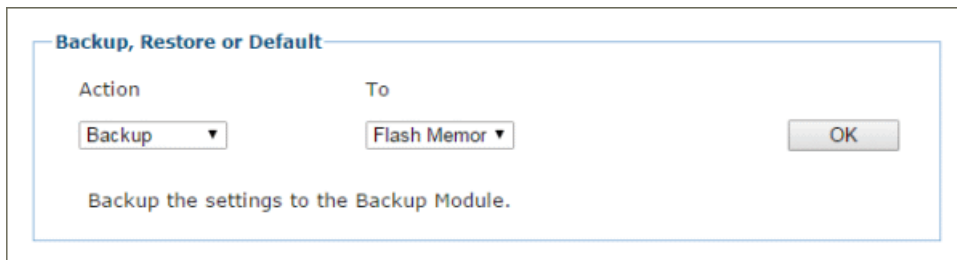
2. From the drop-down lists shown, select an **Action** and a **To/From** option.

Action	To/From	
Backup	**Flash Memory**	When this option is selected, click **OK** to save the settings to the Backup Module (BM100) in the CBX Connection Box. A progress box displays the percent complete of the save operation.
	File	When this option is selected, click **OK** to download the file to your computer. The file can then be saved to an appropriate backup folder.
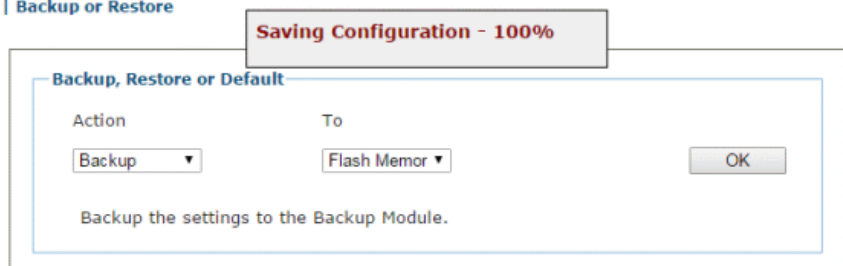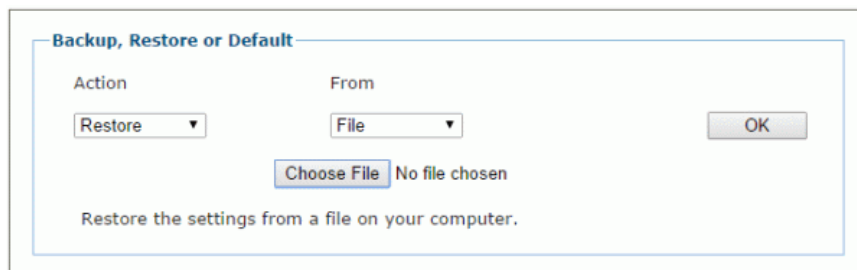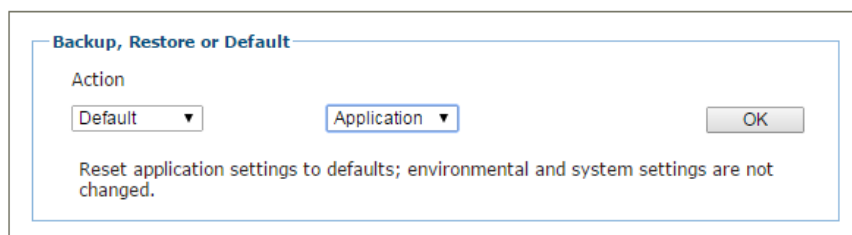
Action	To/From	
Restore	**Flash Memory**	When this option is selected, click **OK** to retrieve the settings to the Backup Module in the CBX. A progress box displays the percent complete of the restore operation.
	File	When this option is selected, a **Choose File** button is revealed. Click **Choose File** to open a file browser and located the settings .txt file to be restored. When the file has been located and selected, click **OK** to save the file to the device.

Default	**Application**	When this option is selected, click **OK** to restore application settings to Factory defaults, except for Ethernet and PackTrack.

	App and Env	When this option is selected, click **OK** to restore all settings including Ethernet and PackTrack.
	All	When this option is selected, click **OK** to **COMPLETELY RESET** the scanner to Factory configuration.

4.8.2   Utilities | Reboot

Use the **Reboot** window the restart the scanner or system.

To use the Reboot function:

1. In the tree menu under **Utilities**, click **Reboot** Info. The Reboot window opens.
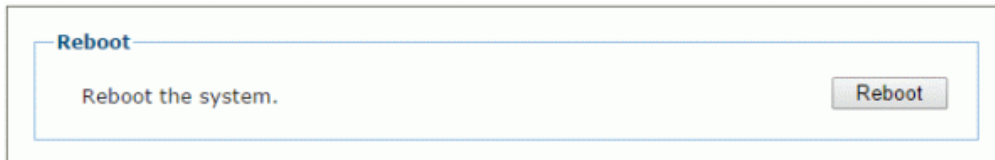
2. Click **Reboot.** A confirmation box appears.
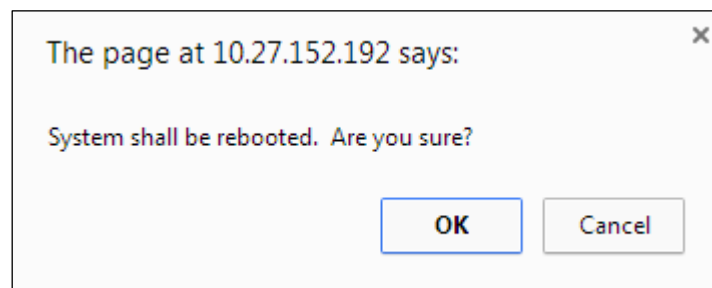
3. Click **OK** to reboot the system, or click **Cancel** to return to the reboot window without restarting the system.

4.8.3   Utilities | Update Firmware

Use **Update Firmware** to reload the scanner system firmware.

⚠️ **CAUTION:** This function should only be performed under the guidance of Datalogic Technical Support.

To Extract Image:

1. In the tree menu under **Utilities**, click **Update Firmware**. The **Update Firmware** window opens.

To Burn Flash

1. Click Browse.
2. In Open window, open an image file (*.as) to burn to flash.
3. Click Burn Flash. The graphic on-screen indicates Burn Flash is in-process.
4. A message will appear when Burn Flash is complete.
5. Reboot (cycle power) your scanner.

To Extract Image

1. Click Extract Image.
2. In Save window, save the image (*.as) file to your computer. The graphic on-screen indicates Extract Image is in-process.
3. A message will appear when Extract Image is complete.

Choose File | No file chosen

Extract Image   Burn Flash   Reboot

2. Click **Extract Image**. A confirmation box appears.

The page at 10.27.154.125 says:

Extracting Firmware Image. Click OK to begin.

OK
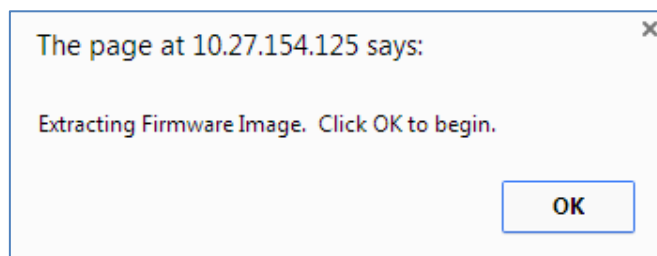
3. Click **OK** to continue.

4. The graphic on screen indicates **Extract Image** is in-process. A message will appear when **Extract Image** is complete.

> The page at 10.27.154.125 says:
>
> Firmware download complete.
>
> OK
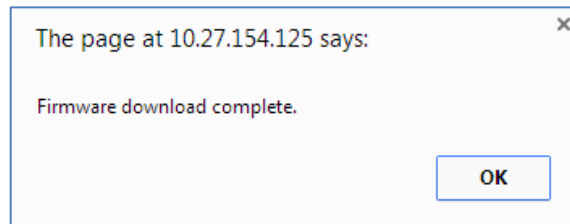
To Burn Flash:

1. Click **Choose File**. In the browse window, select an image file (*.as) to burn to flash.

> NOTE: The appearance of these functions may vary from browser to browser.

2. Click **Burn Flash**. The graphic on-screen indicates **Burn Flash** is in-process.

3. A message will appear when **Burn Flash** is complete.

To Reboot the System:

1. Click **Reboot.** A confirmation box appears.

> The page at 10.27.152.192 says:
>
> System shall be rebooted. Are you sure?
>
> OK   Cancel
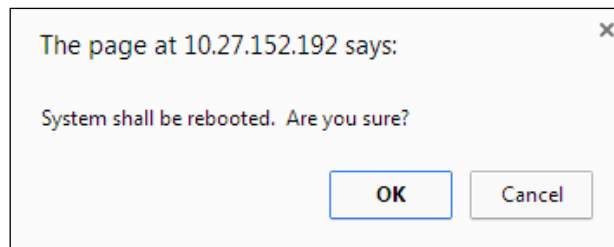
2. Click **OK** to reboot the system, or click **Cancel** to return to the reboot window without restarting the system.

4.8.4   Utilities | Help

e-Genius provides complete online help.

To use the Help system:

In the tree menu under **Utilities**, click **Help**. The **Online Help** window opens.

The **Welcome** page provides important product information as well as three ways to find specific help information: **Contents, Index,** and **Search.**
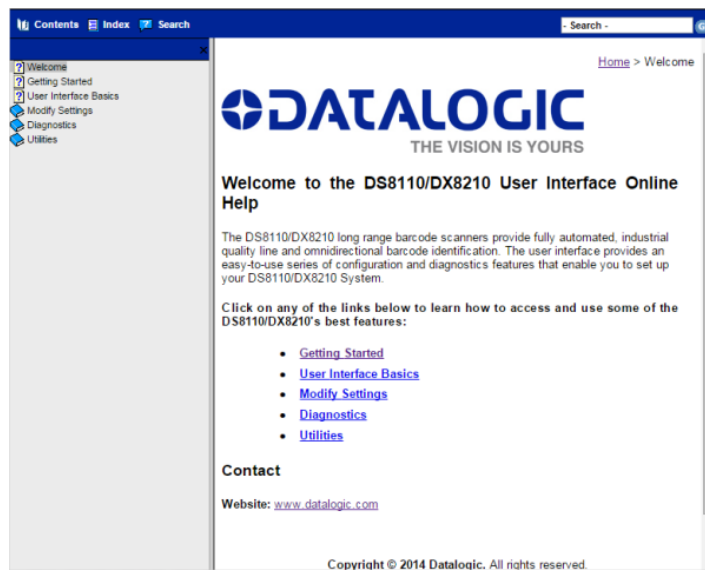
To display contextual help for a current window:

Click the **Help Icon** [icon] displayed at the top right of the screen. A help window appears, providing you with information for that specific page.
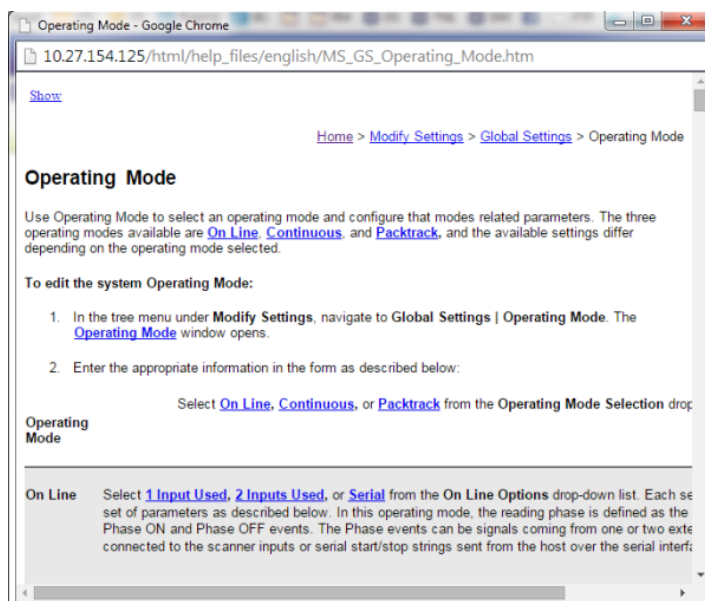
Click the **Show** link in the upper left corner of the help window to access Contents, Index, and Search options.

5   BARCODE SCANNING FEATURES

This chapter provides details on how the DX8210 Barcode Scanning System functions during normal operation. It also helps familiarize the user with status indicator LEDs, Control Panel operation, system setup, and how the scanners can be easily and quickly replaced with a new unit if necessary.

> **IMPORTANT:** The procedures outlined in this chapter should only be performed by a Datalogic trained technician.
>
> For further information on training, contact us through the Datalogic website at www.datalogic.com.

5.1   FIRST-TIME STARTUP

> **NOTE:** Before starting up or testing the scanner, it must be connected to a CBX510 Connection Box or an SC5000 Controller depending on the system configuration.

On initial power-up, the DX8210 performs a series of self-diagnostic and LED tests. The complete power-up sequence takes about 20 seconds. When the **READY** LED flashes and turns a steady green the power-up sequence is complete, and the scanner is operational.

5.1.1   Default Parameters

The barcode scanners are shipped from the factory with these defaults:

- Default Password: DLA
- Control Panel Buttons Enabled
- Code 128 (10-30 characters), Code 39
- IP address HOST (ETH1) 172.27.101.220; Setup 192.168.3.100 (ETH2)

Perform the following setup procedure using these defaults or configure your Barcode scanner with your application's parameters using **e-Genius** *(see Chapter 4).*

5.1.2   Check Operations using Test Mode

> **NOTE:** Perform the following test using a bar code that matches the default parameters. A barcode test chart is included in the box with each scanner, and a code from the chart can be used to perform the test
> If the default parameters have been changed, you must enable the control panel buttons and the other default parameters listed.

To quickly check DX8210 operation:

1. Make sure the scanner is connected to a CBX510 or SC5000.

2. Apply power to the reader.

3. Press and hold the X-Press button until the first two red LEDs light, and then release the button.

4. Position a test barcode symbol approximately 750 mm [30 inches] from the reader. Skew the bar code symbol slightly.

5. The laser(s) should be scanning continuously during normal operations. (Observe the laser safety warnings.)

6. Observe the LEDs. The LEDs illuminate when the reader is scanning and decoding the bar code symbol, and indicate the rough read rate of the scan (see 5.5.1).

5.2 BASIC INSTALLATION PROCEDURES WITH THE CBX510

1. Mechanically install the scanner(s) according to the application drawing for your system.

2. Install the CBX510 according to the application drawing or in a location for best wiring access to scanner(s), encoder (tachometer), and photoelectric sensor.

3. If using more than one scanner, connect the host cable to ETH1 of the designated Master. Then wire ETH2 from the Master to ETH1 of the first Slave, and then from the first slave ETH2 to ETH1 of the next slave and so on.

4. Connect the 25 pin I/O communication cable from the scanner (Master only in multihead systems) to the CBX510.

5. Wire the encoder (tachometer) and photoelectric sensor into the CBX510 *(see sections 3.9 and 3.11).*

6. After the scanner(s), CBX510, and accessories have been carefully wired, apply power to the system.

7. When everything is powered up, connect a laptop to the ETH2 of the scanner (last slave in a multihead system.)

8. Open a browser and enter the default IP (192.168.3.100, *see section 4.5.7.).* **e-Genius** opens.

> **NOTE:** Detailed information on connecting a laptop to the system and using **e-Genius** is available in *Chapter 4.*

9. Log on to **e-Genius** *(see section 4.1.2.).*

10. From the menu tree, select **Modify Settings | System Info**.

11. Select **Standalone** (single head) or **Master** (multihead) from the **Role** drop-down list.

12. If Master is selected, the system is poled, and the other scanners are added to the Device information list.

13. From **Modify Settings | Global Settings | Operating Mode**, select a mode, trigger source, encoder setting.

14. Adjust the barcode settings in **Modify Settings | Global Settings | Barcode Settings Table** according to the needs of your system.
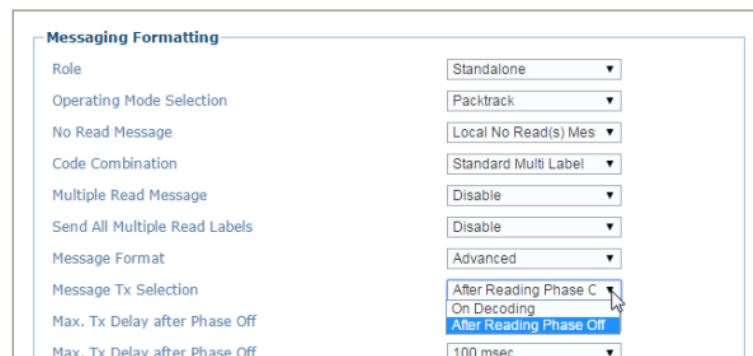
15. In **Modify Settings | Global Settings | Barcode Configuration** select single, multiple, or logical combination of labels, based on your application.


16. Move through the menu tree to configure **Serial Ports, Ethernet,** and **Messaging** settings based on your application requirements.

17. In **Global Settings | Messaging | Message Format** change the **Message Tx Selection** to **After Reading Phase OFF**.

18. Run the **PackTrack** calibration procedure *(see section 5.7).*

19. When the scanner(s) has been configured and calibrated, backup the system configuration using **Utilities | Backup or Restore.** It is recommended to save the system parameters to the backup module on the CBX510 and to a file on your computer.
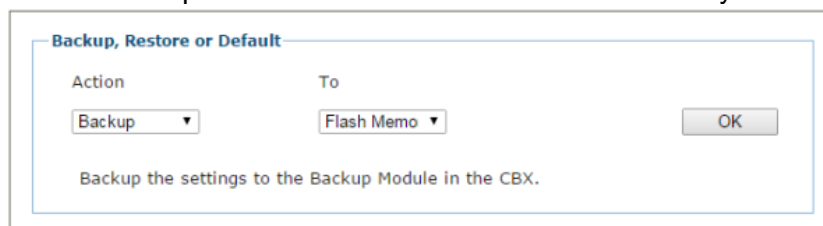
20. Select **Backup** from the **Action** drop-down list, and select **Flash Memory** from the **To** drop-down list.

21. Click **OK**. The following message will be displayed.

22. Next, select **Backup** from the **Action** drop-down list, and select **File** from the **To** drop-down list.

23. Click **OK** to download the configuration text file (param.txt) to your computer.

5.3 BASIC INSTALLATION WITH SC5000 CONTROLLER

1. Mechanically install the scanners according to the application drawing for your system.

2. Install the SC5000 according to the application drawing or in a location for best wiring access to scanner(s), encoder (tachometer), and photoelectric sensor.

3. Connect the host cable to the HOST of the SC5000 *(see figure below)*. Next, wire ETH2 from the SC5000 to ETH1 of the first Slave, and then from the first slave ETH2 to ETH1 of the next slave and so on. If wiring the scanners in a complete ring configuration, connect ETH2 of the last slave in the series to ETH1 of the SC5000.

Figure 41 - SC5000 Standard Model Connector Panel

①	CFG – Configuration	⑥	25-Pin D, Scanner Connector
②	Host	⑦	ENC – Encoder/Tachometer
③	ETH2 – EBC scanner network	⑧	TRG – Trigger/Photoelectric Sensor
④	ETH1 – EBC scanner network	⑨	Watertight Wire Seals
⑤	PWR – Power	⑩	Connector Add-On Panel

4. Connect the encoder (tachometer) and photoelectric sensor (trigger) to the bottom of the SC5000 Controller *(see figure above).*

5. Connect the (unpowered) Power supplies to the scanners and SC5000.

6. After the scanner(s), SC5000, and accessories have been carefully wired, apply power to the system.

7. When everything is powered up, connect a laptop to the CFG port on the front of the SC5000.

8. Open a browser and enter the default IP (192.168.3.100, *see section 4.1.2).* **e-Genius** opens.

> **NOTE:** Detailed information on connecting a laptop to the system and using **e-Genius** is available in *Chapter 4.*

9. Log on to the **e-Genius** *(see section 4.1.2.).*

10. From the menu tree, select **Modify Settings | System Info**.

11. If Master is selected, the system is poled, and the other scanners are added to the Device information list. The SC5000 Controller always serves as the Master when used.

12. From **Modify Settings | Global Settings | Operating Mode**, select a mode, trigger source, encoder setting.

13. Adjust the barcode settings in **Modify Settings | Global Settings | Barcode Settings Table** according to the needs of your system.

14. Adjust the barcode settings in **Modify Settings | Global Settings | Barcode Settings Table** according to the needs of your system.

15. In **Modify Settings | Global Settings | Barcode Configuration** select single, multiple, or logical combination of labels, based on your application.

16. Move through the menu tree to configure **Serial Ports, Ethernet,** and **Messaging** settings based on your application requirements.

17. In **Global Settings | Messaging | Message Format** change the **Message Tx Selection** to **After Reading Phase OFF**.

18. Run the **PackTrack** calibration procedure *(see section 5.7).*

19. When the scanner(s) has been configured and calibrated, backup the system configuration using **Utilities | Backup or Restore.** It is recommended to save the system parameters to *Flash Memory* on the SC5000 and to a *File* on your computer.
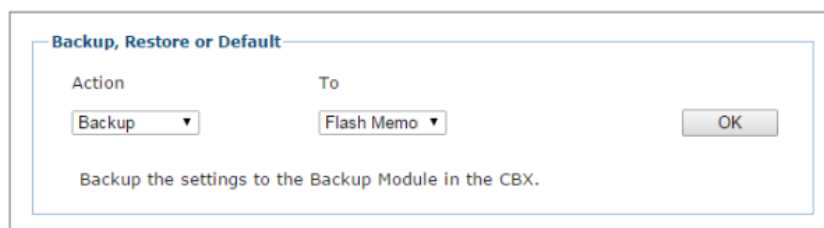
20. Select **Backup** from the **Action** drop-down list, and select **Flash Memory** from the **To** drop-down list.

21. Click **OK**. The following message will be displayed.

22. Next, select **Backup** from the **Action** drop-down list, and select **File** from the **To** drop-down list.

23. Click **OK** to download the configuration text file (param.txt) to your computer.

5

5.4 LED INDICATORS

The DX8210 barcode scanners have several pipe LEDs spanning the top and front panel.
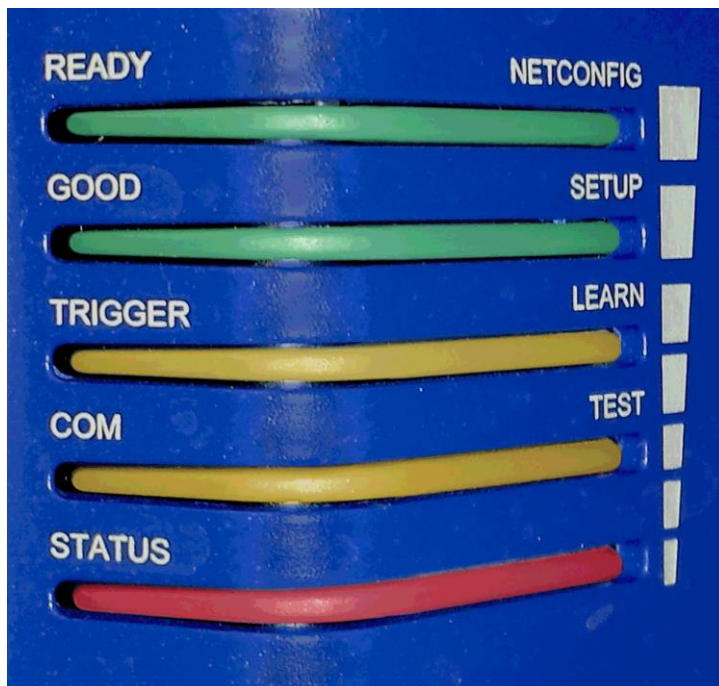
Figure 42: LED Indicators

The indicators have the following meanings:

LED	Description
READY / NETCONFIG	Solid **GREEN** indicates the device is ready to operate.
GOOD / SETUP	Flashes **GREEN** to indicate a barcode was successfully read.
TRIGGER / LEARN	Flashes **YELLOW** to indicate an active external presence sensor. **NOTE:** When operation mode is set to PackTrack *(see section 4.5.1),* these LEDs are inactive on slave scanners.
COM / TEST	Flashes **YELLOW** to indicate data transmitting from main serial port. **NOTE:** When operation mode is set to PackTrack *(see section 4.5.1),* these LEDs are inactive on slave scanners.
STATUS	Flashes **RED** on a NO READ

For alternate functions, *see 5.5.1 X-Press Human Machine Interface* below.

5.5 CONTROL PANEL BUTTONS
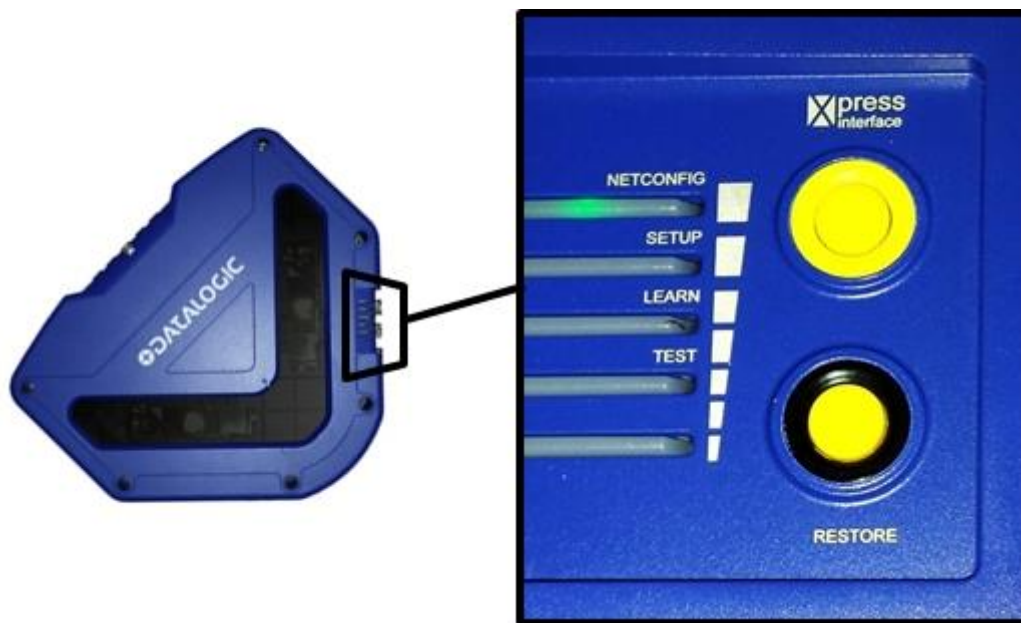
Figure 43: Control Panel Buttons

5.5.1 X-Press™ Human Machine Interface

X-Press is the intuitive Human Machine Interface designed to improve ease of installation and maintenance.

Status information is clearly presented by means of the five colored LEDs, whereas the single push button gives immediate access to the following relevant functions:

- **TEST** with bar graph visualization to check static reading performance

- **LEARN** to self-detect and auto-configure for reading unknown codes

- **SETUP** to allow the open Ethernet port in the last slave scanner in a Master/Slave system to work as a dedicated setup port

- **NETCONFIG** to locate and configure slave scanners in a array (tunnel)

X-PRESS FUNCTIONS

Quick access to the following functions is provided by an easy procedure using the push button:

1. Press the button (the Status LED will give a visual feedback).

2. Hold the button until the specific function LED is on (**TEST, LEARN, SETUP,** or **NETCONFIG**).

3. Release the button to enter the specific function.

Once button is pressed and held, the cycle of LEDs activation is as follows:

Release Button to Exit

Release Button to enter **Test Mode**

Release Button to enter **Learn Mode**

Release Button to enter **Setup Mode**

Release Button to enter **Network Configuration Mode**
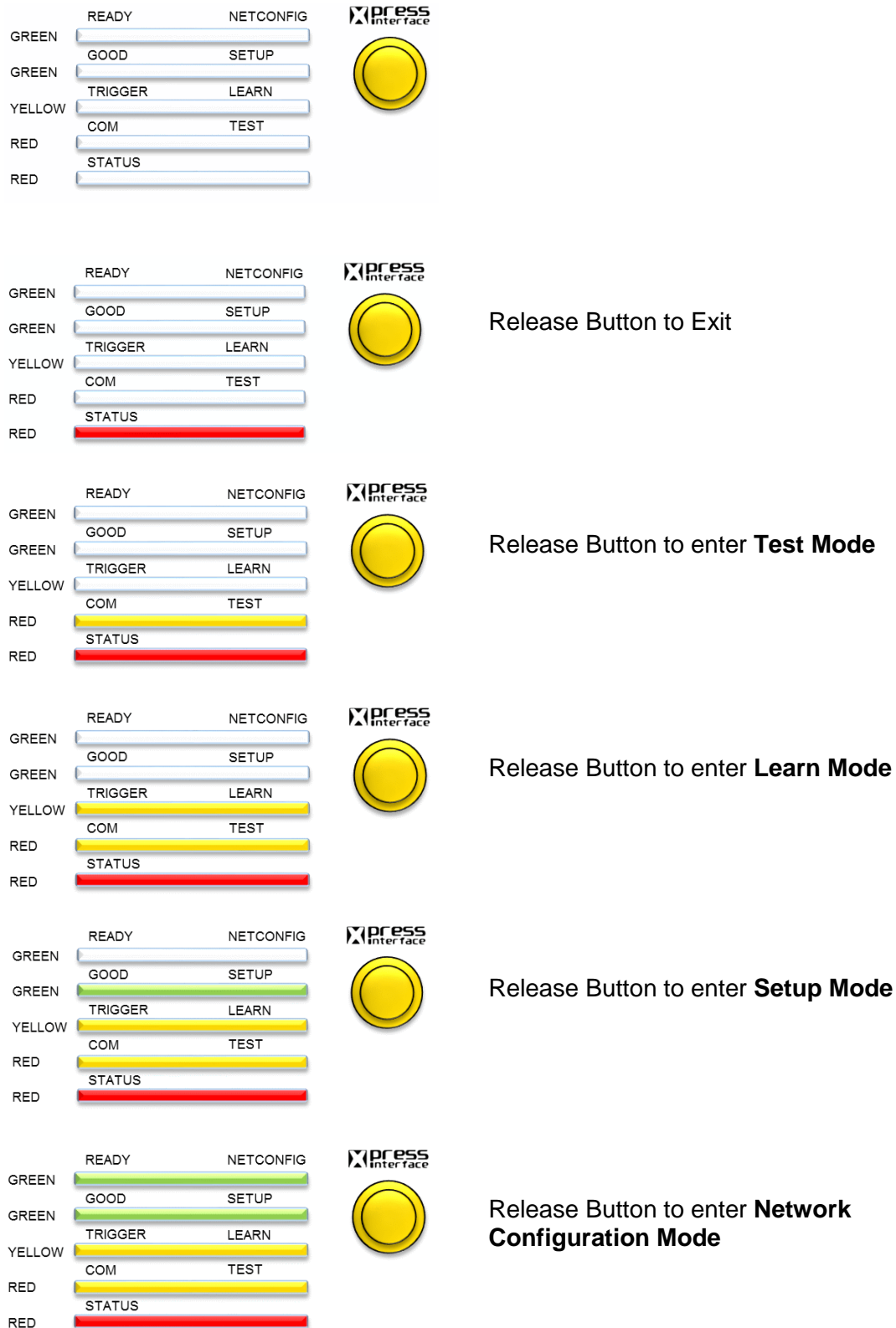
Figure 44: X-Press LED modes

TEST MODE

Once entered, the five LEDs are activated and if the scanner starts reading barcodes. The LEDs indicate the read rate percentage. In case of a NO READ condition, only the Status LED is on and blinks.

The LEDs indicate the read rate percentage as follows:
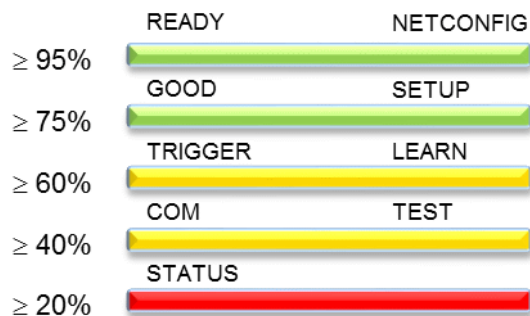
Figure 45: X-Press LED test mode read rate percentages

To exit the **Test Mode**, press the **X-PRESS** push button once.

NOTE: By default, the Test exits automatically after two minutes.

LEARN

Once entered, the **LEARN** LED blinks and scanner starts a procedure to automatically detect and recognize barcodes, which are presented to it.

Place a barcode into the scan line and the **LEARN** LED goes solid for a short time as Processing and Decoding parameters are successfully saved.

If the calibration cannot be reached after a timeout of about 3 (three) minutes, the scanner will exit Learn Mode without saving the parameters.

SETUP

This mode is available in a master/slave system (scanner as master, not an SC5000.)

This option applies to the last slave scanner in the daisy-chain system, allowing its open Ethernet port to work as a dedicated setup port.

In practice, you can always communicate using this port, but the Setup Mode turns off all of the other EBC traffic on that port.

CAUTION: This option must only be applied to the last slave scanner in the EBC network. Applying this option to the other slaves will disrupt the EBC network.

NETCONFIG

Once entered from a Master scanner in a multi-scanner array (tunnel), the system detects and identifies Slave scanners in the array. The Slave scanners (and the Master) will then be available in **e-Genius** *(see chapter 4).*

Press the X-PRESS button once again to exit.

5.5.2   Restore Button and Other Functions

Function	Description
Scanner Replacement	Hold down **RESTORE** button until all LEDs turn on. After all LEDs go off, then READY LED comes back on. Parameters stored in the CBX510 are now being used in the scanner.
Software Recovery Mode	Hold down **X-Press** button while scanner is powered up.
Reset Scanner to Factory Defaults	Hold down **X-Press** and **RESTORE** buttons while scanner powers. When default is successful, all LEDs will flash 3 times.

5.6   BUILT-IN CALIBRATION FOR TOP-MOUNT

When installing a top mounted DX8210 scanner, the **Use Built-in Calibration** selection in the **Device Settings | Device Name | Mounting** window can be used as a quick alternative to the **PackTrack Wizard**.

To Use the Built-in Calibration:

1. In the tree menu under **Modify Settings**, navigate to **Device Settings | Mounting**. The **Mounting** window opens.

2. Select **Use Built-in Calibration** from the **Calibration Method** drop-down list. The **Scanner Orientation** window appears.
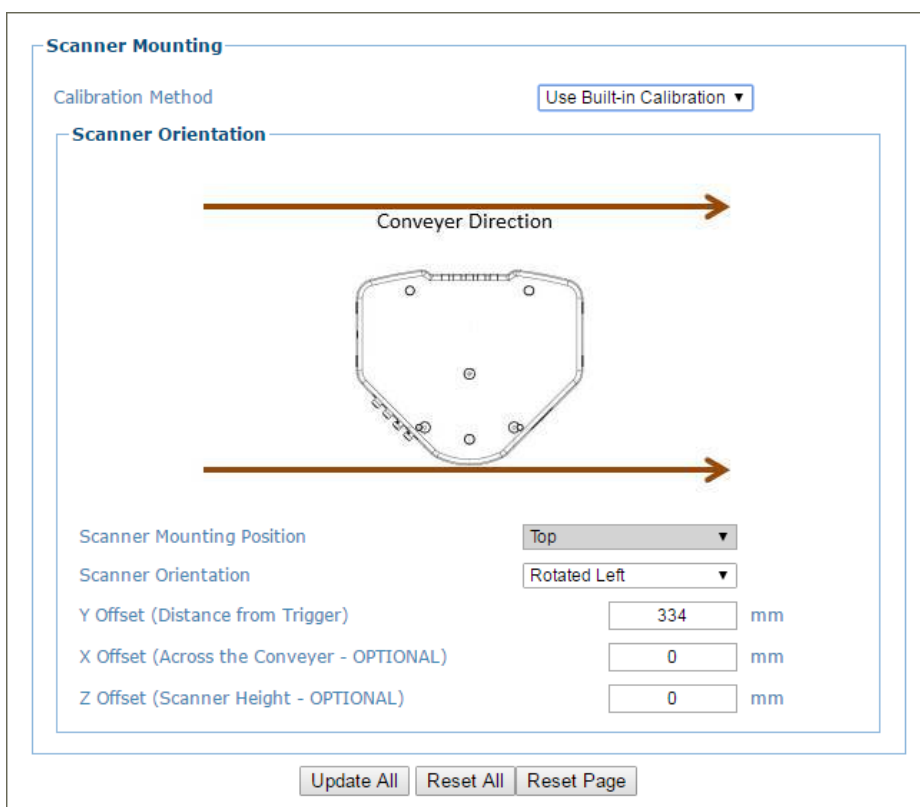
3. Select the scanners orientation to the conveyor from the **Scanner Rotation Angle** drop-down list. Selections include:
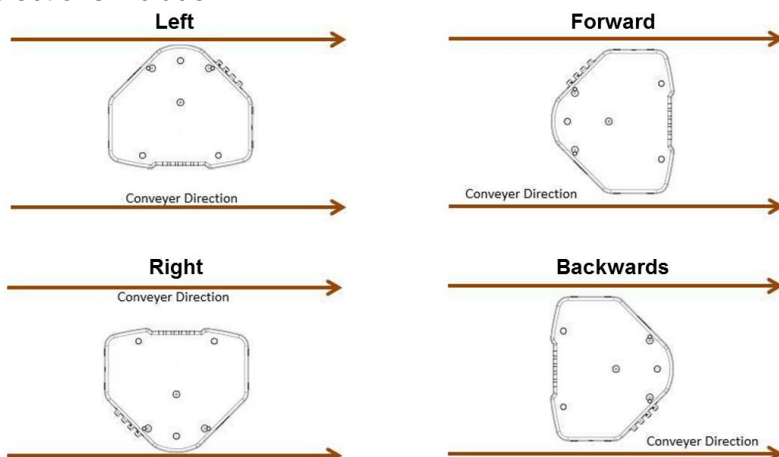
4. With the scanner powered on and the conveyor stopped, tape a piece of paper on the conveyor directly below the top-mounted scanner.

> **NOTE:** The scanner must be mounted with its face parallel and level with the conveyor surface.

5. Suspend a plumb bob from the 0 (zero) locator on the face of the scanner to the paper placed on the conveyor.
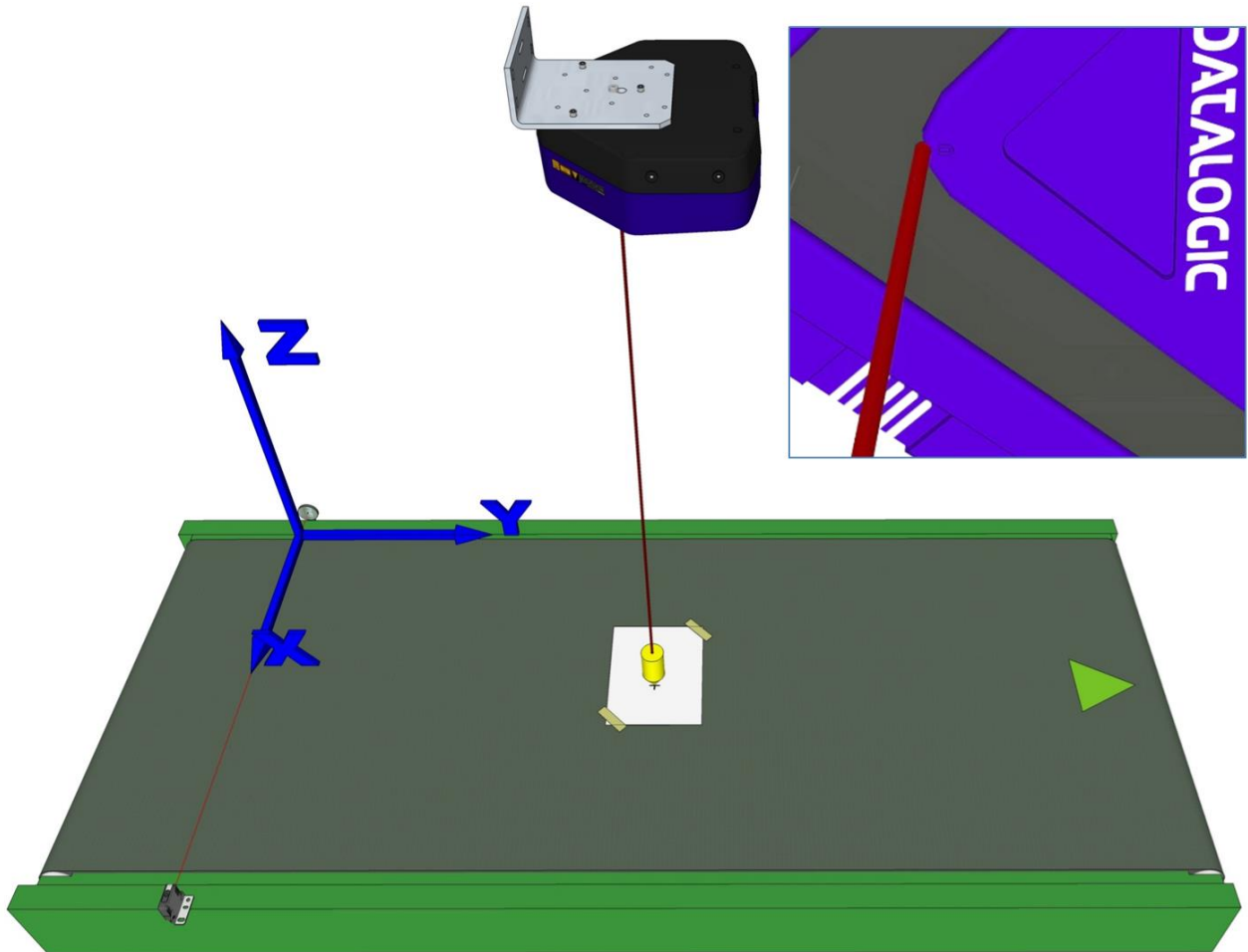
Figure 46: Using a plumb bob to mark scanner location on conveyor

6. Mark the locus of the plumb bob on the paper that is taped to the conveyor surface. For this step, it is helpful to have one person to anchor the plumb bob and a second person to mark its location on the paper.

7. Measure the Y distance from the trigger (photo sensor line) to the locus mark on the paper.
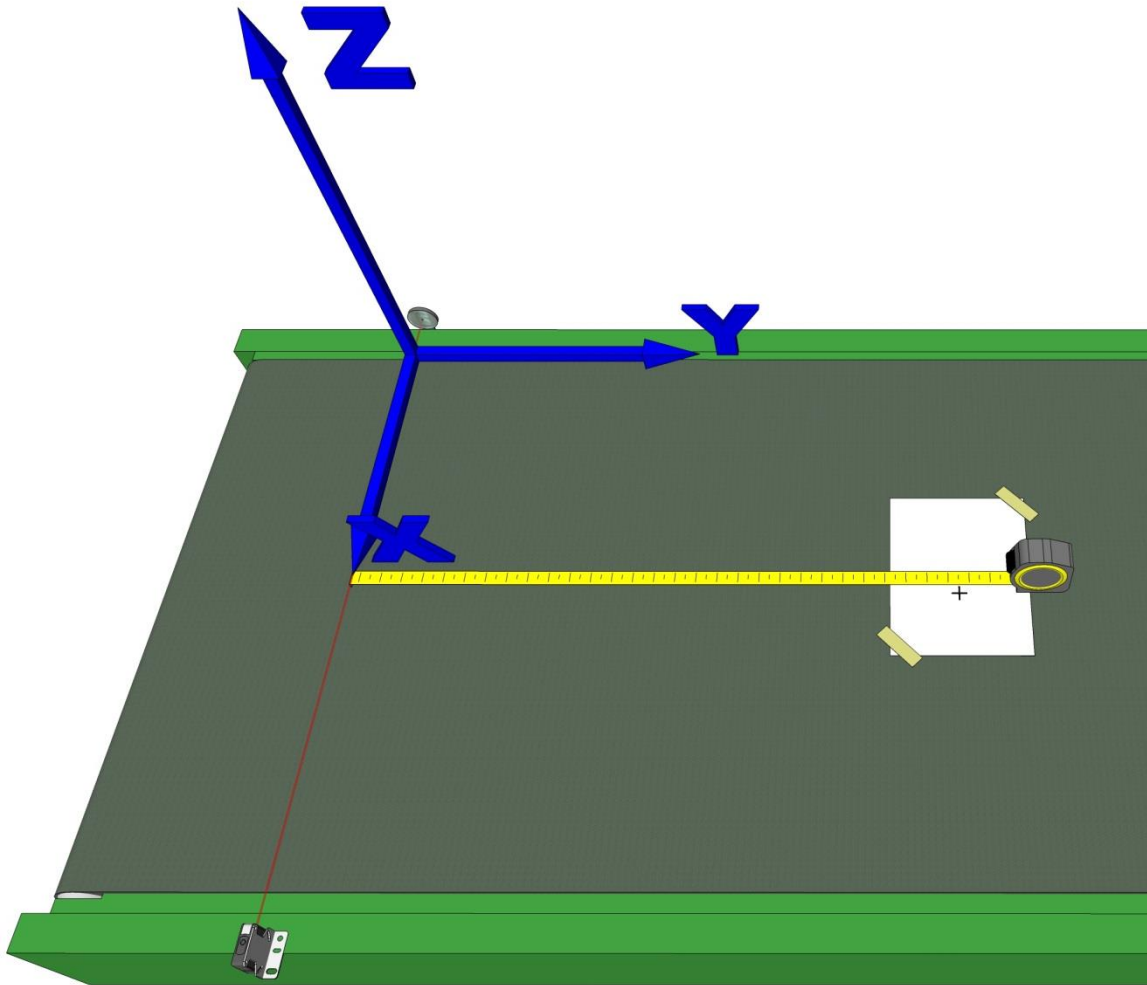
Figure 47: Measuring the Y Offset

8. Enter the Y Offset distance measured in the **Y Offset (Distance from Trigger)** text field.

Y Offset (Distance from Trigger)	1211	mm

5

9. Measure the X Offset from the edge of the conveyor (outside package edge) to the locus mark on the paper.
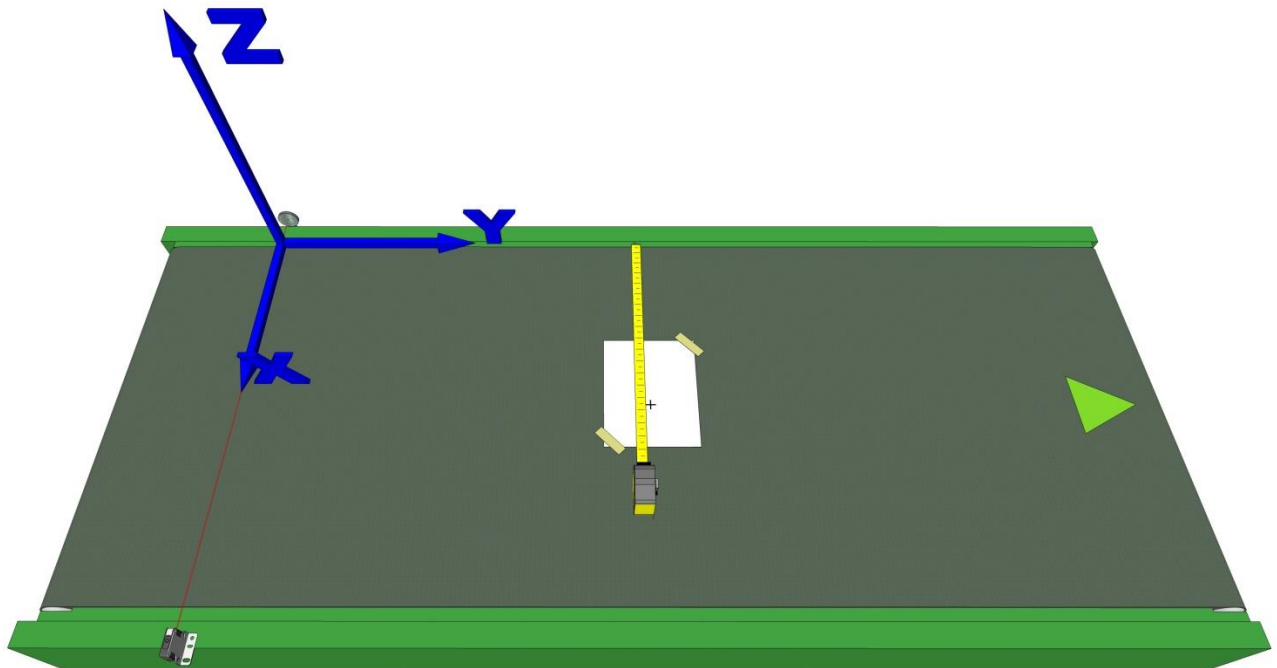
Figure 48: Measuring the X Offset

10. Enter the X Offset distance measured in the **X Offset** text field.

11. Measure the Z Offset from the 0 (zero) locator on the face of the scanner to the locus mark on the paper.
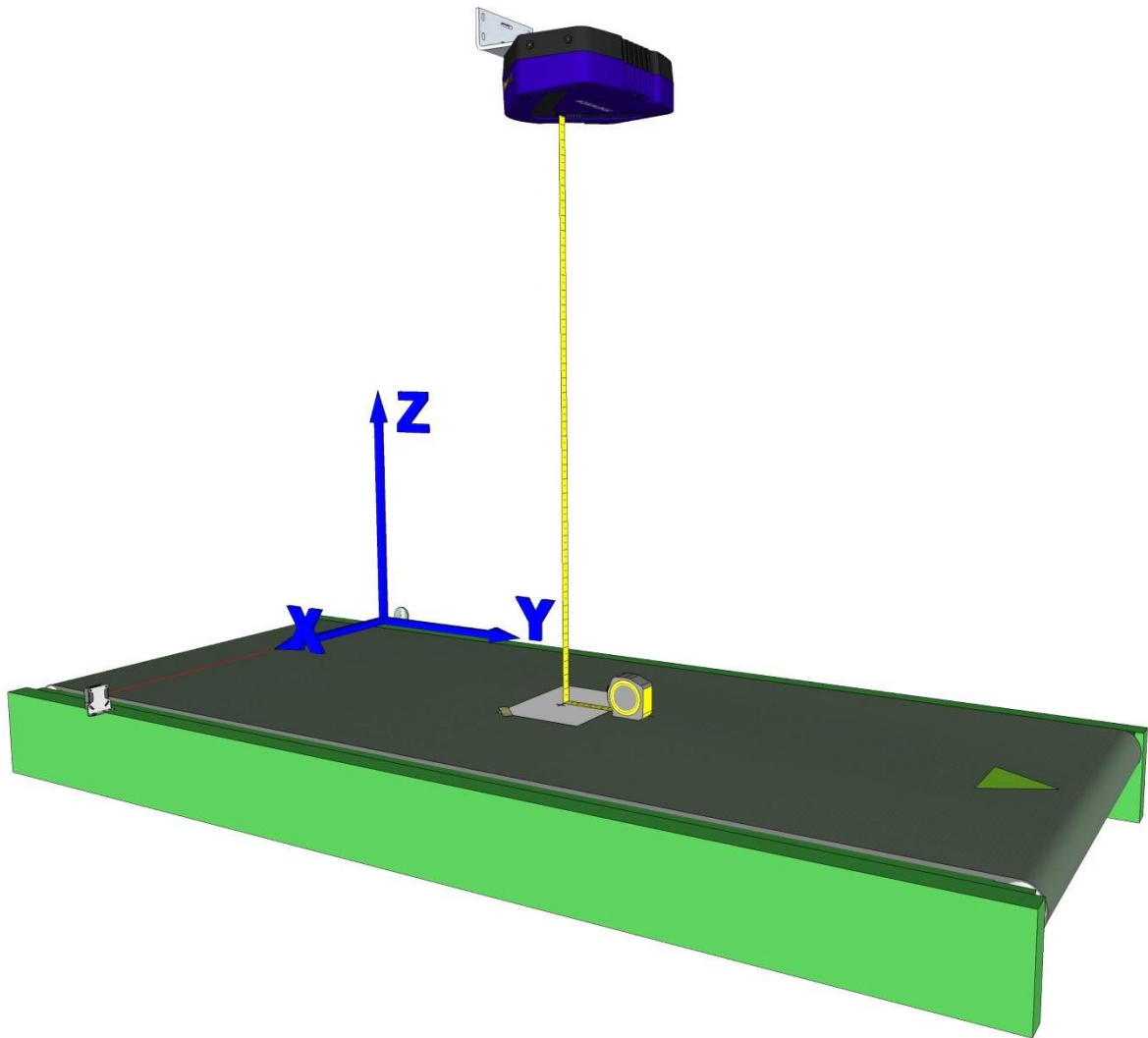
Figure 49: Measuring the Z Offset

12. Enter the Z Offset distance measured in the **Z Offset** text field.

Z Offset (Scanner Height - OPTIONAL)   1490   mm

13. Click **Update** to save the changes.

5.6.1   Built-In Calibration Static Test

1. Place a test label in the center of a box, and place the test box in the scan line as shown below.
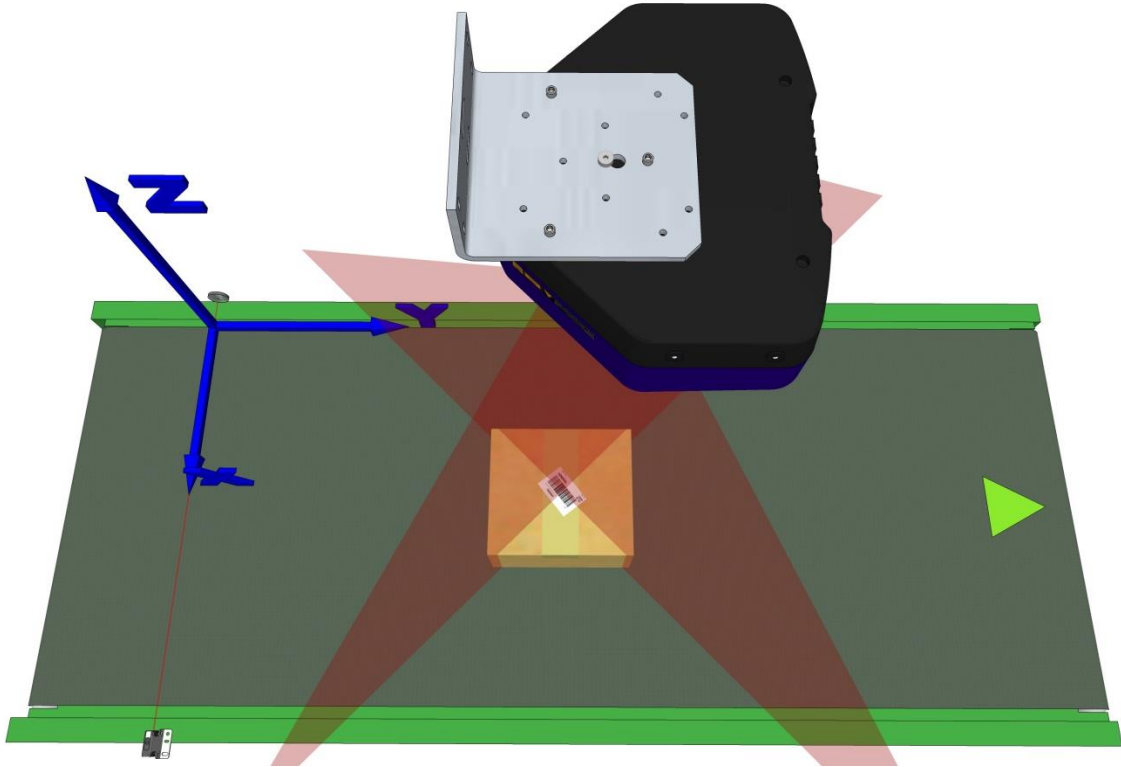
Figure 50: Test box and label placed in laser line

2. In **e-Genius**, navigate to **Diagnostics | Read Test**. The Read Test window opens.

3. Click **Start Test**. The resulting Y-Coordinate returned should be close to the Y Offset measured in the **Alternate Built-In Calibration for Top-Mount** procedure.
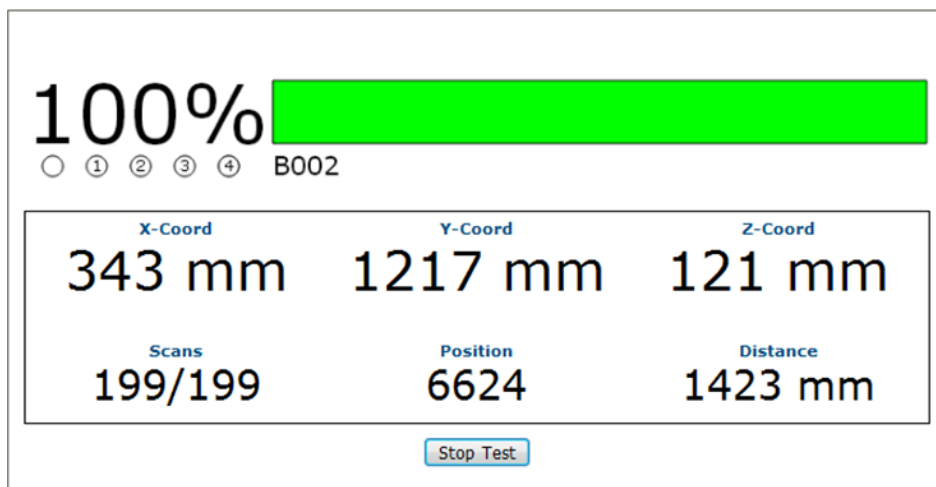
5.6.2 Built-In Calibration Dynamic Test

1. Turn on the conveyor.

2. In **e-Genius**, navigate to **Diagnostics | Monitor**. The **Monitor** window opens.

3. Place a test label in the center of a box, and run the box under the scanner.

4. The scanner should read the label and the results will be displayed on the **Monitor** window.
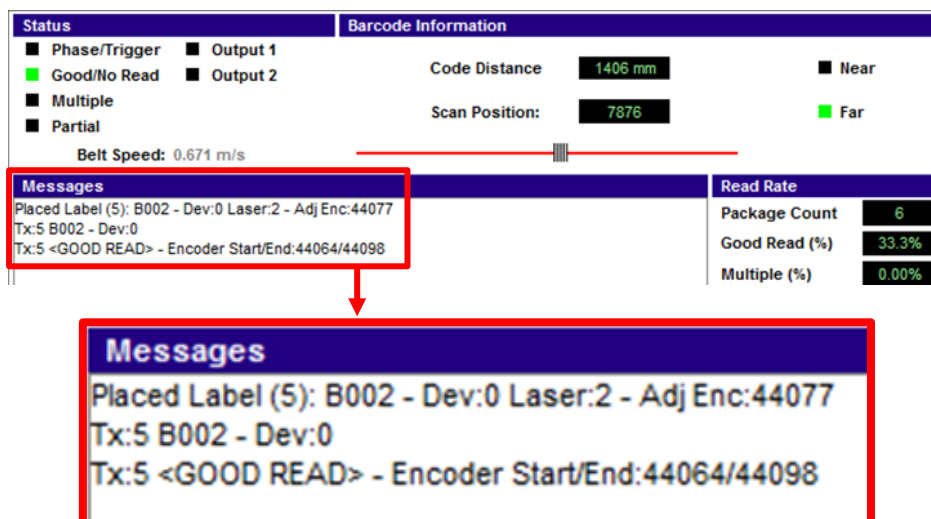
The **Adj Enc** (Adjusted Encoder) value indicates the encoder count at which the label was read. **Encoder Start/End** indicates the encoder values at the start and end of the test box.

The **Adj Enc** value must fall between the start and end values, indicating that the label is on the box. If this is the case, the message states **"Placed Label."**

If the **Adj Enc** value falls outside the start and end values, the message states **"Unplace Label."**

To Verify Label Placement:

1. Using a short test box, place the test label on the leading edge of the top of the box, and run the box under the scanner. If the measurements were correct, the monitor window message should show "Placed Label."
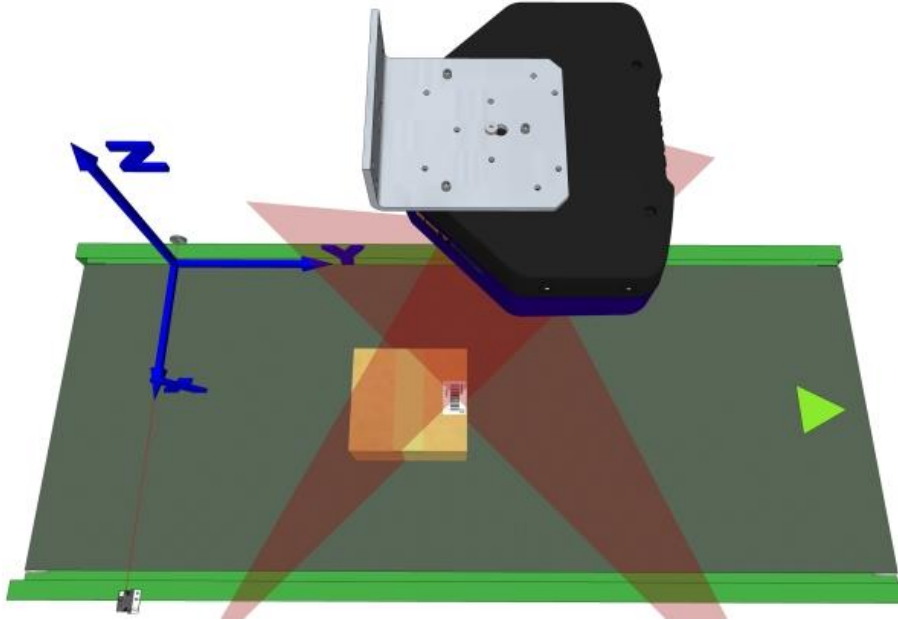
Figure 51: Short box with test label placed on the leading edge

2. Repeat the test three more times with a label on the trailing edge of the same box and on the leading and trailing edges of a tall system box. In each case, the monitor window message should show "Placed Label."

5.7 PACKTRACK™

PackTrack is a patented operating mode for Datalogic Omni-Directional Reading Stations used to read and correctly assign codes read on different packs when placed in the scanner Reading Area at the same time.

In fact, in the following example, the codes of two or more consecutive packs are found at the same time in the scanner reading area. Therefore, the condition occurs where, in the sequence of the two packs, the code of the second pack is read first, just before the code of the previous pack. A system without **PackTrack** would assign the code of the second pack to the first pack and vice versa, thus causing a gross error in sortation.
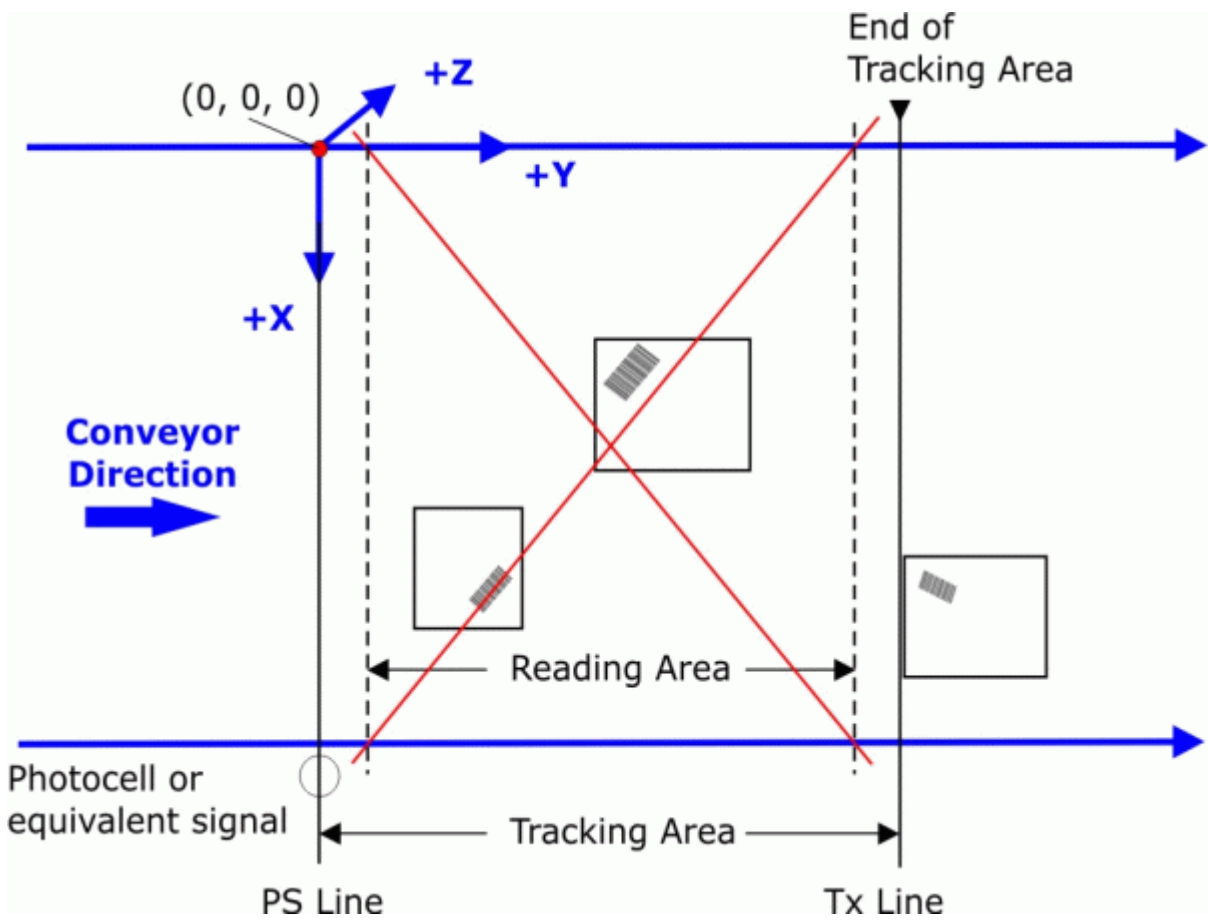
Figure 52: Tracking Problem

NOTE: Tracking starts 10 cm before and stops 10 cm after the Reading Area in order to ensure the barcode is assigned to the correct package.

PackTrack uses a right-handed reference system where the **X** axis coincides with the Photoelectric Sensor line, the **Y** axis coincides with the conveyor direction, and the **Z** axis is oriented upwards from the conveyor (see figure below). The arrows point in the positive direction. The coordinate point of origin (0,0,0) is on the left edge of the conveyor as illustrated.

5
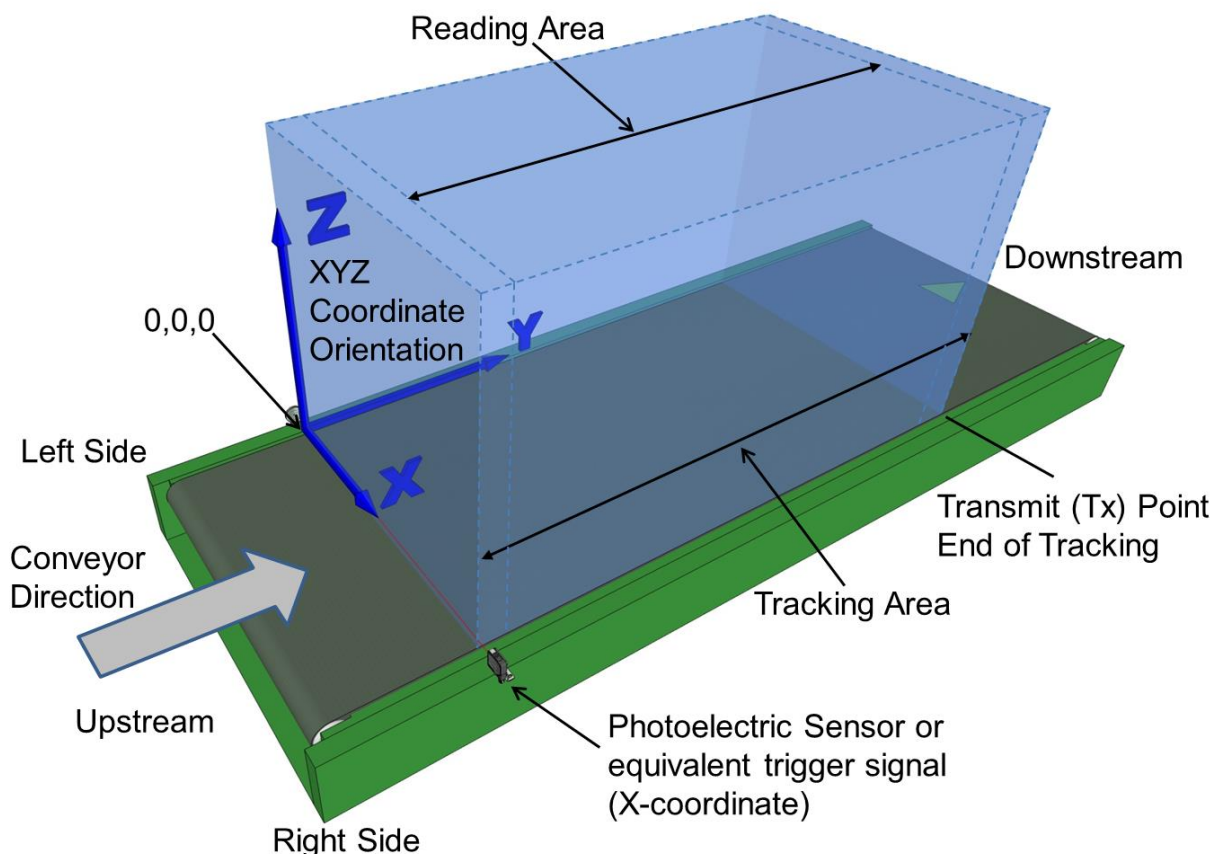
Figure 53: Tracking Area

This coordinate system is absolute for the reading station, i.e. valid for all the scanners independently from their position or orientation with respect to the conveyor. For this reason, after the **PackTrack** configuration (and calibration) has been correctly performed, when a barcode is under the beam to be read by the scanners, its position is defined by the coordinates of its central point, independently from which scanner is reading it.

Step-by-step procedures for calibrating Top-Mounted and Side-Mounted barcode scanners are described below.

5.7.1   Using the PackTrack Wizard

Before you begin calibration:

1. In **Modify Settings/Global Settings/Barcode Settings**, select and configure a system barcode.

2. In **Modify Settings/Global Settings /Barcode Configuration**, create a **Global No Read** message you can easily recognize, such as **NO READ**.

3. In **Modify Settings/Global Settings /Operating Mode**, select **PackTrack** as your **Operating Mode Selection**. Make sure the mode settings and encoder settings match your system parameters.

4. Navigate to **Diagnostics/Read Test.**

5. Place a system barcode in the scan line of the barcode scanner.

6. Click **Start Test**. The scanner should successfully read the barcode. If it doesn't, read successfully or registers a low read rate, check the system specifications for mounting distance and barcode specifications. Then make adjustments as necessary and repeat the test. If the scanner continues to have problems reading the barcode, contact Datalogic (www.datalogic.com).

Diagnostics | Read Test
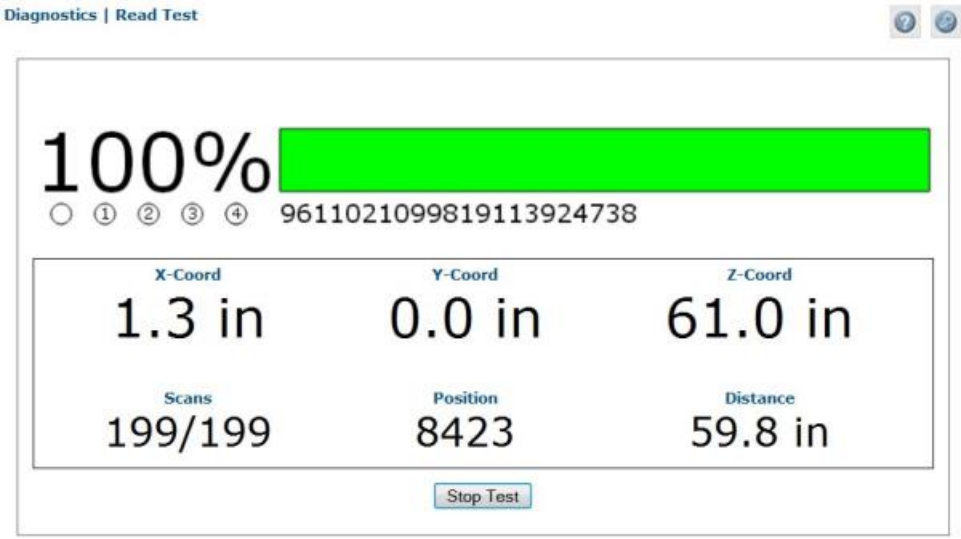
NOTE: A read test tool has now been added to the bottom section of the **PackTrack Calibration Wizard**, which can supply the read rate and XYZ coordinates.

7. Repeat the test for both legs (each laser line of the X-pattern) of a DX8210 scanner.

8. Click **Stop Test**.

To access the PackTrack Wizard:

1. In the tree menu under **Modify Settings**, navigate to **Device Settings | Mounting**. The **Mounting** window opens.

2. Select **PackTrack Calibration** from the **Calibration Method** drop-down list.

3. Select **Leg1** from the drop-down list at the top of the window.

4. Click **Launch Wizard**. The **PackTrack Calibration** wizard window opens.

The **PackTrack Calibration Wizard** asks you to physically measure and enter barcode coordinates for the extremes of your barcode scanning system. You will measure and enter XYZ coordinates for barcodes in three different locations along each of the DX8210's laser line (legs). One leg of a **top-mounted** and **side-mounted** DX8210 scanner is shown in the illustrations below.
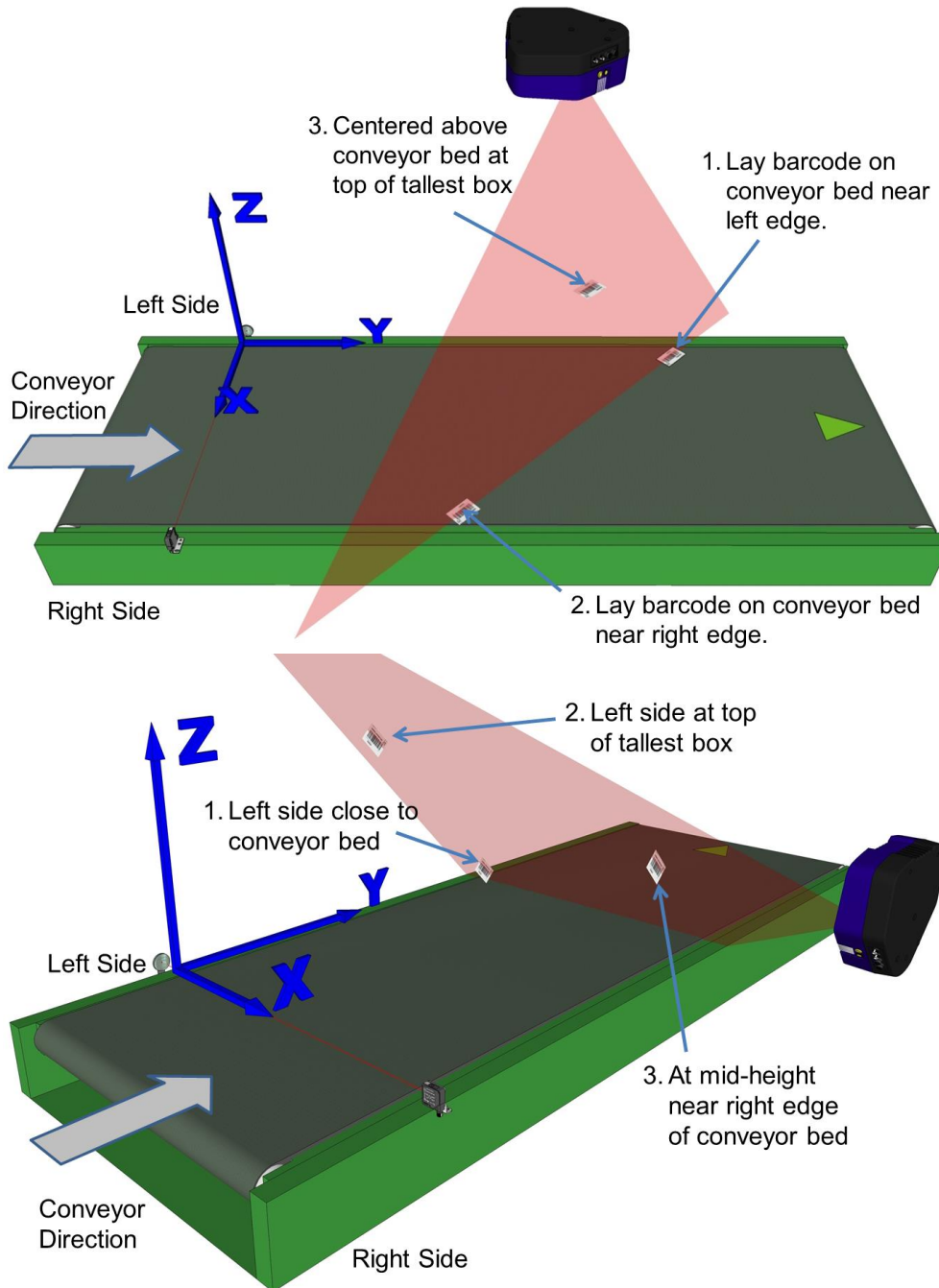
Figure 54: Barcode locations for Top Mount and Side Mount barcode scanners

NOTE: A barcode test chart is included in the box with each scanner, and a code from the chart can be used for the PackTrack calibration. You may also use a standard barcode from your specific application, however, test the code to make sure the scanner reads it at 100% using **Diagnostics | Read Test** in **e-Genius** *(see 4.7.2).*

5

5.7.2 Top-Mounted Barcode Scanner Calibration Using PackTrack

NOTE: It is not possible to illustrate every possible installation angle and scanner mounting position in this manual. Use the following steps as a general guide to calibrating each system scanner using barcodes in three positions. You will need to make adjustments to the label/box position based on your situation. It is, however, important to note the fixed XYZ coordinates of the conveyor.

With the belt stopped, measure and enter the barcode XYZ coordinate data for each scanner as follows:

1. Make sure that the intended scanner (in a multi-head system) and **Leg1** have been selected from the drop-down lists at the top of the wizard window.

2. Lay a system barcode on the conveyor bed in the laser line close to the left edge (X=0 edge) of the conveyor bed. *See illustration below.*
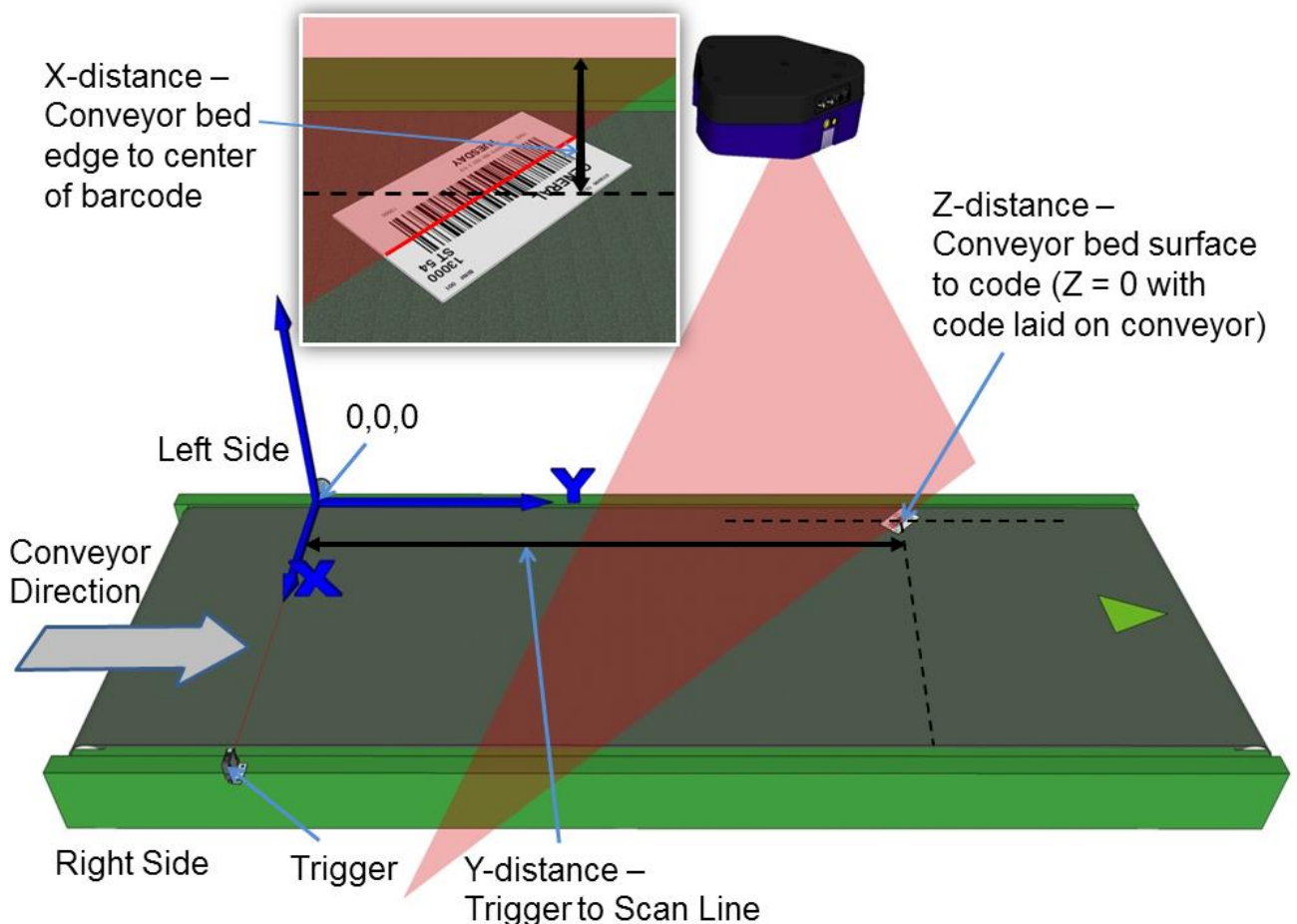
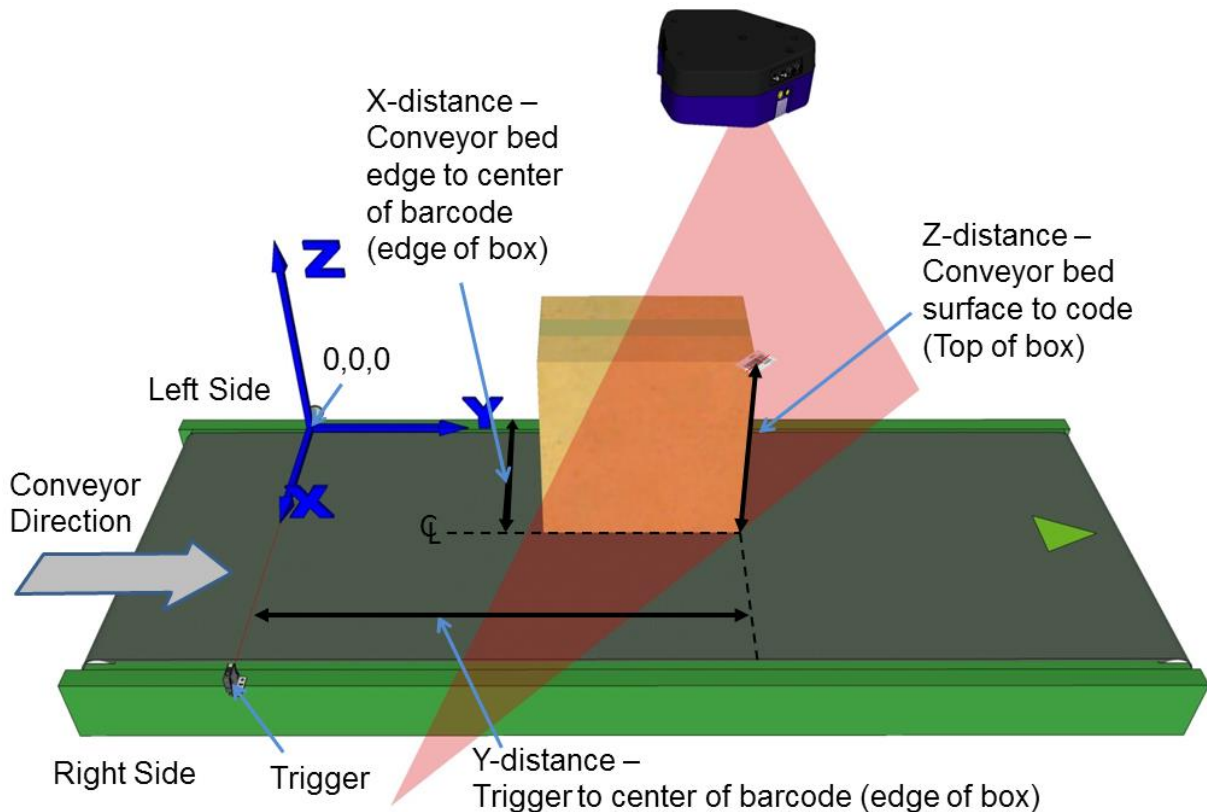**Figure 55: Top-read 1ˢᵗ barcode placement**

3. Measure the distance for **X** from the edge of the conveyor bed to the center of the barcode, and enter that distance in the first box under **X-Coord (mm)** in the **PackTrack Calibration Wizard**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
210		

4. Measure the distance for **Y** from the trigger (PS line) to the barcode scanner's laser line on the barcode, and enter that distance in the first box under **Y-Coord (mm)**.

> **NOTE:** To make it easier to measure the Y-Coordinate, place a box along the photoelectric sensor laser line (Trigger). Then the end of the tape measure or ruler can be place against the edge of the box. *See below.*
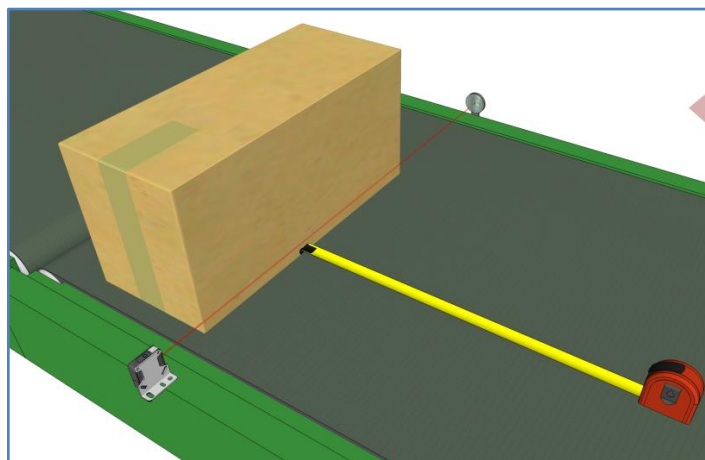
Figure 56: Measuring from trigger

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
210	1080	

5. Measure the distance for **Z** from the conveyor bed to the barcode, and enter that distance in the first box under **Z-Coord (mm)**. Since the barcode is directly on the conveyor bed, the value should be "0."

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
210	1080	0

6. Click **Calibrate 1.** PackTrack data is displayed for the first code.

```
Code 1 -  X/Y/Z:       210.000000 / 1080.000000 / 0.000000
(Leg 1)   Dist/Angle: 1963.987500 / -0.325454
```

[Initialize] [Display 1] [Display 2] [Display 3]

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
210	1080	0	Calibrate 1
			Calibrate 2
			Calibrate 3

[Compute Result]

[Update]

7. Next, place a system barcode on the conveyor bed in the laser line close to the right edge of the conveyor bed. *See illustration below.*
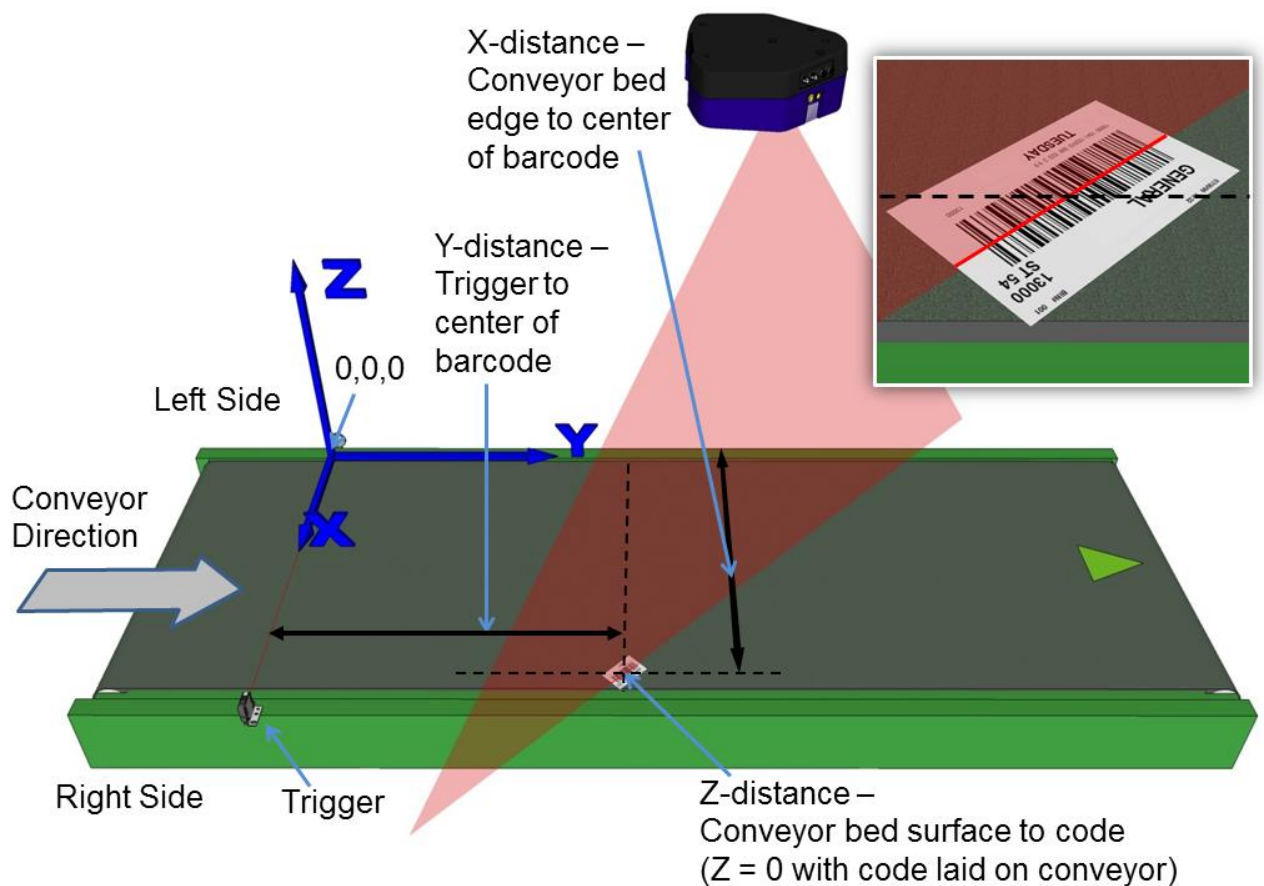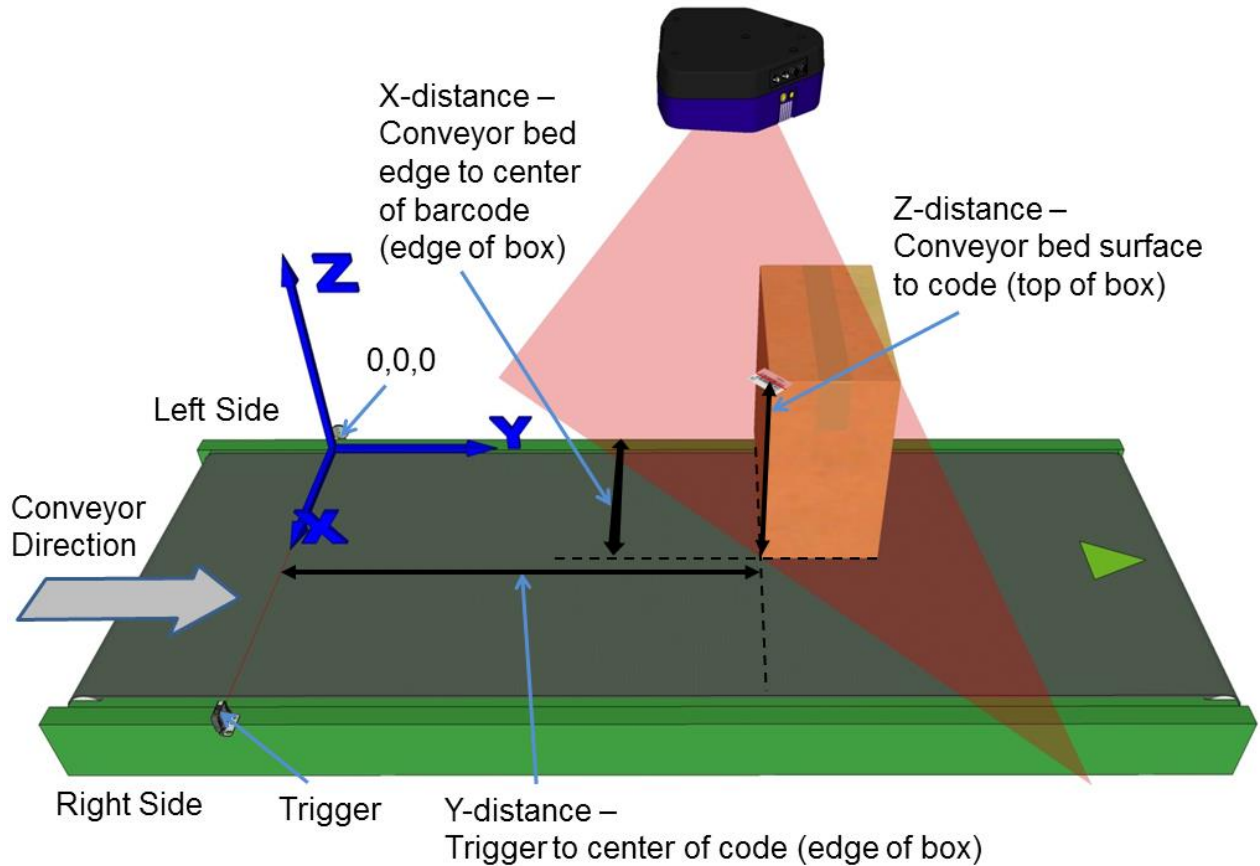

Figure 57: Top-read 2nd barcode placement

8. Measure the distance for **X** from the left edge of the conveyor bed to the center of the barcode, and enter that distance in the first box under **X-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
210	1080	0
1130		

9. Measure the distance for **Y** from the trigger (PS line) to the barcode scanner's laser line on the barcode, and enter that distance in the first box under **Y-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
210	1080	0
1130	218	

10. Measure the distance for **Z** from the conveyor bed to the barcode, and enter that distance in the first box under **Z-Coord (mm)**. Since the barcode is directly on the conveyor bed, the value should be "0."

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
210	1080	0
1130	218	0

11. Click **Calibrate 2.** PackTrack data is displayed for the second code.

```
Code 2 -   X/Y/Z:       1130.000000 / 218.000000 / 0.000000
(Leg 1)    Dist/Angle: 1924.300000 / 0.319797
```

Initialize	Display 1	Display 2	Display 3

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)		
210	1080	0		Calibrate 1
1130	218	0		Calibrate 2
				Calibrate 3

Compute Result

Update

12. Finally, place a system barcode on the back right corner of the tallest system box, as shown in the illustration below.
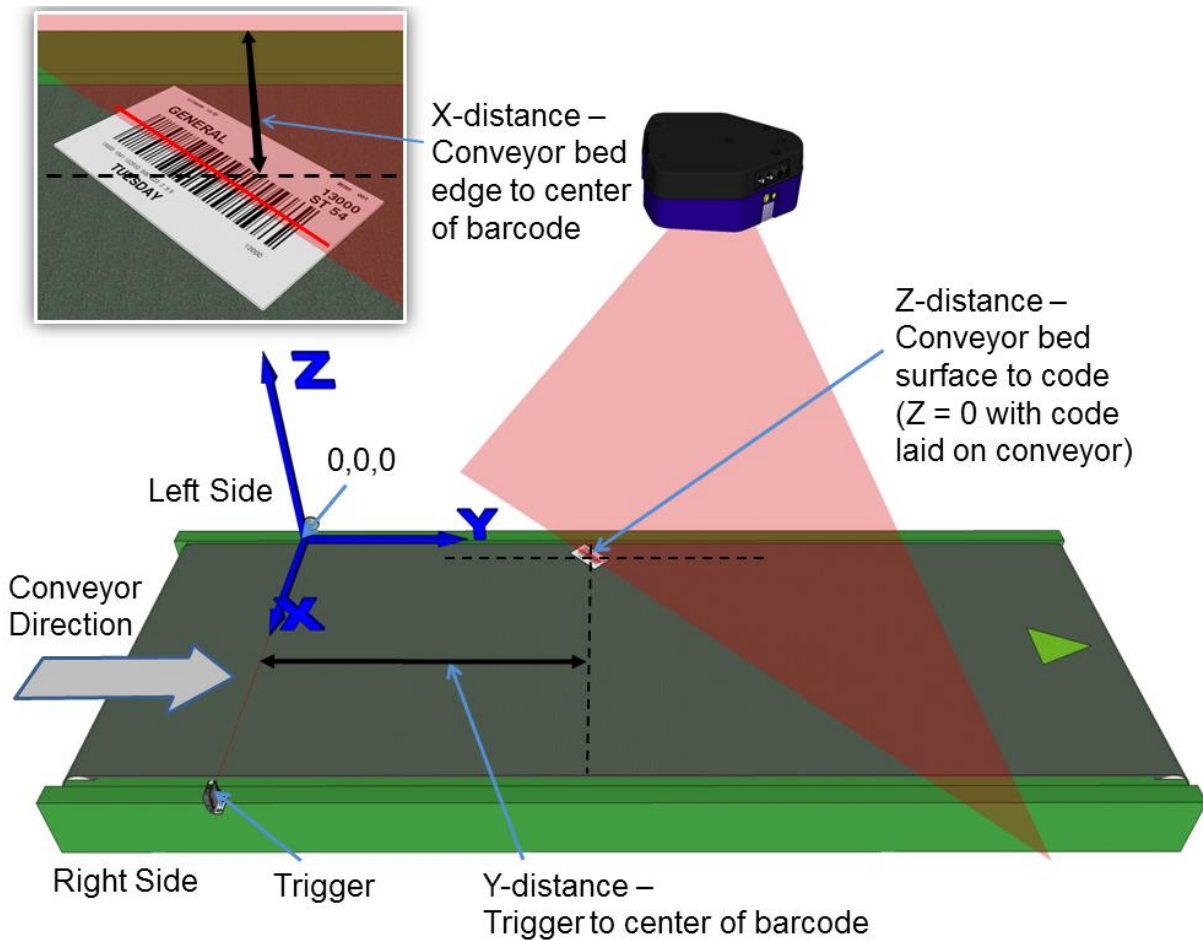

Figure 58: Top-read 3ʳᵈ barcode placement

13. Measure the distance for **X** from the left edge of the conveyor bed to the center of the barcode (edge of box), and enter that distance in the first box under **X-Coord (mm).**

> Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
210	1080	0
1130	218	0
502		

14. Measure the distance for **Y** from the trigger (PS line) to the barcode scanner's laser line on the barcode (back edge of box), and enter that distance in the first box under **Y-Coord (mm)**.

> Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
210	1080	0
1130	218	0
502	650	

15. Measure the distance for **Z** from the conveyor bed to the barcode, and enter that distance

in the first box under **Z-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
210	1080	0
1130	218	0
502	650	910

16. Click **Calibrate 3.** PackTrack data is displayed for the third code.

```
Code 3 -   X/Y/Z:      502.000000 / 650.000000 / 910.000000
(Leg 1)    Dist/Angle: 879.725000 / -0.159012
```

| Initialize | Display 1 | Display 2 | Display 3 |

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
210	1080	0	Calibrate 1
1130	218	0	Calibrate 2
502	650	910	Calibrate 3

Compute Result

Update

17. Click Compute Results. The results are displayed at the top of the **PackTrack Calibration** window.

0 - Top-X   Leg1

```
Result:    0.748256    0.074221 541.760010
          -0.696657    0.090266 474.549408
          -0.025756   -0.929780 1714.043823
```

| Initialize | Display 1 | Display 2 | Display 3 |

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
210	1080	0	Calibrate 1
1130	218	0	Calibrate 2
502	650	910	Calibrate 3

Compute Result

Update

18. Click **Update**. "Update Successful" should be displayed in the **PackTrack Calibration** window.

19. Next, select **Leg2** from the drop-down list at the top of the wizard window. Leg 2 laser comes on.

20. Rotate the tall system box 90-degrees and make sure the laser (leg 2) is centered on the barcode on its top corner, as shown in the illustration below.
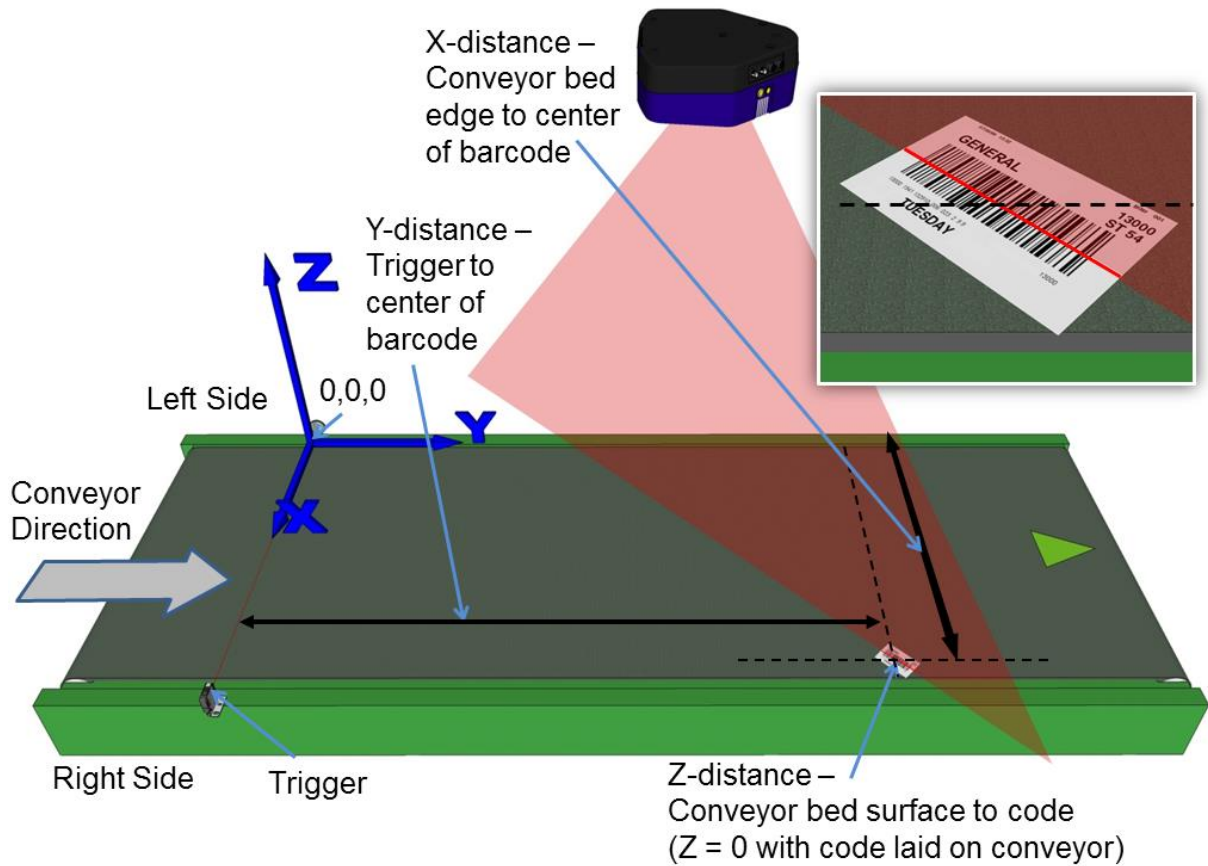

Figure 59: Top-read leg 2- 1st barcode placement

21. Measure the distance for **X** from the left edge of the conveyor bed to the center of the barcode (edge of box), and enter that distance in the first box under **X-Coord (mm).**

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
705		

22. Measure the distance for **Y** from the trigger (PS line) to the barcode scanner's laser line on the barcode (edge of box), and enter that distance in the first box under **Y-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
705	623	

23. Measure the distance for **Z** from the conveyor bed to the barcode, and enter that distance in the first box under **Z-Coord (mm)**.

> Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
705	623	910

24. Click **Calibrate 1.** PackTrack data is displayed for the first code.

```
Code 1 -   X/Y/Z:        705.000000 / 623.000000 / 910.000000
(Leg 2)    Dist/Angle: 860.675000 / 0.076654
```

Initialize	Display 1	Display 2	Display 3

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
705	623	910	Calibrate 1
			Calibrate 2
			Calibrate 3

Compute Result

Update

25. Place a system barcode on the conveyor bed in the laser line close to the left edge (X=0 edge) of the conveyor bed. *See illustration below.*

Figure 60: Top-read leg 2- 2nd barcode placement

26. Measure the distance for **X** from the edge of the conveyor bed to the center of the barcode, and enter that distance in the first box under **X-Coord (mm)** in the **PackTrack Calibration Wizard**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
705	623	910
158		

27. Measure the distance for **Y** from the trigger (PS line) to the barcode scanner's laser line on the barcode, and enter that distance in the first box under **Y-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
705	623	910
158	202	

28. Measure the distance for **Z** from the conveyor bed to the barcode, and enter that distance in the first box under **Z-Coord (mm)**. Since the barcode is directly on the conveyor bed, the value should be "0."

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
705	623	910
158	202	0

29. Click **Calibrate 2**. PackTrack data is displayed for the first code.

```
0 - Top-X          ▼   Leg2        ▼
```

```
Code 2 -  X/Y/Z:      158.000000 / 202.000000 / 0.000000
(Leg 2)   Dist/Angle: 1903.662500 / -0.339835
```

Initialize   Display 1   Display 2   Display 3

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
705	623	910	Calibrate 1
158	202	0	Calibrate 2
			Calibrate 3

Compute Result

Update

30. Next, place a system barcode on the conveyor bed in the laser line close to the right edge of the conveyor bed. *See illustration below.*

Figure 61: Top-read leg 2- 3rd barcode placement

31. Measure the distance for **X** from the left edge of the conveyor bed to the center of the barcode, and enter that distance in the first box under **X-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
705	623	910
158	202	0
1030		

32. Measure the distance for **Y** from the trigger (PS line) to the barcode scanner's laser line on the barcode, and enter that distance in the first box under **Y-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
705	623	910
158	202	0
1030	1134	

33. Measure the distance for **Z** from the conveyor bed to the barcode, and enter that distance in the first box under **Z-Coord (mm)**. Since the barcode is directly on the conveyor bed, the value should be "0."
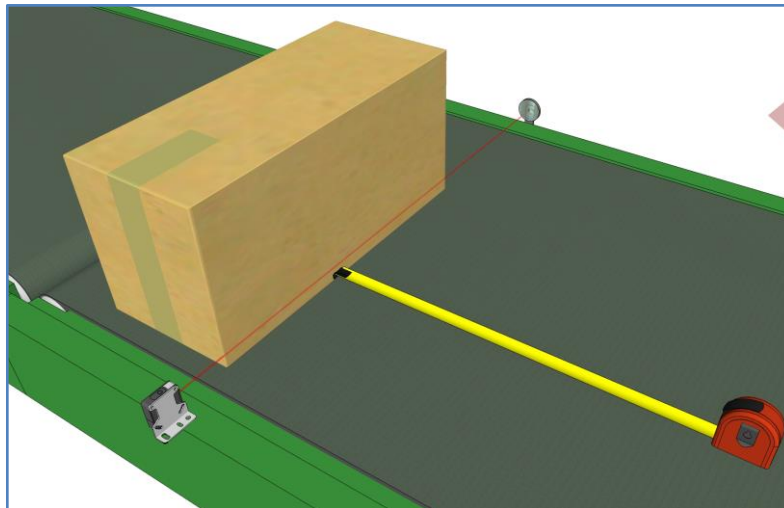
Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
705	623	910
158	202	0
1030	1134	0

34. Click **Calibrate 3.** PackTrack data is displayed for the second code.

```
Code 3 -   X/Y/Z:      1030.000000 / 1134.000000 / 0.000000
(Leg 2)    Dist/Angle: 1944.937500 / 0.317304
```

<kbd>Initialize</kbd> <kbd>Display 1</kbd> <kbd>Display 2</kbd> <kbd>Display 3</kbd>

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
705	623	910	Calibrate 1
158	202	0	Calibrate 2
1030	1134	0	Calibrate 3

<kbd>Compute Result</kbd>
<kbd>Update</kbd>

35. Click **Compute Results**. The results are displayed at the top of the **PackTrack Calibration** window.

0 - Top-X ▼   Leg2 ▼

```
Result:    0.704872  -0.056868 707.343628
           0.746137   0.108514 480.701294
           0.040237  -0.941464 1715.262817
```

<kbd>Initialize</kbd> <kbd>Display 1</kbd> <kbd>Display 2</kbd> <kbd>Display 3</kbd>

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
705	623	910	Calibrate 1
158	202	0	Calibrate 2
1030	1134	0	Calibrate 3

<kbd>Compute Result</kbd>
<kbd>Update</kbd>

36. Click **Update**. "Update Successful" should be displayed in the **PackTrack Calibration** window.

37. Close the **PackTrack Calibration Wizard** window. **PackTrack Calibration Coefficients** have been populated on the Scanner Mounting widow.

38. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

39. See **Verifying PackTrack Calibration** *(section 5.7.4)*.

5.7.3 Side-Mounted Barcode Scanner Calibration Using PackTrack

NOTE: It is not possible to illustrate every possible installation angle and scanner mounting position in this manual. Use the following steps as a general guide to calibrating each system scanner using barcodes in three positions. You will need to make adjustments to the label/box position based on your situation. It is, however, important to note the fixed XYZ coordinates of the conveyor.

With the belt stopped, measure and enter the barcode XYZ coordinate data for each scanner as follows:

1. Make sure that the intended scanner (in a multi-head system) and **Leg1** have been selected from the drop-down lists at the top of the wizard window.

2. Start by placing a system barcode at a 45-degree angle centered on the edge of a box as shown below. Set the box, with the barcode in the scan line, close to the left edge of the conveyor bed. The label should be placed close to the conveyor bed.
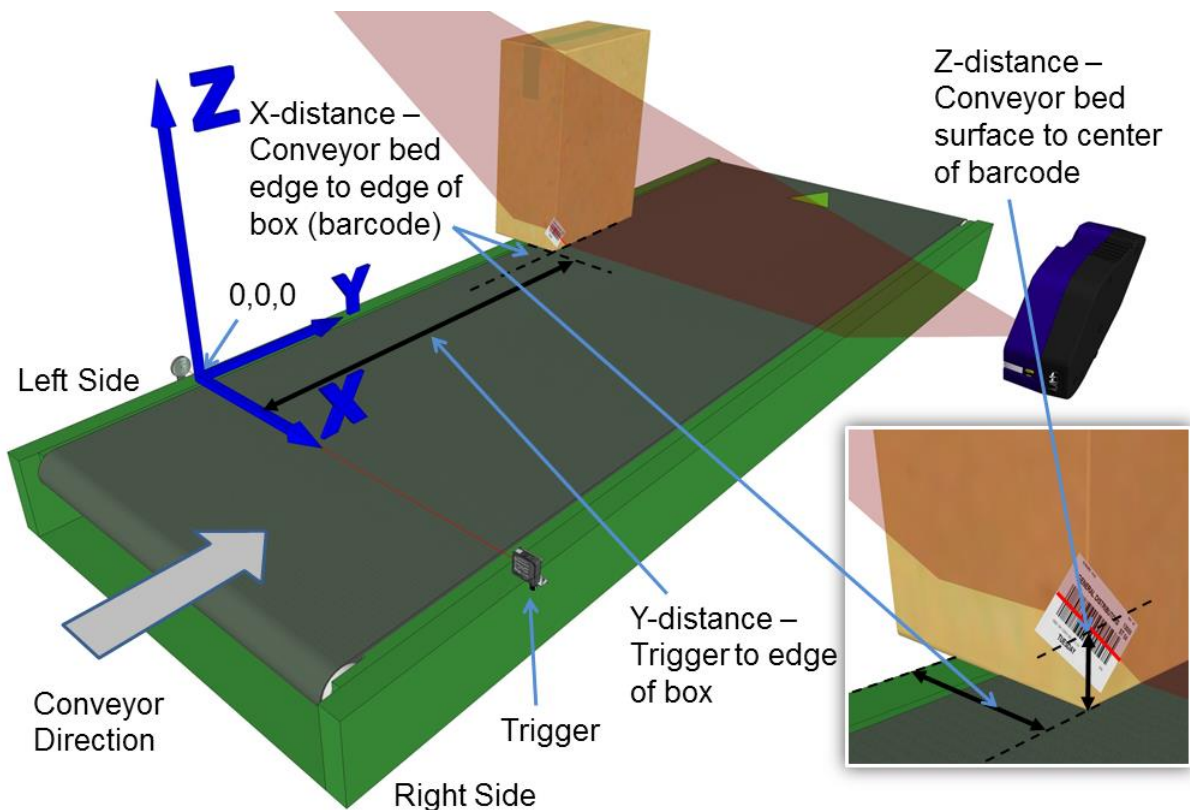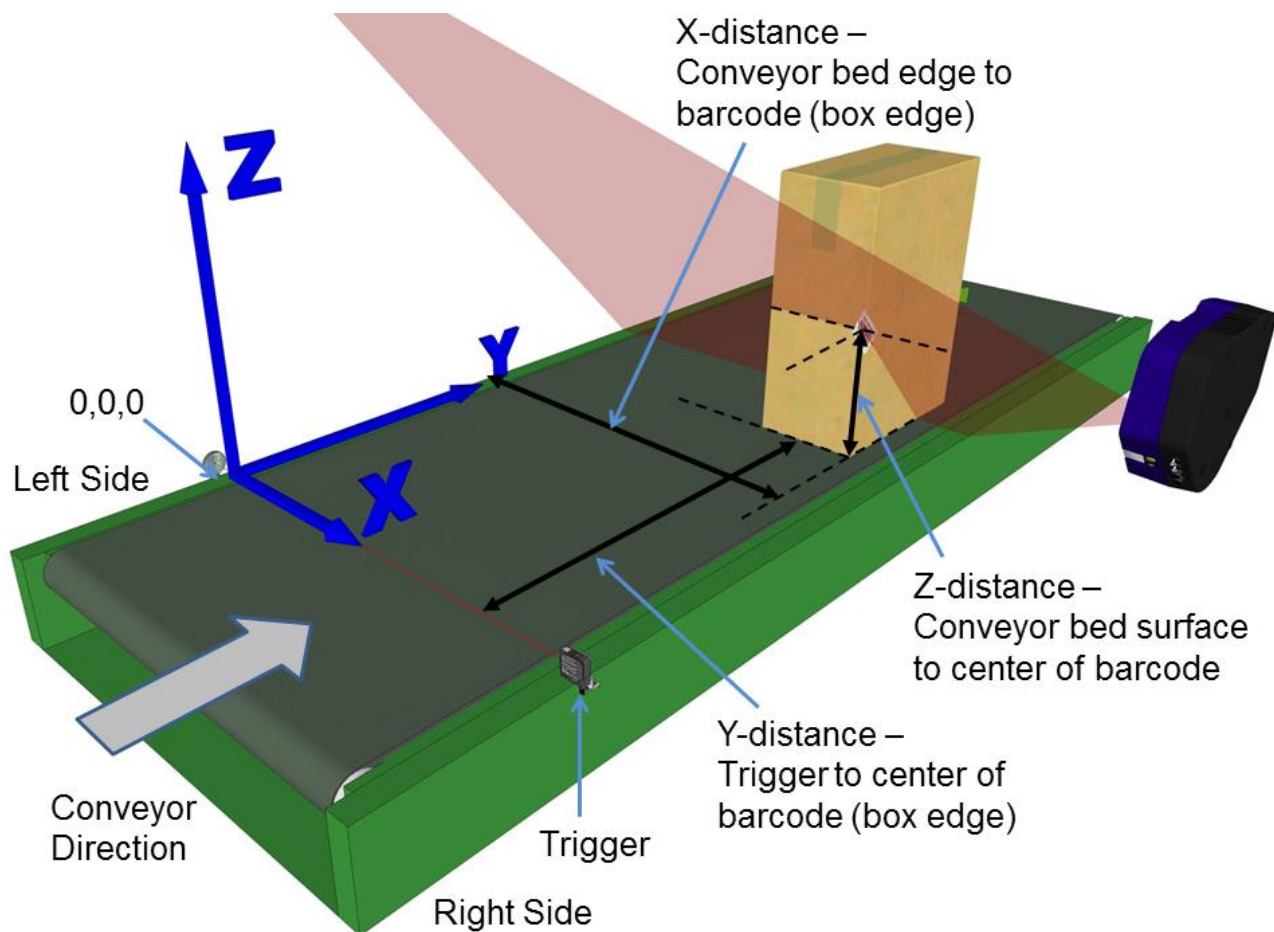

Figure 62: Side-read 1ˢᵗ barcode placement

3. Measure the distance for **X** from the edge of the conveyor bed to the barcode (right edge of box), and enter that distance in the first box under **X-Coord (mm)** in the **PackTrack Calibration Wizard.**

    Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153		

4. Measure the distance for **Y** from the trigger (PS line) to the center of the barcode (edge of the box), and enter that distance in the first box under **Y-Coord (mm)**.

    NOTE: To make it easier to measure the Y-Coordinate, place a box along the photoelectric sensor laser line (Trigger). Then the end of the tape measure or ruler can be place against the edge of the box. *See below.*

Figure 63: Measuring from trigger

    Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	864	

5. Measure the distance for **Z** from the conveyor bed to the center of the barcode, and enter that distance in the first box under **Z-Coord (mm)**.

    Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	864	65

6. Click **Calibrate 1.** PackTrack data is displayed for the first code.

```
Code 1 -  X/Y/Z:     153.000000 / 864.000000 / 65.000000
(Leg 1)   Dist/Angle: 1406.775000 / 0.204170



                  Initialize   Display 1   Display 2   Display 3
```

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
153	864	65	Calibrate 1
			Calibrate 2
			Calibrate 3

Compute Result

Update

7. Next, place a barcode overhanging the top corner of the tallest box specified for your scanning system as shown in the illustration below. Place the box close to the left edge of the conveyor bed, aligning the top corner with the laser line as shown.
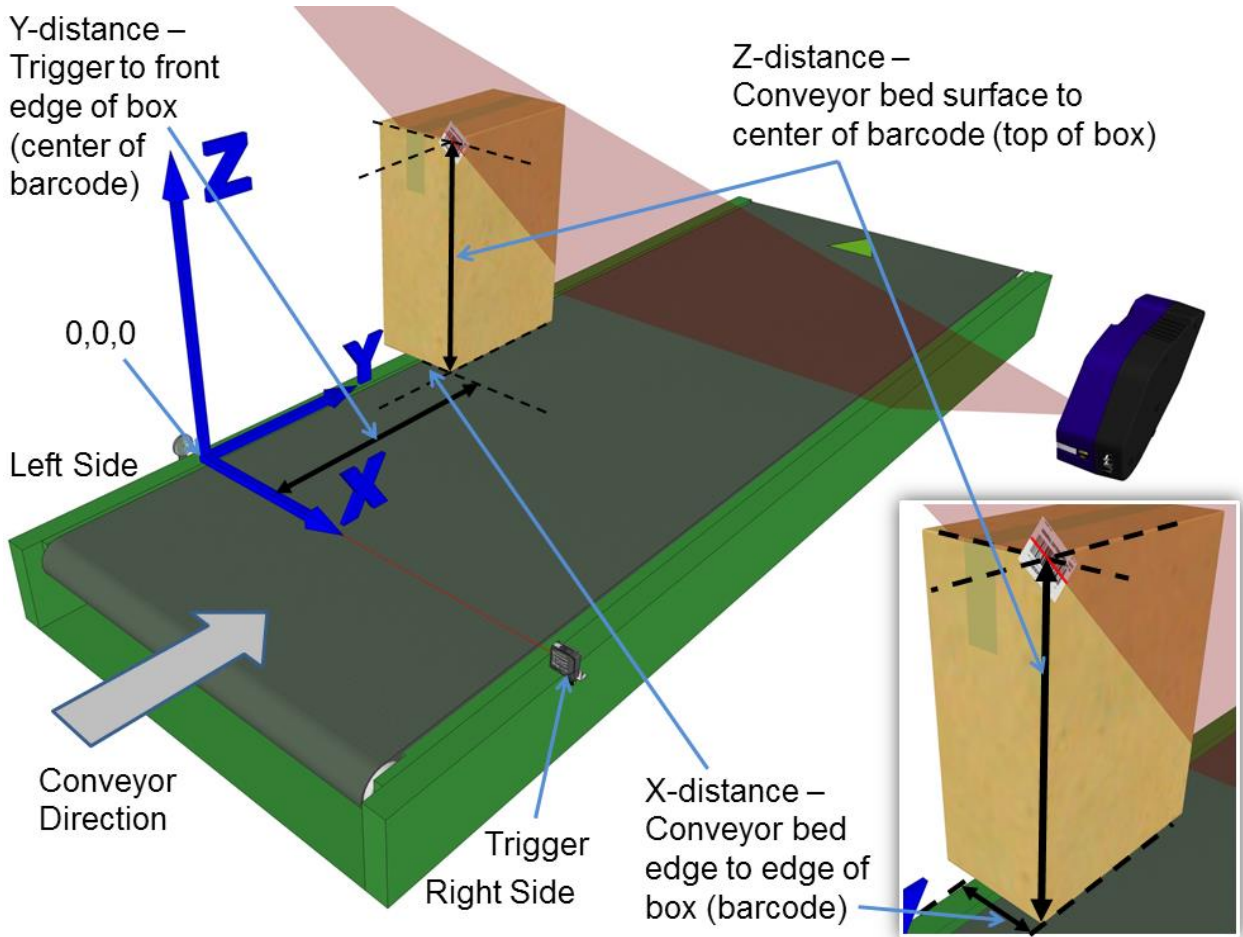
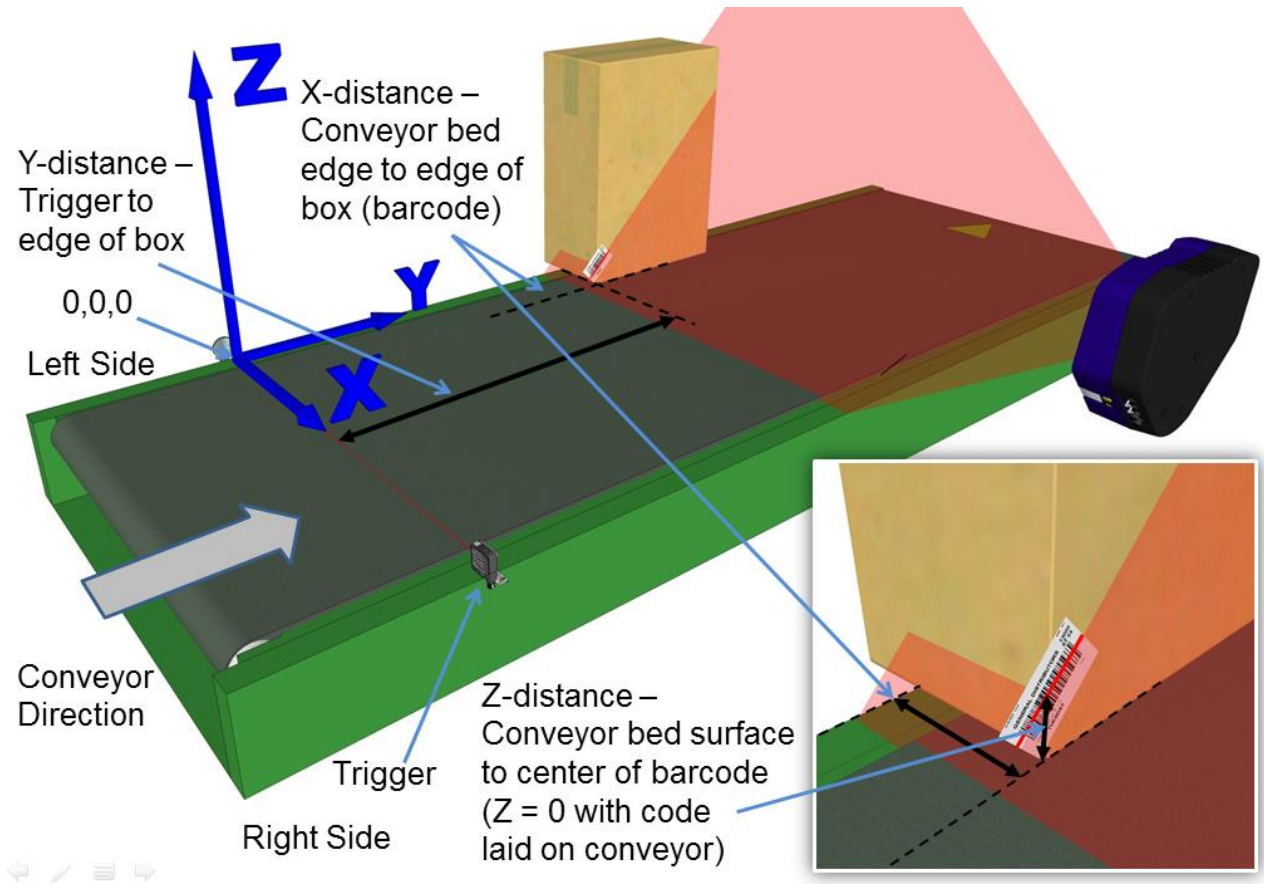**Figure 64: Side-read 2nd barcode placement**

8. Measure the distance for **X** from the left edge of the conveyor bed to the center of the barcode (right edge of box), and enter that distance in the first box under **X-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	864	65
153		

9. Measure the distance for **Y** from the trigger (PS line) to the center of the barcode (leading edge of the box), and enter that distance in the first box under **Y-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	864	65
153	1540	

10. Measure the distance for **Z** from the conveyor bed to the center of the barcode (top of box), and enter that distance in the first box under **Z-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	864	65
153	1540	760

11. Click **Calibrate 2.** PackTrack data is displayed for the second code.

```
Code 2 -  X/Y/Z:      153.000000 / 1540.000000 / 760.000000
(Leg 1)   Dist/Angle: 1595.687500 / -0.416537
```

Initialize Display 1 Display 2 Display 3

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
153	864	65	Calibrate 1
153	1540	760	Calibrate 2
			Calibrate 3

Compute Result

Update

12. Place a system barcode on the right edge of a box, about halfway up the scanner field of view as shown in the illustration below.

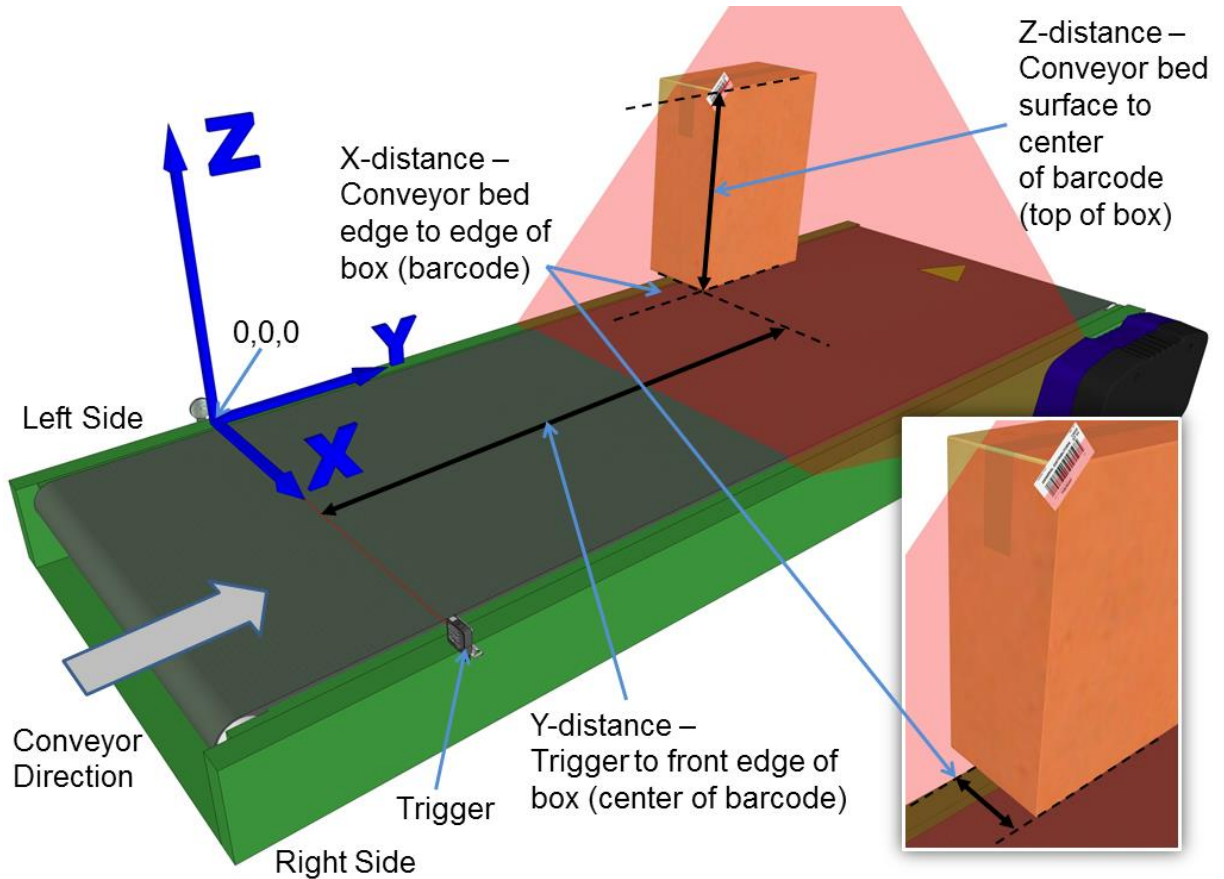**Figure 65: Side-read 3rd barcode placement**

13. Measure the distance for **X** from the left edge of the conveyor bed to the barcode (right edge of box), and enter that distance in the first box under **X-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	864	65
153	1540	760
903		

14. Measure the distance for **Y** from the trigger (PS line) to the center of the barcode (leading edge of box), and enter that distance in the first box under **Y-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	864	65
153	1540	760
903	928	

15. Measure the distance for **Z** from the conveyor bed to the laser line intersecting the barcode (center of barcode), and enter that distance in the first box under **Z-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	864	65
153	1540	760
903	928	303

16. Click **Calibrate 3.** PackTrack data is displayed for the third code.

```
Code 3 -  X/Y/Z:      903.000000 / 928.000000 / 303.000000
(Leg 1)   Dist/Angle: 646.362500 / 0.093144
```

| Initialize | Display 1 | Display 2 | Display 3 |

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
153	864	65	Calibrate 1
153	1540	760	Calibrate 2
903	928	303	Calibrate 3

Compute Result

Update

17. Click Compute Results. The results are displayed at the top of the **PackTrack Calibration** window.

```
Result:  -0.087326  -0.995023 1548.607300
         -0.714644   0.131983 886.024170
         -0.754781  -0.092767 408.076813
```

| Initialize | Display 1 | Display 2 | Display 3 |

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
153	864	65	Calibrate 1
153	1540	760	Calibrate 2
903	928	303	Calibrate 3

Compute Result

Update

18. Click **Update**. "Update Successful" should be displayed in the **PackTrack Calibration** window.

19. Select **Leg2** from the drop-down list at the top of the wizard window.

20. Reposition the system barcode, rotating it on the box, so it matches the angle of the Leg 2 laser line. Set the box, with the barcode in the scan line, close to the left edge of the conveyor bed. The label should be placed close to the conveyor bed.
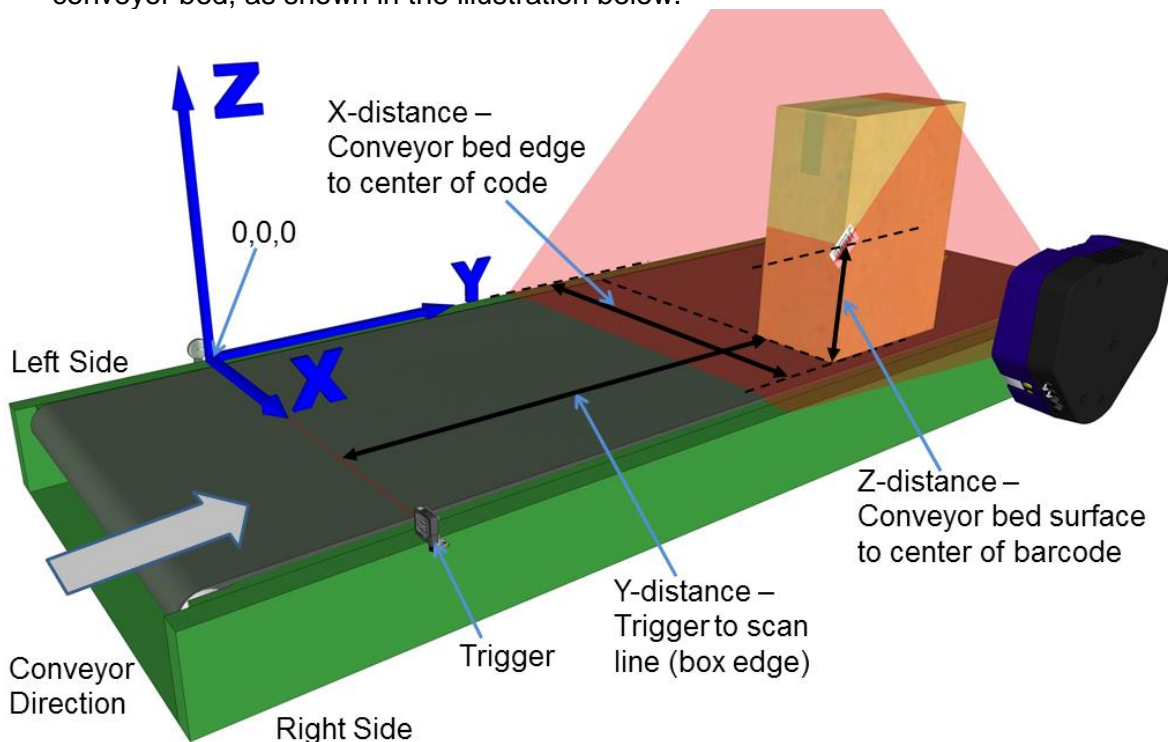

Figure 66: Side-read 1st barcode placement

21. Measure the distance for **X** from the left edge of the conveyor bed to the barcode (right edge of box), and enter that distance in the first box under **X-Coord (mm)** in the **PackTrack Calibration Wizard.**

    Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153		

22. Measure the distance for **Y** from the trigger (PS line) to the leading edge of the box, and enter that distance in the first box under **Y-Coord (mm)**.

    Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	1370	

23. Measure the distance for **Z** from the conveyor bed to the center of the barcode, and enter that distance in the first box under **Z-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	1370	60

24. Click **Calibrate 1.** PackTrack data is displayed for the first code.

```
Code 1 -   X/Y/Z:      153.000000 / 1370.000000 / 60.000000
(Leg 2)    Dist/Angle: 1468.687500 / 0.230248
```

Initialize Display 1 Display 2 Display 3

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)	
153	1370	60	Calibrate 1
			Calibrate 2
			Calibrate 3

Compute Result

Update

25. Next, place a system barcode overhanging the top corner of the tallest box specified for your scanning system as shown in the illustration below. Place the box close to the left edge of the conveyor bed, aligning the top corner with the laser line as shown.

Figure 67: Side-read 2ⁿᵈ barcode placement

26. Measure the distance for **X** from the left edge of the conveyor bed to the center of the barcode (right edge of box), and enter that distance in the first box under **X-Coord (mm).**

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	1370	60
153		

27. Measure the distance for **Y** from the trigger (PS line) to the leading edge of the box, and enter that distance in the first box under **Y-Coord (mm)**.

Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	1370	60
153	642	

28. Measure the distance for **Z** from the conveyor bed to the center of the barcode (top of box), and enter that distance in the first box under **Z-Coord (mm)**.

> Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	1370	60
153	642	760

29. Click **Calibrate 2.** PackTrack data is displayed for the second code.

```
Code 2 -  X/Y/Z:      153.000000 / 642.000000 / 760.000000
(Leg 2)   Dist/Angle: 1489.325000 / -0.424111
```

Initialize | Display 1 | Display 2 | Display 3

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	1370	60
153	642	760

Calibrate 1
Calibrate 2
Calibrate 3

Compute Result
Update

30. Finally, place a system barcode on the leading right edge of a small box close to the conveyor bed, as shown in the illustration below.

Figure 68: Side-read 3rd barcode placement

31. Measure the distance for **X** from the left edge of the conveyor bed to the center of the barcode (right edge of box), and enter that distance in the first box under **X-Coord (mm).**

 Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	1370	60
153	642	760
903		

32. Measure the distance for **Y** from the trigger (PS line) to the barcode scanner's laser line on the barcode (leading edge of box), and enter that distance in the first box under **Y-Coord (mm)**.

 Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	1370	60
153	642	760
903	947	

33. Measure the distance for **Z** from the conveyor bed to the center of the barcode, and enter that distance in the first box under **Z-Coord (mm)**.

 Your measurements will likely differ from those shown below.

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	1370	60
153	642	760
903	947	304

34. Click **Calibrate 3**. PackTrack data is displayed for the third code.

```
Code 3 -   X/Y/Z:      903.000000 / 947.000000 / 304.000000
(Leg 2)    Dist/Angle: 628.900000 / -0.060546
```

Initialize | Display 1 | Display 2 | Display 3

X-Coord (mm)	Y-Coord (mm)	Z-Coord (mm)
153	1370	60
153	642	760
903	947	304

Calibrate 1
Calibrate 2
Calibrate 3

Compute Result

Update

35. Click **Compute Results.** The results are displayed at the top of the **PackTrack Calibration** window.

36. Click **Update**. "Update Successful" should be displayed in the **PackTrack Calibration** window.

37. Close the **PackTrack Calibration Wizard** window. **PackTrack Calibration Coefficients** have been populated on the Scanner Mounting widow.

38. When you have finished making changes, click **Update All** to save all pending changes, click **Reset All** to revert to all previously saved values, and click **Reset Page** to revert to previous saved values on the current page.

39. See **Verifying PackTrack Calibration** *(section 5.7.4).*

5.7.4　Verifying PackTrack Calibration

1.　In the menu tree, navigate to **Diagnostics/Read Test**. The **Read Test** window opens.
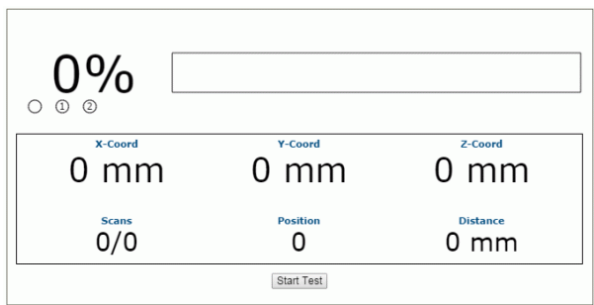
2.　Place a barcode anywhere in the scanner's laser beam other than where you placed the labels for calibration.

3.　Click **Start Test**. The system runs a test to identify the location of the barcode within the read area and displays the results in the Read Test window.
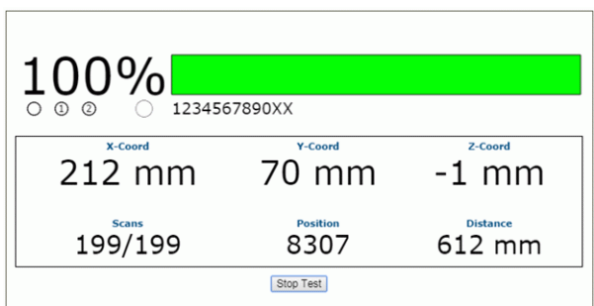
4.　Physically measure the X (from left edge), Y (From PS), and Z (code height) coordinates of your test barcode, and compare your measured results to the Read Test results. Your measured results and those displayed should be close (within a few millimeters) but do not need to be exact.
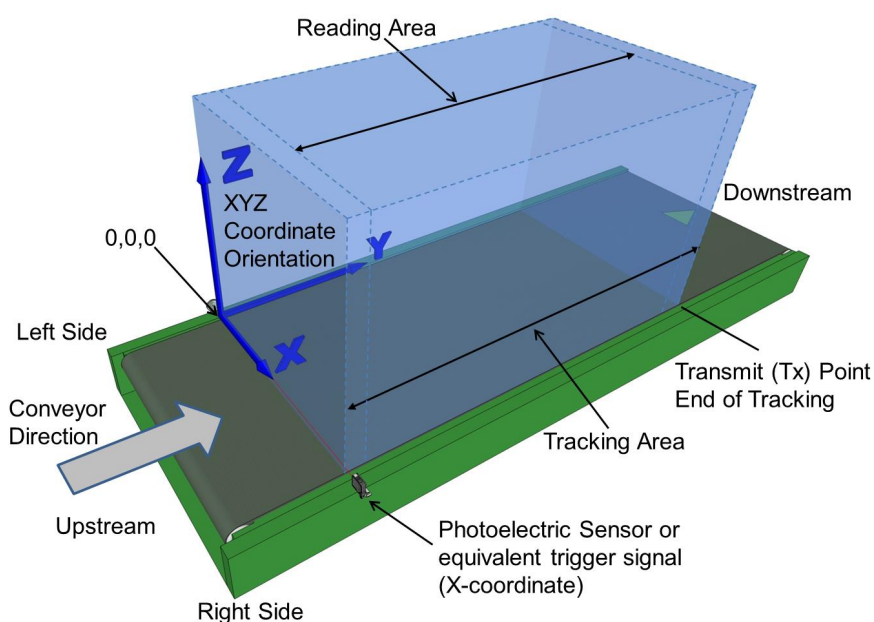
Figure 69: Tracking Area

5. Next, in the menu tree, navigate to **Diagnostics/Monitor**.

6. Turn on conveyor and run a box with a readable barcode past the barcode scanner.

7. Check the **Monitor** to make sure the barcode on the box is being read. If you see a no read (the barcode doesn't read on the box), double check your physical measurements you entered in the **PackTrack Calibration Wizard,** and enter them again.

5.8   REPLACING AN INSTALLED DX8210

If for any reason, a scanner fails, it can be replaced quickly with a spare unit with parameters recovered from flash memory or a saved parameter file.

NOTE: This procedure assumes that system parameters have been properly saved as described in sections 4.8.1, 5.2 and 5.3.

NOTE: If you are not sure the replacement scanner has been defaulted to factory settings, it is a good idea to default the unit before installing it in a system. To do this:

1. Attach a power cable to the replacement scanner and apply power.

2. Simultaneously, press and hold down the yellow X-Press and Restore buttons on the unit until the LEDs flash three times.

3. Release the buttons. The unit is now reset to the factory default.

5.8.1   Replacing a Standalone Scanner Using Restore

A standalone scanner (a single scanner not connected to an array/tunnel) can be replaced using the Restore button located near the LEDs on the side of the housing.

Figure 70: Restore Button

To replace the scanner using Restore:

1. Remove power from the existing scanner and remove the power and I/O cables.

2. Label the cables attached to ETH1 and/or ETH2 so you can easily identify where they were connected, then remove the cables.

3. Detach the existing scanner from its mounting bracket, leaving the bracket attached to the mounting structure.

4. Attach the replacement scanner to the mounting bracket.

5. Reattach the power, I/O, ETH1 and/or ETH2 cables.

6. Apply power to the system.

7. Once the scanner has booted up and the **READY** LED lights solid green, press and hold the **RESTORE** button until all of the LEDs turn on, indicating that the parameters are being restored from the CBX510's BM100 backup module.

8. Release the **RESTORE** button. The green **READY** LED should come back on.

5.8.2   Replacing a Slave Scanner in an Array/Tunnel Automatically

e-Genius provides an option for automatically replacing a slave scanner in a tunnel when the system is configured. To enable this option in **e-Genius**, select **Modify Setting/System Info** from the **e-Genius** menu tree. The System Info window opens.

Select the **Enable Automatic Slave Replacement** check box, click **Update**, and save the system parameters as described in sections *4.8.1, 5.2* and *5.3*.

If the **Enable Automatic Slave Replacement** check box has been selected and saved in the system parameters, use the following procedure to replace a slave scanner:

1. Remove power from the array.

2. Remove the power and I/O cables from the scanner being replaced.

3. Label the cables attached to ETH1 and/or ETH2 so you can easily identify where they were connected, then remove the cables.

4. Detach the existing scanner from its mounting bracket, leaving the bracket attached to the mounting structure.

5. Attach the replacement scanner to the mounting bracket.

6. Reattach the power, I/O, ETH1 and/or ETH2 cables.

7. Apply power to the array. The system will automatically find and download system parameters to the replacement scanner.

5.8.3   Replacing a Slave Scanner in an Array/Tunnel Using Restore

If the **Enable Automatic Slave Replacement** check box has NOT been selected and saved in the system parameters, use the following procedure to replace a slave scanner:

1. Remove power from the array.

2. Remove the power and I/O cables from the scanner being replaced.

3. Label the cables attached to ETH1 and/or ETH2 so you can easily identify where they were connected, then remove the cables.

4. Detach the existing scanner from its mounting bracket, leaving the bracket attached to the mounting structure.

5. Attach the replacement scanner to the mounting bracket.

6. Reattach the power, I/O, ETH1 and/or ETH2 cables.

7. Apply power to the array.

8. Once the scanner has booted up and the **READY** LED lights solid green, press and hold the **RESTORE** button until all of the LEDs turn on, indicating that the parameters are being restored from the CBX510's BM100 backup module or SC5000 flash memory.

9. Release the **RESTORE** button.

5.8.4   Replacing a Master Scanner in an Array/Tunnel Using Restore

1. Remove power from the array.

2. Remove the power and I/O cables from the Master scanner being replaced.

3. Label the cables attached to ETH1 and/or ETH2 so you can easily identify where they were connected, then remove the cables.

4. Detach the existing scanner from its mounting bracket, leaving the bracket attached to the mounting structure.

5. Attach the replacement master scanner to the mounting bracket.

6. Reattach the power, I/O, ETH1 and/or ETH2 cables.

7. Apply power to the array.

8. Once the scanner has booted up and the **READY** LED lights solid green, press and hold the **RESTORE** button until all of the LEDs turn on, indicating that the parameters are being restored from the CBX510's BM100 backup module or SC5000 flash memory.

9. Release the **RESTORE** button.

5.8.5 Checking the Operation of the Replacement

With the scanner replaced and your PC connected to the system, navigate to **Modify Setting/System Info** from the **e-Genius** menu tree. The System Info window opens.

The **Device Information** section of the window should now list all of the scanners (and an SC5000 Controller if used), including the scanner you just replaced.

5.9 TYPICAL LAYOUTS

The following typical layouts refer to system hardware configurations, but also require the correct setup of the software configuration parameters

Other layouts require the use of a specific SC5000 Controller model.

The accessories and cables indicated in the following figures are Datalogic products. We suggest their use to guarantee the correct system functioning.

5.9.1 Large Synchronized Network Layout

When building a large local EBC (Ethernet Based Connectivity) network, an SC5000 Controller should be used together with a PWR-480B power supply unit. In this case the SC5000 unit acts as the system master and is connected to the host through one of its interfaces.

- The SC5000 can be connected to the Host in several different layouts depending on the controller model.

  The SC5000 Standard models provide both Ethernet connections (direct or through a Hub/Switch) and point-to-point connections on the Main interface using either RS232 or RS422 full-duplex;

  Fieldbus models, additionally provide the model specific Fieldbus: Profibus, Profinet IO, etc.

- All scanners act as slaves and are connected to the SC5000 through the EBC interface.

External devices such as a presence sensor and an encoder are all connected either to the SC5000 through its M12 circular connectors, or to the CBX510 connection box (connected to the Controller), wiring the signals through the CBX510 compression connectors.

SC5000: Basic Layout: Ethernet TCP/IP to Host

(1) PWR Cable AS-I 10m/25m (93ACC0081/82)

(2) PWR Cable M12 - AS-I 1m/2m (93ACC0067/68)

(3) Ethernet Cable M12-M12 Straight-Straight 1m/3m/5m (93A050065/66/67)

(4) Ethernet Cable M12-M12 Straight-90° 1m/3m/5m (93A050068/69/70)

(5) Ethernet Cable M12-RJ45 90°-Straight 5m (93A050088)
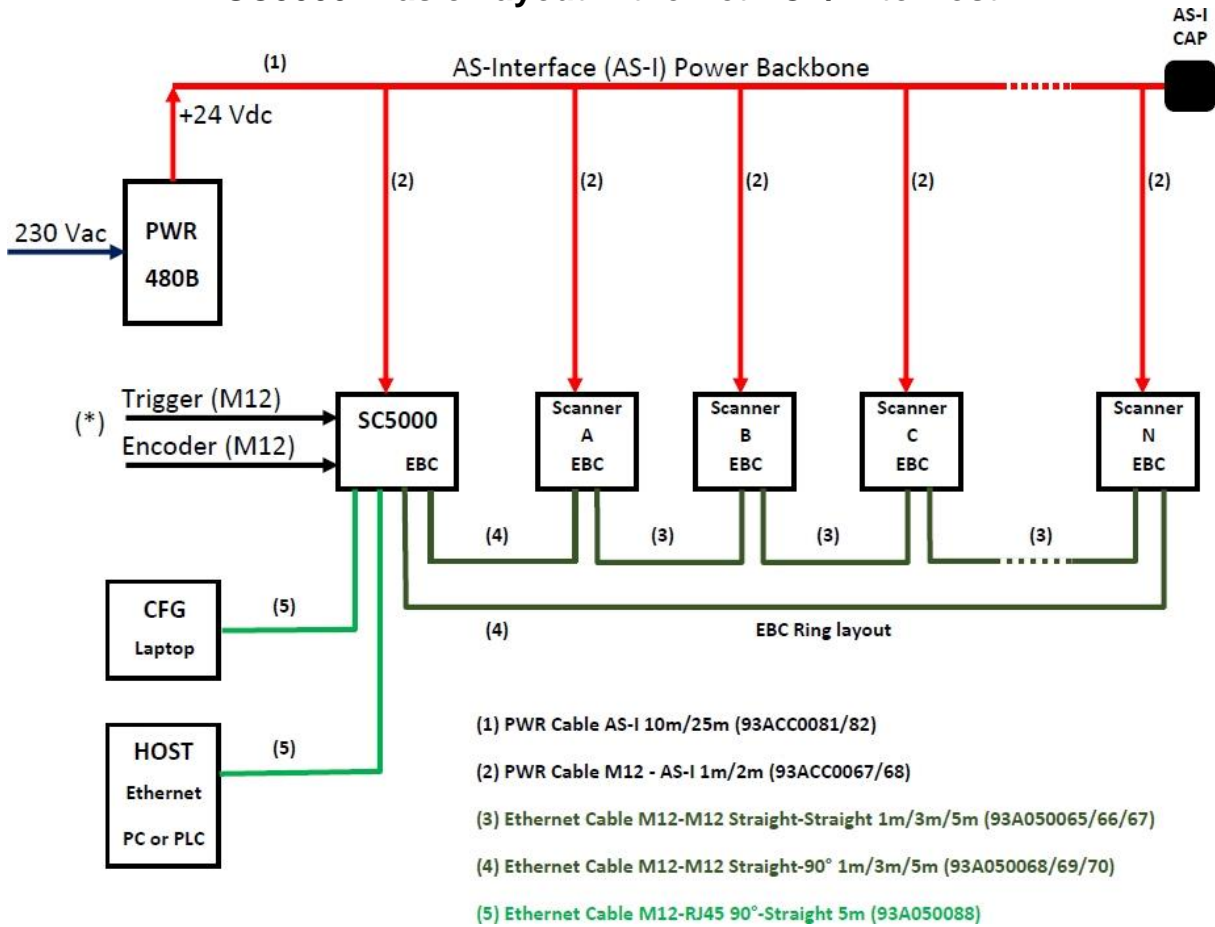
(*) If you prefer an alternative wiring connection, rather than the M12 connection type, use the CBX510 accessory, as shown below.

(6) CAB SC5000 TO CBX510 (93A050071)
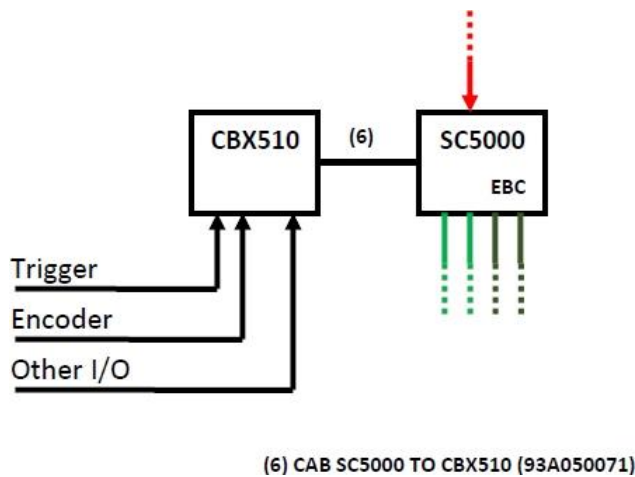
Figure 71 – Large Synchronized Network with DX8210 Scanners

SC5000: Basic Layout: COM to Host

If the Host supports a COM communication type (RS232 or RS422) rather than the Ethernet one, use the CBX510 accessory, as shown below.

The remaining part of the layout (scanners, PWR etc.) does not change.

As already mentioned, the CBX510 can also be used to wire the Trigger and Encoder signals (and other I/O) as an alternative to the M12 connection.
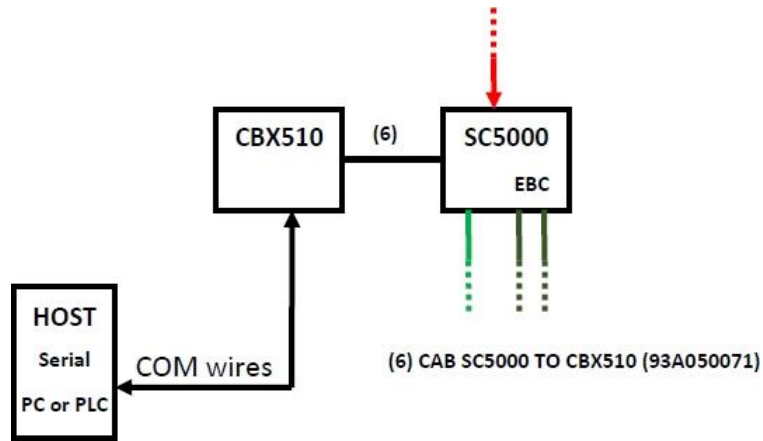
Figure 72 – Large Synchronized Network with COM to Host
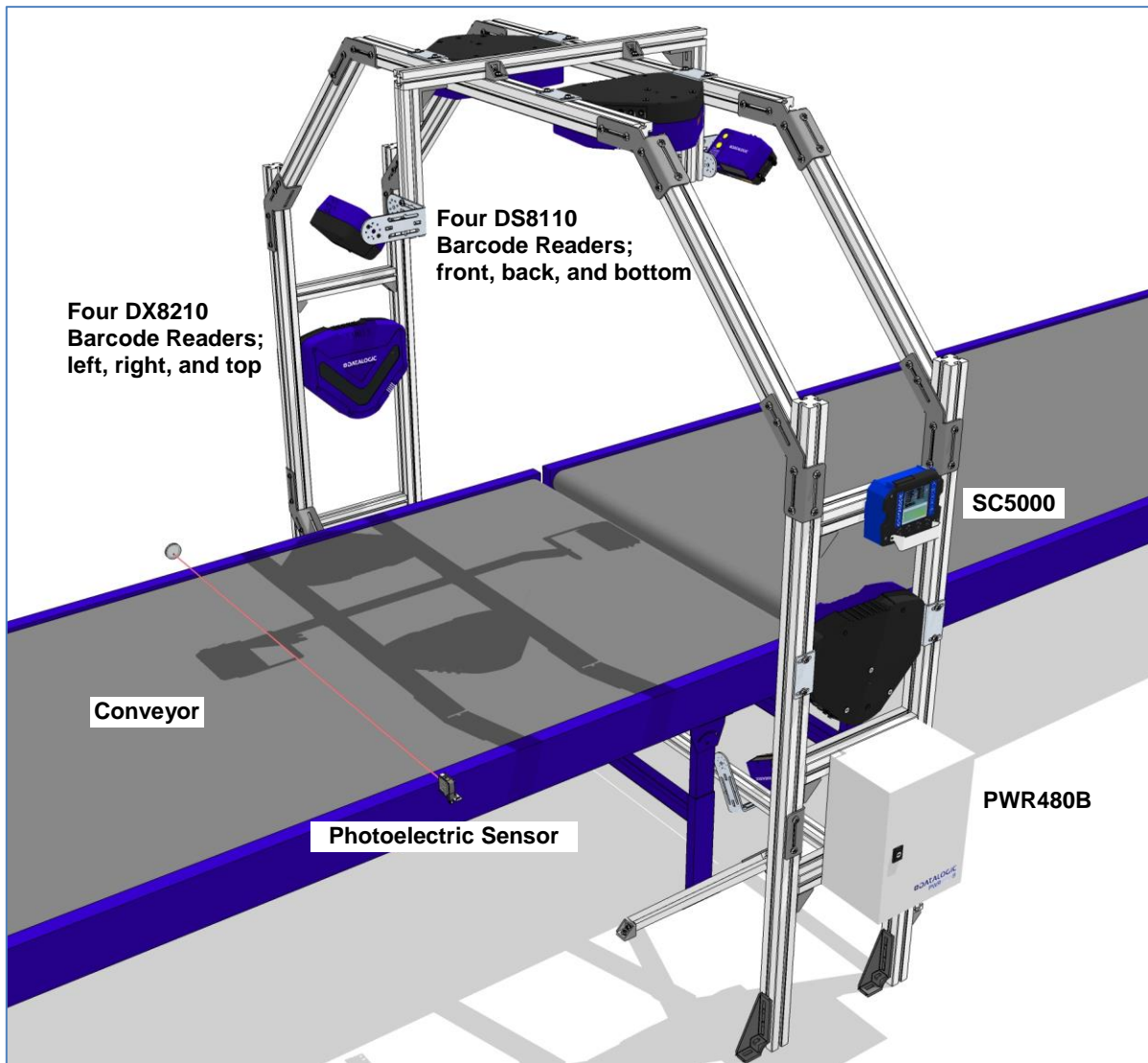
Figure 73 – Example Large Synchronized Network Reading Station

For applications having regular shaped packages, the default settings are sufficient, but for Airport applications working in PackTrack Operating Mode, irregular shaped packs can cause PS signal glitches resulting in false "packs too short" or "packs too close" errors.
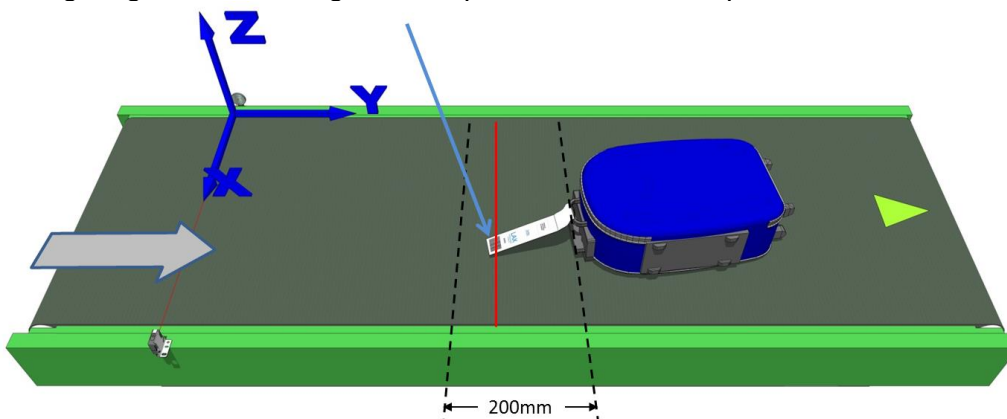
Figure 74 – Compensating for Irregular-Shaped Packages

To correct this, set the following Operating Mode parameters: Minimum Distance Between Packs = 200 mm, Minimum Pack Length = 200 mm, Window Dimension = 200 mm.

5.10 ADVANCED CODE RECONSTRUCTION (ACR™)

The traditional way of barcode reading could be called "Linear Reading". In this case, the laser beam crosses the barcode symbol from its beginning to its end as shown in the following figure:
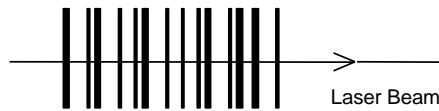
Figure 75 – Linear Reading

In Advanced Code Reconstruction mode it is no longer necessary for the laser beam to cross the label from the start to the end. With just a set of partial scans on the label (obtained using the motion of the label itself), the DX8210 is able to "reconstruct" the barcode. A typical set of partial scans is shown in the figure below:
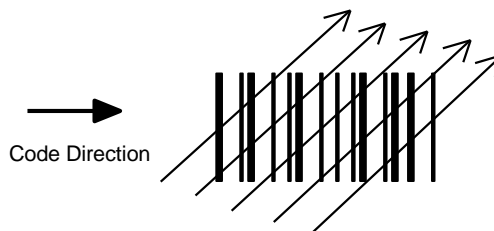
Figure 76 – Partial Scans

None of the partial scans contains the whole label. The decoder aligns each partial scan correctly and combines them in order to obtain the entire code.

The alignment is performed by calculating the time difference from one partial scan to another using a reference code element.

5.10.1 Tilt Angle for Advanced Code Reconstruction

The most important parameter in Advanced Code Reconstruction is the value of the maximum tilt angle (α maximum) under which the code reconstruction process is still possible.
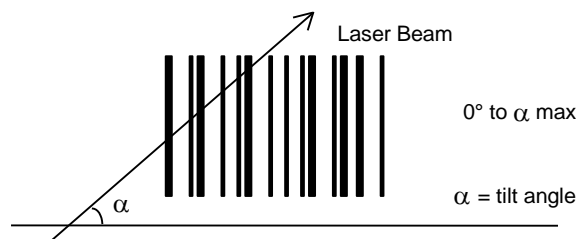
Figure 77 – Tilt Angle

The decoder will be able to read the label with a tilt angle between + α max and - α max as shown in the following figure:
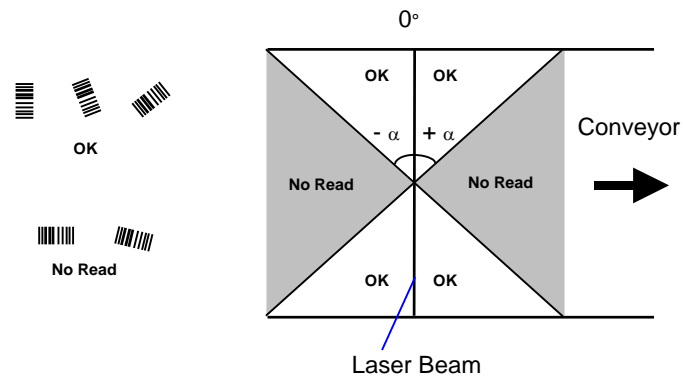
Figure 78 – Reading Zones with α Max

The formulas to calculate α maximum depend on various parameters such as: label height, number of scans per second, code motion speed, etc.

DX8210 scanners provide omnidirectional reading by dividing the scan line into two legs, which produce a cross pattern where angle α is fixed for each leg (see figure below). Since code reconstruction is used, minimum label heights at different conveyor speeds are given in the tables in *section 5.10.2,* which guarantee omnidirectional reading for your application.
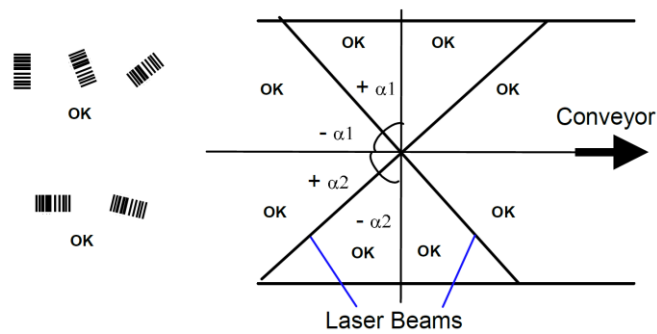
Figure 79 – X-Pattern Reading Zones with α Max

5.10.2 Minimum Code Height for Advanced Code Reconstruction

Based on the scanner read rate of 1000 scans/sec., minimum label heights at different conveyor speeds are given in the tables below.

Refer to the reading diagrams in *section 5.11* for further details on the reading features. These diagrams are taken on various resolution sample codes at a 25 °C ambient temperature depending on the conditions listed under each diagram.

- ANSI Grade B minimum
- 1000 scans/sec

The following tables describe the requirements for standard applications.

		Minimum Code Height for ACR Reading (mm)					
		45°					
Conveyor Speed (m/s)		0.5	1	1.5	2	2.5	3
2/5 Interleaved Code Resolution (mm)	0.25	10	11	13	14	16	17
	0.30	12	13	14	16	17	19
	0.33	12	14	15	17	18	20
	0.38	14	15	16	18	19	21
	0.50	18	18	20	21	23	24
	0.72	24	25	26	27	28	30
	1.00	33	33	34	35	36	37

Ratio 3:1

Table 1

		Minimum Code Height for ACR Reading (mm)					
		45°					
Conveyor Speed (m/s)		0.5	1	1.5	2	2.5	3
Code 39 Code Resolution (mm)	0.25	9	9	11	12	14	15
	0.30	10	11	12	13	15	16
	0.33	11	11	12	14	15	17
	0.38	12	13	13	15	16	18
	0.50	15	16	16	17	18	20
	0.72	20	21	22	22	23	24
	1.00	27	28	29	29	30	31

Ratio 3:1; Interdigit = Module Size

Table 2

	Minimum Code Height for ACR Reading (mm)					
	45°					
Conveyor Speed (m/s)	0.5	1	1.5	2	2.5	3
Code 128 – GS1-128 Code Resolution (mm)　0.25	7	9	10	12	13	15
0.30	8	9	11	12	14	15
0.33	9	10	11	13	14	16
0.38	10	11	12	14	15	17
0.50	12	13	14	16	17	19
0.72	16	17	18	19	21	22
1.00	21	22	23	24	25	26

Table 3

	Minimum Code Height for ACR Reading (mm)					
	45°					
Conveyor Speed (m/s)	0.5	1	1.5	2	2.5	3
Codabar Code Resolution (mm)　0.25	8	9	10	12	13	15
0.30	9	9	11	12	14	15
0.33	9	10	11	13	14	16
0.38	10	11	12	14	15	17
0.50	13	13	14	16	17	19
0.72	17	18	18	19	21	22
1.00	23	23	24	25	26	26

Ratio 3:1; Interdigit = Module Size

Table 4

	Minimum Code Height for ACR Reading (mm)					
	45°					
Conveyor Speed (m/s)	0.5	1	1.5	2	2.5	3
EAN 8-13, UPC-A Code Resolution (mm)　0.25	7	8	9	11	12	14
0.30	8	9	10	11	13	14
0.33	9	10	10	12	13	15
0.38	10	11	11	12	14	15
0.50	12	13	14	14	15	17
0.72	16	17	18	18	19	20
1.00	21	22	23	24	24	25

Table 5

5.11 READING DIAGRAMS

How to identify the scanner model:

The model type is shown on the serial label.

Figure 80 – Identifying the scanner model

- DX8210-2100 is two-laser, **Standard Resolution**

- DX8210-4100 is four-laser, **Standard Resolution**

- DX8210-4200 is four-laser, **High Resolution**

These reading diagrams were based on the following environment:

- 1000 scans per second (standard) throughout depth-of-field (DOF)

- ANSI Contrast Grade 84% or greater

- ANSI "Grade A" Print Quality

- Pitch not greater than +/- 15°

- Skew not greater than +/- 15°

DX8210-2100 0.25 mm/10 mil
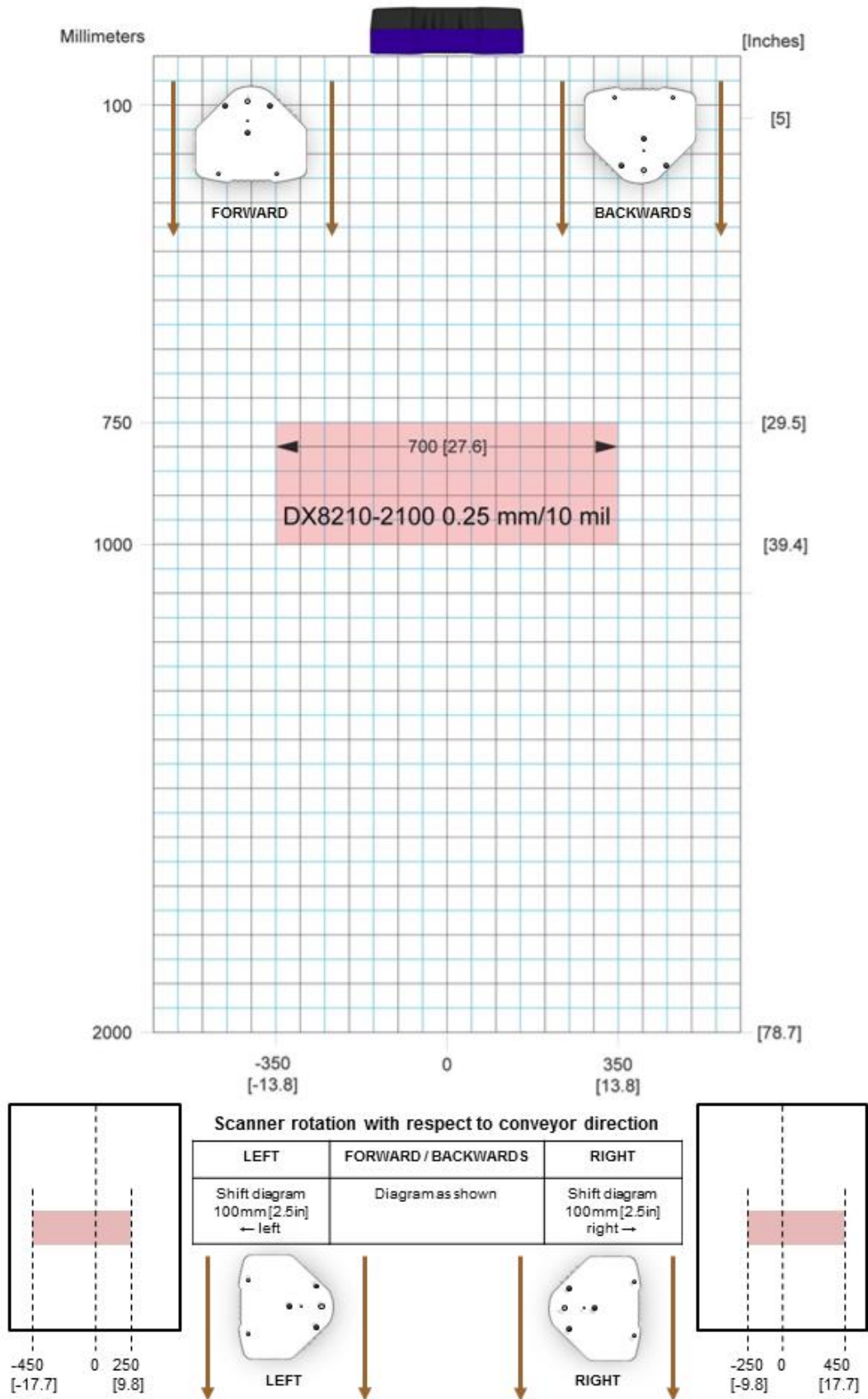
Figure 81 – Reading Diagram for DX8210-2100 0.25 mm/10 mil

DX8210-2100 0.30 mm/12 mil
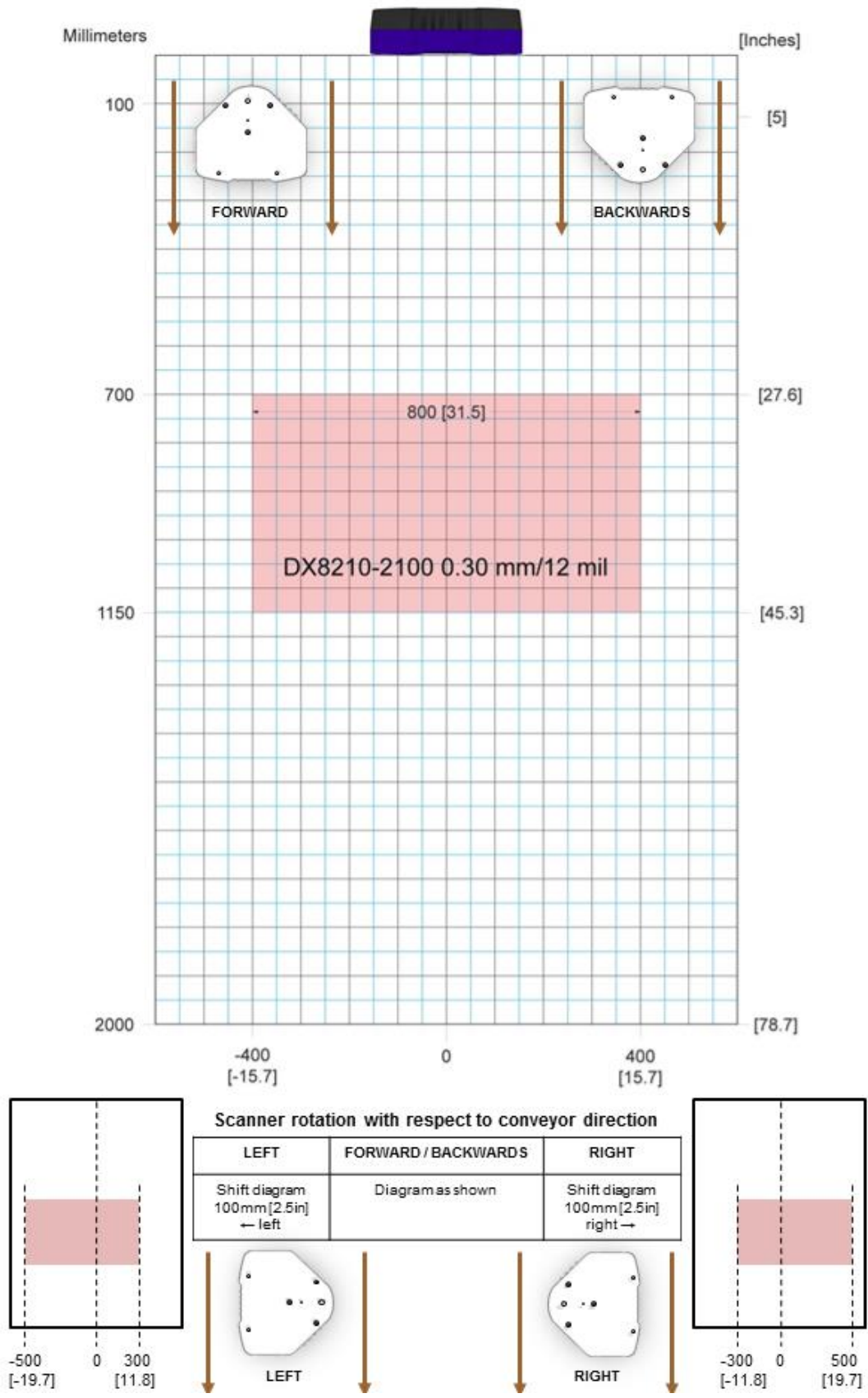
Figure 82 – Reading Diagram for DX8210-2100 0.30 mm/12 mil

DX8210-2100 0.38mm/15mil
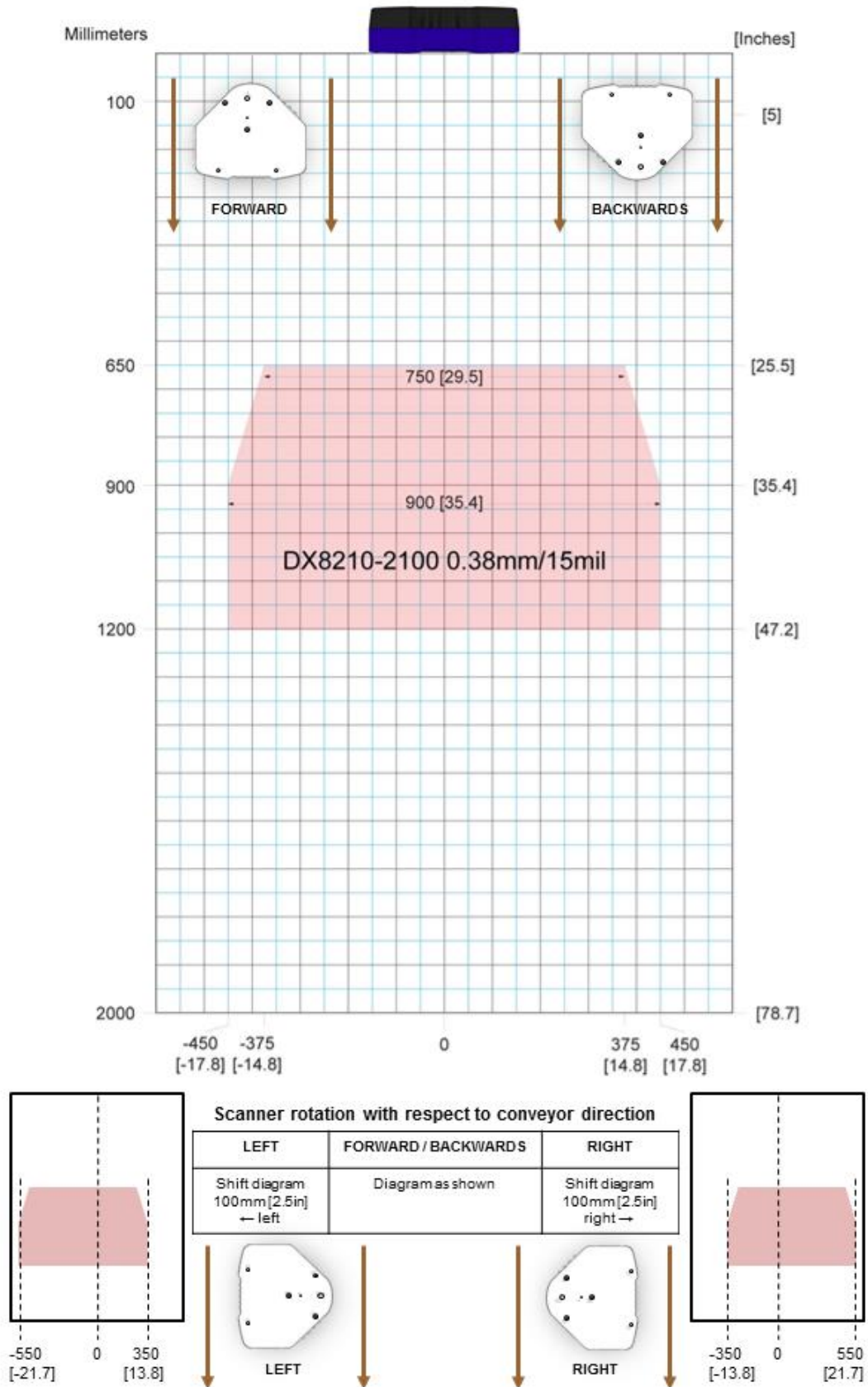
Figure 83 – Reading Diagram for DX8210-2100 0.38 mm/15 mil
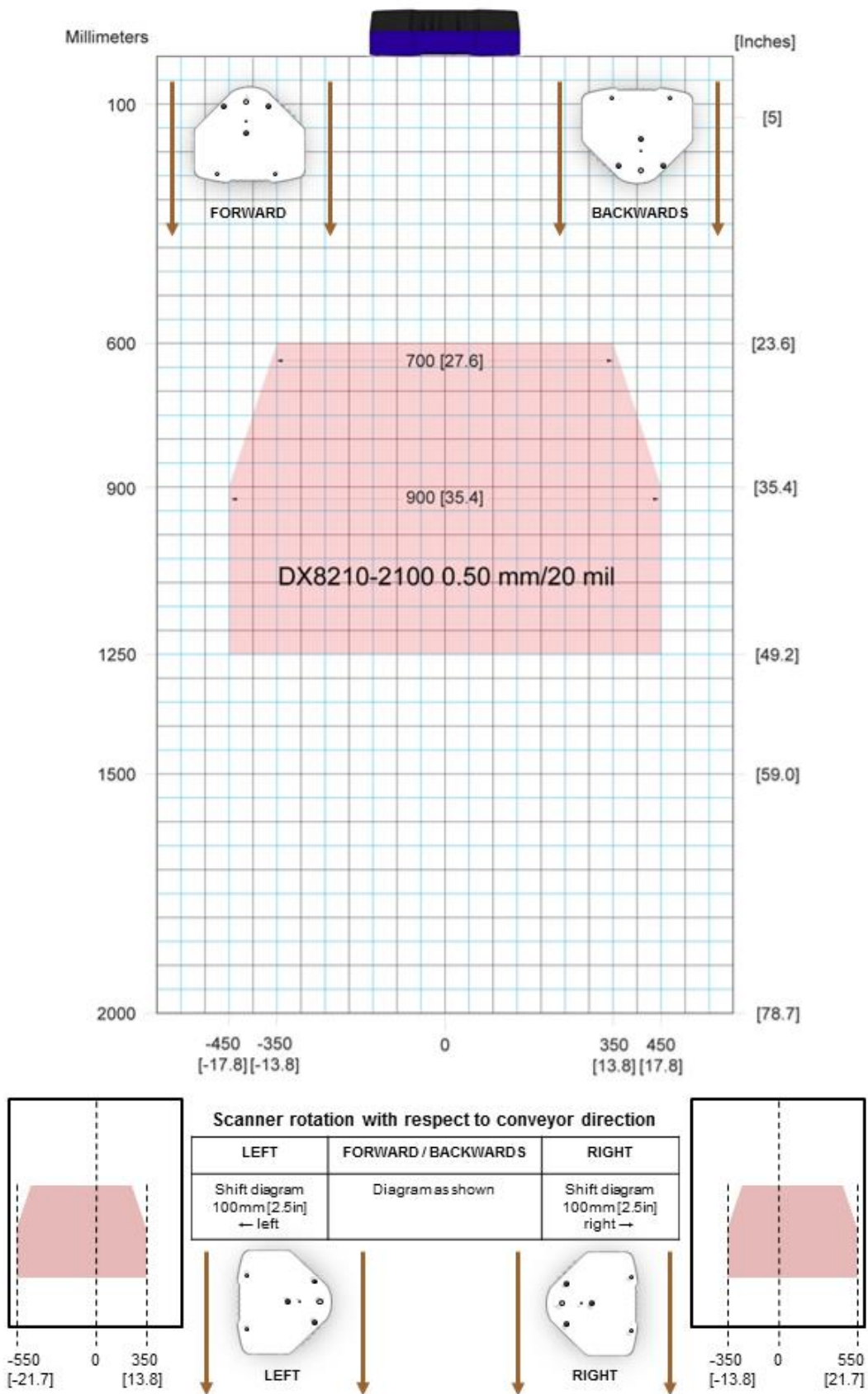
Figure 84 – Reading Diagram for DX8210-2100 0.50 mm/20 mil

DX8210-4100 0.38 mm/15 mil
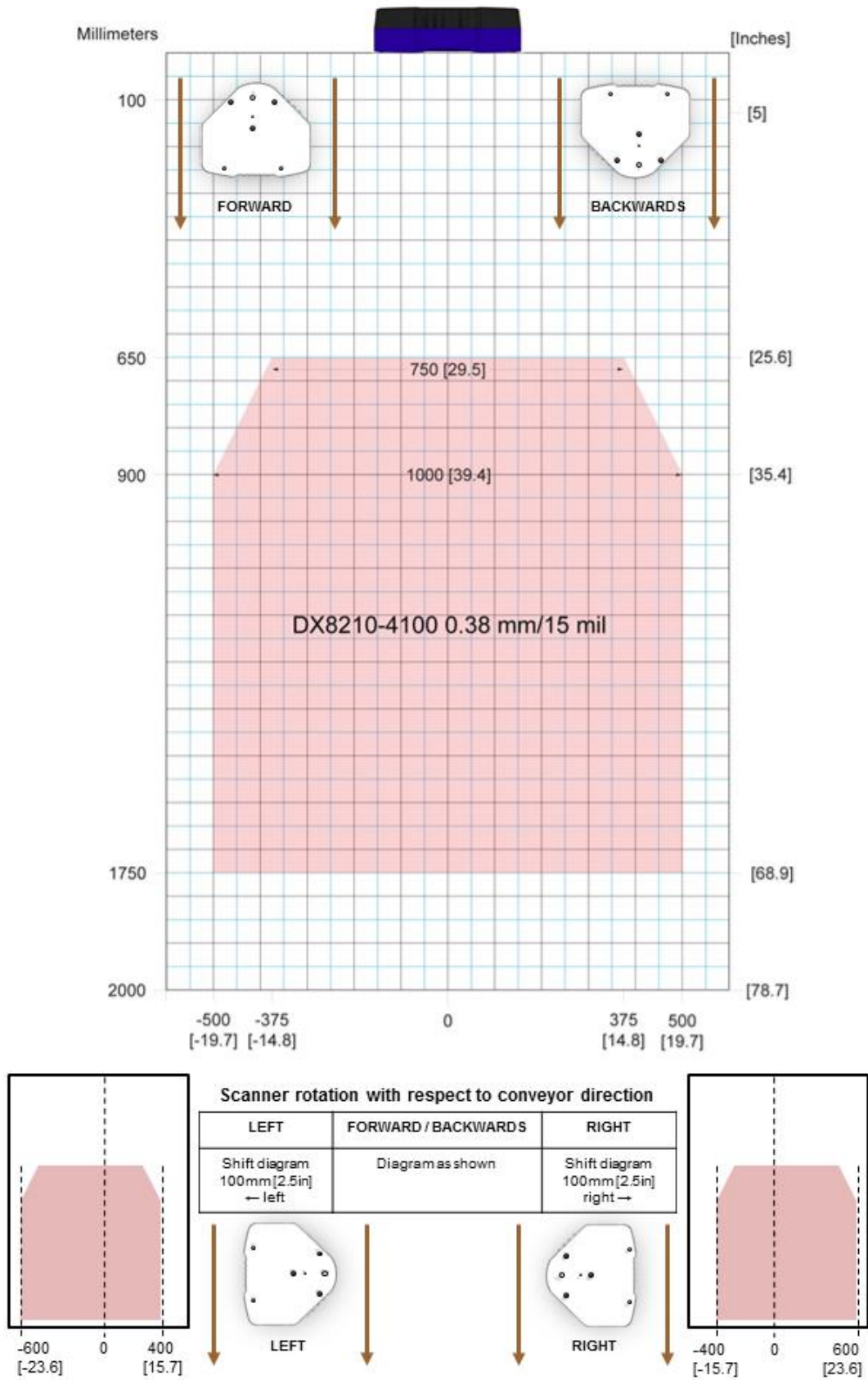
Figure 85 – Reading Diagram for DX8210-4100 0.38 mm/15 mil

DX8210-4100 0.50 mm/20 mil
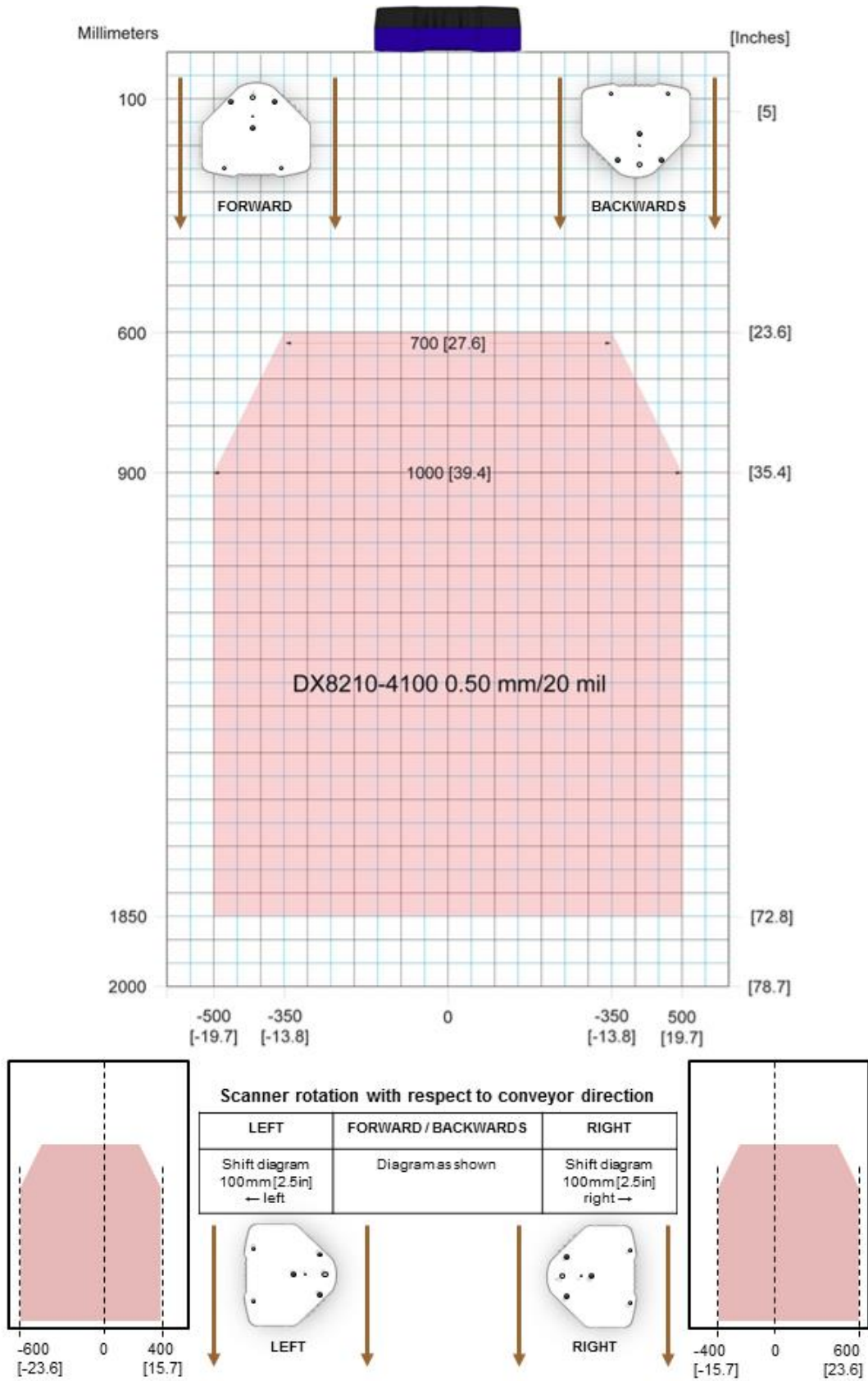
Figure 86 – Reading Diagram for DX8210-4100 0.50 mm/20 mil

DX8210-4200 0.25 mm/10 mil
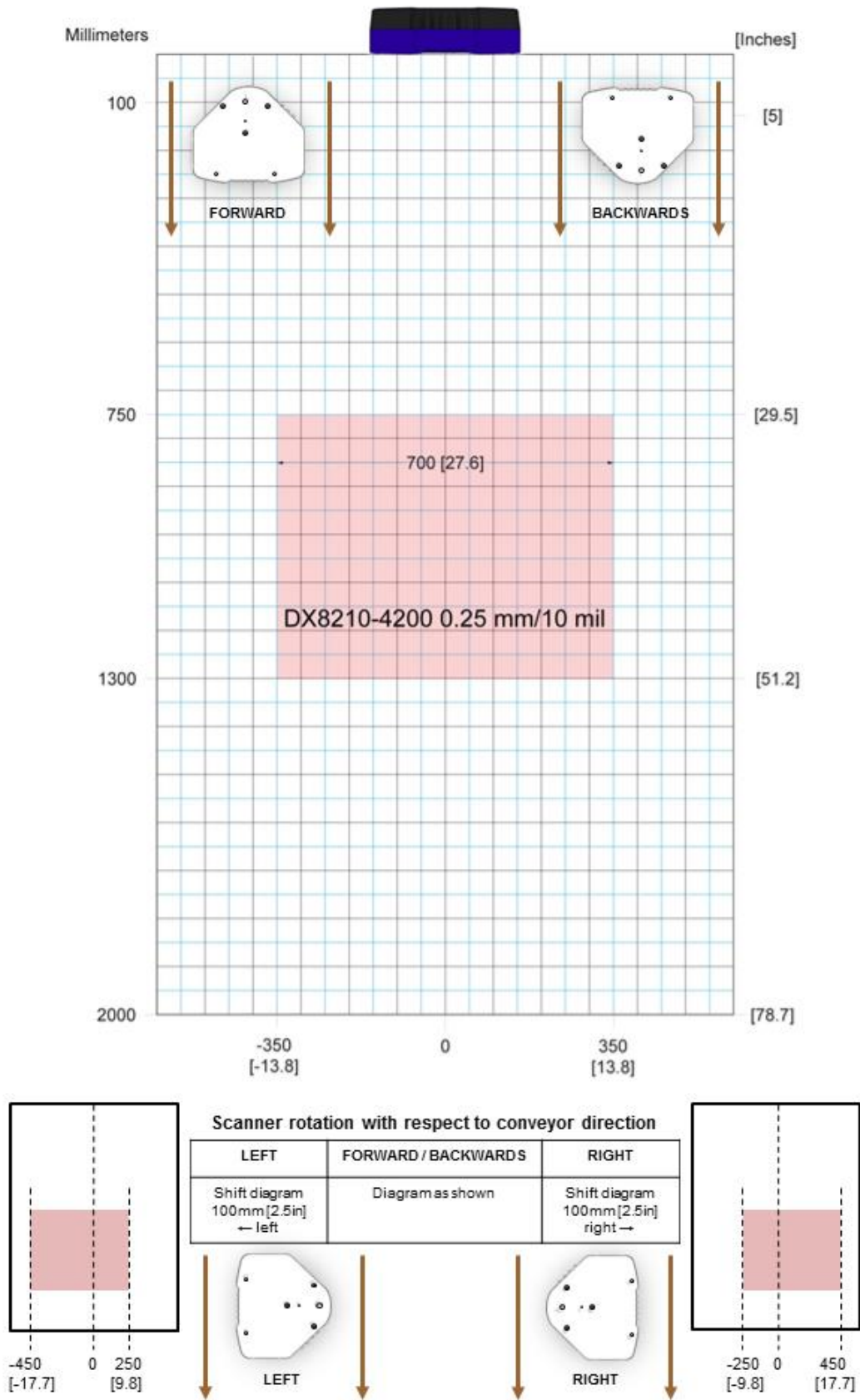
Figure 87 – Reading Diagram for DX8210-4200 0.25 mm/10 mil

DX8210-4200 0.30 mm/12 mil
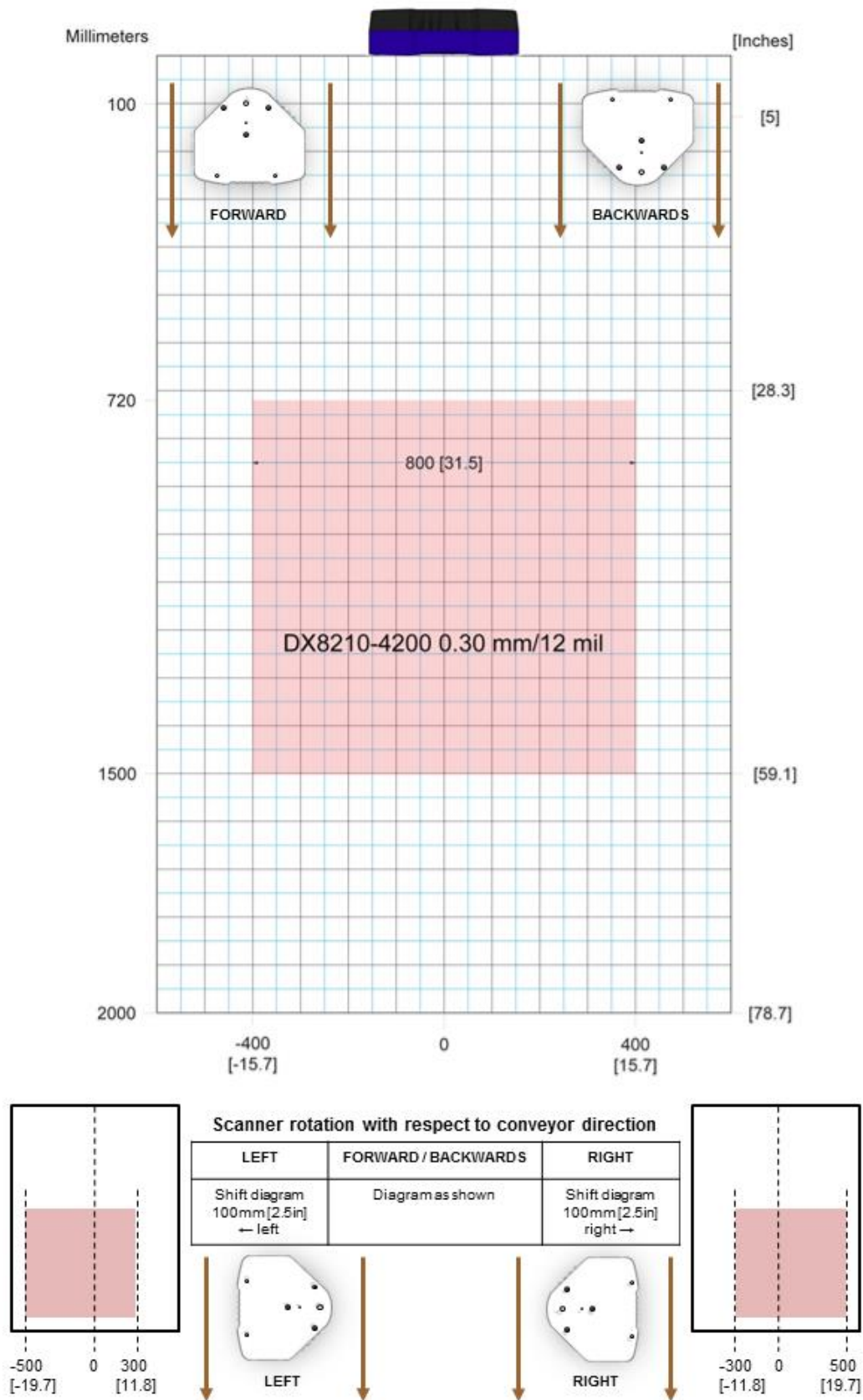
Figure 88 – Reading Diagram for DX8210-4200 0.30 mm/12 mil

6   MAINTENANCE

6.1   OVERVIEW

This chapter provides instructions for maintaining optimum performance and life for your DX8210 barcode scanners. It provides specific information on:

- Maintenance Procedures
- Exterior Cleaning
- Mounting Hardware Checks
- Wiring Connection Checks

Item	Description
Soft-bristle brush	For cleaning the unit's exterior
Clean, soft cloths	For cleaning the unit's exterior
Cleaning solutions	Mild detergent solution for cleaning the unit's exterior.
	70% denatured alcohol, 30% de-ionized water solution for cleaning exit window
Soft cotton swabs or lint-free cloth	Use to clean barcode scanner's exit window

IMPORTANT: Due to the complex and application-specific nature of these installations, the barcode scanner must be setup and serviced by authorized technicians trained by Datalogic.

THE MAINTENANCE PROCEDURES IN THIS CHAPTER MAY BE PERFORMED BY AN END USER TECHNICIAN. Training is recommended if the end user intends to do more than the maintenance procedures provided in this chapter.

THERE ARE NO USER SERVICEABLE PARTS WITHIN THE BARCODE SCANNER.

DO NOT OPEN THE UNIT. Opening the barcode scanner may void its warranty.

CAUTION: Proceeding with any setup, calibration, or service procedures without proper training may void the warranty.

For further information on training, contact us through our website at www.datalogic.com.

6.2 MAINTENANCE TASKS

Perform the maintenance tasks on an "as needed" basis to assure proper operation of the barcode scanner. Task schedule frequency depends upon the application environment conditions. It only requires a few minutes to complete each maintenance task.

Exterior Cleaning

WARNING: Shut down the scanner before performing this maintenance task. Do not stare into the scanner's exit window at the laser light. Avoid direct eye exposure. The laser light level does not constitute a health hazard, however staring at the laser light for prolonged periods could result in eye damage.

CAUTION: Do not use any chemical on the scanner that is unsafe for plastics, such as benzene, acetone, or similar products. Before performing this maintenance task, be sure to shutdown the unit.

The exterior cleaning procedure may be performed without removing the reader from the mounting structure.

1. Turn off the barcode scanner by disconnecting the power source.

2. Clean the exterior (except the exit window) with a clean, soft-bristle brush. Be sure not to brush any dust, dirt, or debris onto the exit window.

3. Carefully remove any debris in or around the exit window.

4. Wipe the exterior (except the exit window) with a clean, soft cloth dampened slightly with a mild detergent solution.

5. The exit window should be cleaned after this task is completed.

6.2.1   Cleaning the Exit Window

Figure 89: Exit window locations

WARNING: Shut down the scanner before performing this maintenance task. Do not stare into the scanner's exit window at the laser light. Avoid direct eye exposure. The laser light level does not constitute a health hazard, however staring at the laser light for prolonged periods could result in eye damage.

CAUTION: Never apply cleaning solution directly to the exit window. Always apply the solution to a cloth, and then the cloth to the window. Do not use any chemical on the barcode scanner that is unsafe for plastics, such as benzene, acetone, or similar products.

The exit window cleaning procedure may be performed without removing the reader from the mounting structure if it is possible to do so.

1. Turn off the scanner by disconnecting the power source.

2. Follow the exterior cleaning procedure before cleaning the exit window

3. Check the exit window surface for any dust, dirt, or smudges. If the window needs to be cleaned, proceed to Step 4.

4. Make a solution of seven parts denatured alcohol and three parts water.

5. Apply the cleaning solution to a cotton swab or lint-free cloth.

6. Apply the cleaning solution to the exit window.

7. Remove any streaks or remaining moisture from the exit window with a dry, soft, lint-free cloth or lens paper.

8. Verify scanner operation.

6.2.2 Cleaning the Photoelectric Sensor

If your application uses the photoelectric sensor option as a hardware trigger, be sure to clean the photoelectric sensor periodically as outlined below.

1. Turn off the product transport.

2. Turn off the scanner by disconnecting the power source.

3. Clean the photoelectric sensor's lens using the denatured alcohol solution and a cotton swab or lens paper.

4. Clean the reflector using the denatured alcohol solution and a cotton swab or lens paper.

5. Verify photoelectric sensor operation.

6.2.3   Cleaning the Tachometer/Encoder

If your application uses the tachometer option for tracking purposes, be sure to clean the tachometer wheels periodically as outlined below.

1. Turn off the product transport.

2. Turn off the scanner by disconnecting the power source.

3. Using a clean, soft cloth, wipe the wheels of the tachometer clean using a mild detergent solution.

4. Before restarting the system, be sure the tachometer is making good contact with the product transport.

5. Verify tachometer operation *(see 6.2.8).*

Figure 90: Tachometer Wheel

6.2.4 Tighten Mounting Hardware

1. Check all barcode scanner, CBX connection box (if applicable), SC5000 Controller (if applicable), and power supply mounting hardware. Tighten as necessary. Do not over-tighten. Be sure not to disturb the equipment's alignment as it relates to the product transport.

2. Check the mounting hardware of the Photoelectric Sensor (if this option is being used). Tighten as necessary. Do not over-tighten.

3. Check the mounting hardware of the tachometer (if this option is being used). Tighten as necessary. Do not over-tighten.

6.2.5 Checking Barcode Scanning System Connections

Wiring connections to the barcode scanners are made to the connector panel and CBX510 or SC5000 Controller. *(See Chapter 3, Electrical Installation.)*

1. Check all wiring connections to the connector panel. Tighten any loose connections as necessary. Do not over-tighten.

2. Check all wiring connections to the CBX510. Tighten any loose connections as necessary. Do not over-tighten.

3. Check all cabling/conduit for signs of wear/damage. Repair/replace any damaged cable connections as necessary.

6.2.6 Verify Barcode Scanner Operation

If after performing maintenance, the barcode scanning system continues to perform below the normal operations experienced with the system under normal daily conditions, contact Datalogic through our website at www.datalogic.com.

6.2.7 Verify Photoelectric Sensor Operation

1. Block the Photoelectric Sensor emitter beam to confirm it is aligned properly with the reflector.

2. Verify that the TRIGGER LED on barcode scanner lights YELLOW when photoelectric sensor beam is blocked.

   If the photoelectric sensor's LED does not light, adjust the photoelectric sensor so that it is properly aligned with the reflector.

   If the TRIGGER LED on the barcode scanner does not light when the photoelectric sensor's beam is blocked, check the cabling between the photoelectric sensor and CBX510 or SC5000 for damage.

6.2.8   Verify Tachometer/Encoder Operation

Rotate the tachometer wheel.

The **ENC/TACH** LED in the CBX510 or the **TACH** LED on the SC5000 should flash indicating the tachometer is operational. Also, you can view the belt speed by navigating to **Diagnostics | Monitor** in **e-Genius** *(see section 4.7.1).*
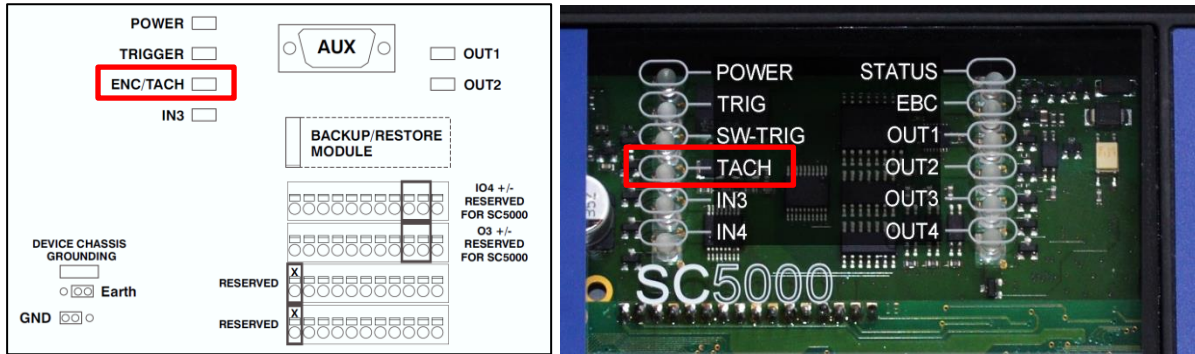
Figure 91: ENC/TACH LED indicators in CBX510 and SC5000

If these indicators do not register feedback when the tachometer wheel is rotated, check the cabling between the tachometer and the CBX510 for damage.

7 TROUBLESHOOTING

IMPORTANT: Due to the complex and application-specific nature of these installations, operational deficiencies of the barcode scanner must be diagnosed and serviced by a trained and authorized Datalogic technician.

There are no user serviceable components or field replaceable units (FRUs) inside the barcode scanner.

For further information on training, contact us through the Datalogic website at www.datalogic.com.

NOTE: When contacting Datalogic for help with a scanner, please be ready to share the unit serial number with the Datalogic technician. The unit's serial number tag is located on the device, where shown below. Help desk contact information is available at www.datalogic.com.

Figure 92: Serial Number Location

7.1 LED DIAGNOSTIC INDICATION

The **STATUS** and **READY** LEDs blink simultaneously to signal the presence of a failure. Diagnostic message transmission on interfaces can be enabled to provide details about specific failure conditions.
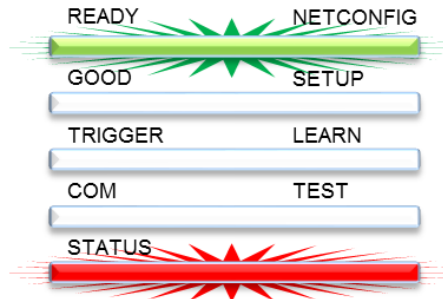
Figure 93: LED Failure Indication

At the same time one or more LEDs light up according to the following scheme:
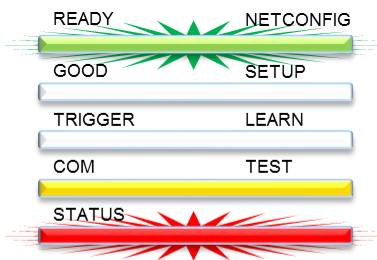
STATUS/READY + COM = Laser Failure
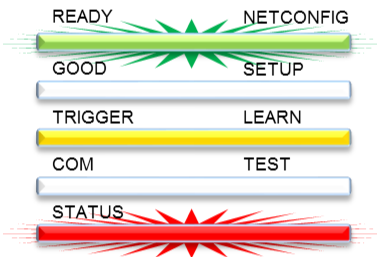
STATUS/READY + TRIGGER = Motor Failure
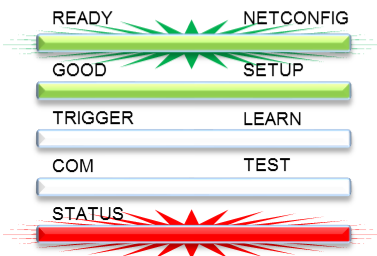
STATUS/READY + GOOD = Other Failure

Figure 94: LED Failure Specific Indication

In a **Master-Slave** configuration, all Slave scanner alarms and failures can also be indicated on the Master by turning on the Master's **GOOD** LED. This feature can be enabled by checking the **HMI Settings | LED Settings | Indicate Errors on Master** parameter.

7.2 ERROR CODES AND RESOLUTIONS

Error Code	Description	Severity	Explanation	Symptom	Troubleshooting	Action required
1	Node not responding	Error	In a Master/Slave configuration, the Master monitors the status of the Slaves in its network. If a slave unit fails to be identified, the Master will post this message.	- The scanning tunnel's no-read rate increases. - More than one slave unit may be shown as not responding.	- In a tunnel configuration, the cabling that connects the system into to a network must be intact or a scanner will be reported as not responding. - Make sure all the slave units are powered on.	- Make sure cables are connected. - Check scanners power source. - Replace scanner.
80	Node Reset	Error	In a Master/Slave configuration, the Master monitors the status of the Slaves in its network. If a Slave resets, it sends a reset message to the Master. The Master then posts this error condition on the diagnostic screen.	- The scanning tunnel's no-read rate may increase during the Slave scanner's reconnection.	- This condition is related to a slave scanner. Make sure the power source of the slave is not faulty.	- If condition persists, replace the scanner.
81	Motor Failure	Error	The scanner's mirror wheel motor has failed.	- The scanner will be powered up but will not emit laser light from its exit window. - The scanners motor will not be spinning.	- Hold your hand in front of the scanner to determine if the laser is on.	This is an internal failure and is not field serviceable - Replace scanner.
83	Laser Failure	Error	Scanner has a laser failure.	- There is no laser light emitted from the scanner - The mirror wheel motor may still be spinning, however, the motor speed may be out of range at which time the scanner will turn off the laser light.	- Hold your hand in front of the scanner to determine if the laser is on.	This is an internal failure and is not field serviceable. - Replace scanner.

Error Code	Description	Severity	Explanation	Symptom	Troubleshooting	Action required
130	Encoder Timeout	Warning	No encoder (tachometer) is detected in specified time. The Encoder signal provides the scanner with belt speed and other tracking information. This error will only occur when the scanner is in the PackTrack mode.	- The scanner may experience an increase in no-reads. - The scanner may start missing the transmit point.	- Confirm that the belt is running. - Make sure the encoder (tachometer) wheel is making a firm contact with the conveyor. - Check the **Global Settings | Diagnostics | Encoder Timeout** setting to confirm that it is not set too low *(See section 4.5.9).*	- Adjust the encoder (tachometer) mounting. - Adjust the **Encoder Timeout** setting *(See section 4.5.9).*
131	Input 1 Failure	Error	The Primary PS (photoelectric sensor) Input is stuck in the active state (PackTrack Mode).	- The scanner will not go into trigger. - No data will be transmitted to the Host.	- Check the alignment of the photoelectric sensor. - Check the functionality of the photoelectric sensor.	- Realign the photoelectric sensor. - Replace the photoelectric sensor.
132	No Phase Error	Error	No Phase "timeout" is exceeded (On-Line and PackTrack Mode). - Trigger must be identified within a specified time.			
133	Input 2 Failure	Error	Secondary PS (photoelectric sensor) Input Failure Stuck Active (PackTrack Mode).	- The scanner will not go into trigger. - No data will be transmitted to the Host.	- Check the alignment of the photoelectric sensor. - Check the functionality of the photoelectric sensor.	- Realign the photoelectric sensor. - Replace the photoelectric sensor.

Error Code	Description	Severity	Explanation	Symptom	Troubleshooting	Action required
135	Encoder Failure	Error	Phase input (trigger source) is activated while encoder (tachometer) is stopped (PackTrack Mode).	- No data will be transmitted to the host. - Scanner(s) will not read any barcodes. - System receives trigger cycle when no encoder signal is present.	- Check D**iagnostics | Monitor** to see if the scanner is reporting a conveyor speed *(See section 4.7.1).* - Make sure the encoder (tachometer) wheel is making a firm contact with the conveyor.	- Adjust, realign, or replace the encoder (tachometer).
157	SD Card Failure	Error	SC5000 - SD card cannot be accessed. The SD card contains the backup files. It also contains a copy of the scanners application software. This failure is only in the SC5000.	- Unit will not backup or restore the parameters.	Try to save the parameters from the **SC5000** to the SD card *(see SC5000 System Controller Reference Manual).*	- Confirm that the SD card is seated properly in the SC5000. - Replace SD card *(see SC5000 System Controller Reference Manual).*
169	Main Serial Port Error	Error	Protocol Index message not received on Main Serial Port.			
176	Aux Serial Port Error	Error	Protocol Index message not received on Aux Serial Port.			
178	Ethernet Socket 1 Error	Error	Protocol Index message not received on User Socket 1.			
179	Ethernet Socket 2 Error	Error	Protocol Index message not received on User Socket 2.			
180	Ethernet Socket 3 Error	Error	Protocol Index message not received on User Socket 3.			
181	Ethernet Socket 4 Error	Error	Protocol Index message not received on User Socket 4.			

Error Code	Description	Severity	Explanation	Symptom	Troubleshooting	Action required
182	Ethernet Socket 5 Error	Error	Protocol Index message not received on User Socket 5.			
183	Ethernet Socket 6 Error	Error	Protocol Index message not received on User Socket 6.			
191	Fieldbus Mismatch	Error	Fieldbus module type does not match specified model. - Module selection incorrect compared to the actual module installed.			
193	Fieldbus Config Error	Error	Error configuring fieldbus module.	- Unable to communicate to the module.	- Confirm that the unit is not communicating to the host. - Confirm that the fieldbus parameters are configured properly *(see section 4.5.8)*.	- Replace fieldbus module.
195	Fieldbus DHCP Error	Error	Profinet module had a DHCP error.	- Unable to acquire an IP address.	- Confirm that the unit is not communicating to the host. - Confirm that the fieldbus parameters are configured properly *(see section 4.5.8)*.	- Replace fieldbus module.
205	APD Temperature Error	Error	APD Temperature sensor is not working. A fluctuation in the scanner's temperature can have an adverse effect on several internal functions of the scanner. The scanner monitors the temperature, and if it is erratic, this error is posted.	- The scanner may experience an increase in no-reads. - The scanner may start missing the transmit point.	1. Cycle power on the scanner; 2. Wait until the unit has time to cool down. 3. Restart the scanner and monitor it to determine whether the error reoccurs.	This is an internal failure and is not field serviceable. - Replace scanner.

Error Code	Description	Severity	Explanation	Symptom	Troubleshooting	Action required
207	In Beam Sensor Error	Error	The scanner has an in-the-beam sensor, which provides timing for the decoding of barcodes. The scanner monitors this signal, and posts this error if the signal is sporadic or missing.	- The scanner stops reading barcodes.	- Put the scanner in the test mode to test its ability to read the barcode *(see section 4.7.2)*.	This is an internal failure and is not field serviceable. - Replace scanner.
211	PTP Error	Error	Cannot synchronize the internal clock using the PTP (precision time protocol) protocol. This clock sync pulse is generated by the controller unit. It is used to sync the read data of all the scanners in the network with the master unit.	LEDs flashing.	- Confirm that all the scanners are connected in the chain. - Use the scanner test mode to confirm that the scanner can statically reading a barcode *(see section 4.7.2)*. - Position a barcode on a box so it faces the questionable scanner, and dynamically test the scanner.	- Replace faulty scanner.
219	Fieldbus Comm Error	Error	Cannot communicate with the fieldbus module.	- The host loses communication with the scanner.	- Confirm that the unit is not communicating with the Host. - Confirm that the fieldbus parameters are configured properly *(see section 4.5.8)*.	- Replace fieldbus module.

Error Code	Description	Severity	Explanation	Symptom	Troubleshooting	Action required
220	Network Ring Open	Error	When the SC5000 is used, the scanner internal network is connected in a chain configuration. If the SC5000 detects that network chain is not complete, it will post this error.	- The system experiences a higher no-read rate. - One or more scanners may not appear on the System Info page *(see section 4.4).*	- Confirm that all the scanners are connected in the chain. - Use the scanner test mode to confirm that the scanner can statically reading a barcode *(see section 4.7.2).* - Position a barcode on a box so it faces the questionable scanner, and dynamically test the scanner.	- Replace faulty scanner.

8 TECHNICAL FEATURES

This chapter provides detailed specifications for the DX8210 Omnidirectional Barcode Scanning Systems. It provides specific information on:

- Electrical Features
- Optical Features
- Reading Features
- Physical Features
- Environmental Features
- X-PRESS Interface
- Software Features

8.1 TECHNICAL SPECIFICATIONS

ELECTRICAL FEATURES

Power	
Supply Voltage	20-30VDC
Consumption	1 – 0.7 A Max. (note: 1.3A max peak at motor start-up) 20 W typical
Distributable Current (through I/O connector)	0.6 A Max.
Communication Interfaces	
Main RS232	1200 to 115200 bit/s
Main RS422 full-duplex	1200 to 115200 bit/s
Auxiliary RS232	1200 to 115200 bit/s
Ethernet (x2) TCP/IP	100 Mbit/s
EBC Internal Network	100 Mbit/s
Fieldbus	Embedded: EtherNet/IP Supported through CBX510 connection box or SC5000 models: PROFINET-IO, PROFIBUS-DP
Inputs	3 opto-coupled and polarity insensitive NPN/PNP digital inputs (5-30 Vdc)
Outputs	2 opto-coupled software programmable NPN digital outputs

OPTICAL FEATURES

Wavelength	630 to 680 nm
Safety Class	Class 2 - EN60825-1; Class II – CDRH
Light Source	Visible laser diode
Laser Control	Security system to turn laser off in case of motor slow down
Optic Architecture / Technology	ASTRA™

READING FEATURES

Scan Rate	Typ.:1000 scans/s/ Max.
Maximum Resolution	Min:0.25mm (10mils)/Max: 1.0mm (40mils)
Max. Reading Distance	See section 5.11 Reading Diagrams
Max. Reading Width	See section 5.11 Reading Diagrams
Max. Depth of Field	See section 5.11 Reading Diagrams
Scan Pattern Type	X-Pattern

PHYSICAL FEATURES

Dimensions	381 x 328 x 92.5 mm [15 x 13 x 3.6 in]
Weight	7.7 kg (17 lb)
Enclosure	Aluminum Alloy
Connections	I/O, POWER, ETH1, ETH2; Other connections through CBX510

ENVIRONMENTAL FEATURES

Temperature	Operating: 0 to 50 °C (32 to 122 °F) Storage: -20 to 70 °C (-4 to 158 °F)
Relative Humidity	10-90% non-condensing
Ambient light immunity	>30,000 LUX
Vibration Resistance ①	• SINE vibration as per EN60068-2-6 • 2-10Hz : 14mm / 13-55Hz : 1.5mm / 70-500Hz : 2g • 2h per axis / 3 axes
Shock Resistance	As per EN60068-2-27, 30g / 11ms / 3 times up and 3 times down on each axis / 3 axes
Protection Class	IP65

X-PRESS INTERFACE

LED Indicators	Ready, Good, Trigger, Com, Status
Keypad	HMI Keypad for alternative configuration and test mode and Restore Factory Default

SOFTWARE FEATURES

Readable Code Symbologies

· Code 128 · Interleaved 2 of 5 · Code 39 (Standard)	· GS1-128 · Codabar · Code 93	· EAN-8/13 - UPC-A/E (including Addon 2 and Addon 5)
Operating Mode	On Line, Continuous, PackTrack™, Test	
Configuration Methods	e-Genius multilanguage, browser-based, on board HTML web server interface X-PRESS™ HMI key functions	
Multilabel Reading	Up to 10 different symbologies during the same reading phase	

Headers and Terminators	Up to 128-byte headers and 128-byte terminators
Code Reconstruction Technology	ACR™
Parameter Storage	Non-volatile internal FLASH

OTHER	
Service Options	Installation services and on-site training
Warranty	2-year limited, parts and labor

① Product not installed on provided bracket.

GLOSSARY

ACR™

Each version of the base has the powerful code reconstruction technology (ACR G5). The new fifth generation ACR considerably increases the code reconstruction reading capability in the case of damaged or very tilted barcodes.

Aperture

Term used on the required CDRH warning labels to describe the laser exit window.

Barcode

A pattern of variable-width bars and spaces which represents numeric or alphanumeric data in machine-readable form. The general format of a barcode symbol consists of a leading margin, start character, data or message character, check character (if any), stop character, and trailing margin. Within this framework, each recognizable symbology uses its own unique format.

Barcode Label

A label that carries a barcode and can be affixed to an article.

Baud Rate

A unit used to measure communications speed or data transfer rate.

CDRH (Center for Devices and Radiological Health)

This organization (a service of the Food and Drug Administration) is responsible for the safety regulations governing acceptable limitations on electronic radiation from laser devices. Datalogic devices are in compliance with the CDRH regulations.

Code Positioning

Variation in code placement that affects the ability of a scanner to read a code. The terms Pitch, Skew, and Tilt deal with the angular variations of code positioning in the X, Y and Z axes. Variations in code placement affect the pulse width and therefore the decoding of the code. Pulse width is defined as a change from the leading edge of a bar or space to the trailing edge of a bar or space over time. Pulse width is also referred to as a transition. Tilt, pitch, and skew impact the pulse width of the code.

EEPROM

Electrically Erasable Programmable Read-Only Memory. An on-board non-volatile memory chip.

Full Duplex

Simultaneous, two-way, independent transmission in both directions.

Host

A computer that serves other terminals in a network, providing services such as network control, database access, special programs, supervisory programs, or programming languages.

Interface

A shared boundary defined by common physical interconnection characteristics, signal characteristics and meanings of interchanged signals.

LED (Light Emitting Diode)

A low power electronic device that can serve as a visible or near infrared light source when voltage is applied continuously or in pulses. It is commonly used as an indicator light and uses less power than an incandescent light bulb but more than a Liquid Crystal Display (LCD). LEDs have extremely long lifetimes when properly operated.

PackTrack

PackTrack is a Datalogic patented parcel tracking system which improves the reading features in omnidirectional stations. In particular, PackTrack manages 6-sided reading systems when it is impossible to detect the real position of the code on the parcel, thus overcoming the need for external accessories essential in traditional tracking systems.

Parameter

A value that you specify to a program. Typically parameters are set to configure a device to have particular operating characteristics.

Pitch

Rotation of a code pattern about the X-axis. The normal distance between center line or adjacent characters.

Position

The position of a scanner or light source in relation to the target of a receiving element.

Protocol

A formal set of conventions governing the formatting and relative timing of message exchange between two communicating systems.

Resolution

The narrowest element dimension which can be distinguished by a particular reading device or printed with a particular device or method.

RS232

Interface between data terminal equipment and data communication equipment employing serial binary data interchange.

RS422

Interface that specifies the electrical characteristics of generators and receivers for use in serial communications over longer distances than RS232.

Scanner

A device that examines a printed pattern (barcode) and either passes the uninterpreted data to a decoder or decodes the data and passes it onto the Host system.

Serial Port

An I/O port used to connect a scanner to your computer.

Signal

An impulse or fluctuating electrical quantity (i.e.: a voltage or current) the variations of which represent changes in information.

Skew

Rotation about the Y-axis. Rotational deviation from correct horizontal and vertical orientation; may apply to single character, line or entire encoded item.

Symbol

A combination of characters including start/stop and checksum characters, as required, that forms a complete scannable barcode.

Tilt

Rotation around the Z axis. Used to describe the position of the barcode with respect to the laser scan line.

Trigger Signal

A signal, typically provided by a photoelectric sensor or proximity switch, which informs the scanner of the presence of an object within its reading zone.

UPC

Acronym for Universal Product Code. The standard barcode type for retail food packaging in the United States.

Visible Laser Diode

A light source used in scanners to illuminate the barcode symbol. Generates visible red light at wavelengths between 630 and 680 nm.

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